The HART (highway addressable remote transducer) protocol allows for bidirectional 1.2 kHz/2.2 kHz FSK (frequency shift keying) modulated digital communication over traditional analog 4 mA to 20 mA current loops. This allows for interrogation of the sensor/actuator and provides significant advantages during equipment installation, monitoring, and maintenance. HART provides benefits to maintenance crews using a portable secondary device to interrogate the sensor/actuator, but to fully realize all the benefits HART can bring, the sensor/actuator must be connected to a control system with HART enabled current inputs or outputs. This article will focus on HART enabled current inputs and the challenges associated with adding HART functionality to already space constrained 4 mA to 20 mA input designs.

First, let’s focus on the HART FSK transmit circuitry. Figure 1 shows a traditional approach to the HART FSK transmit circuitry, following a discussion of this circuit we will show an improved circuit design, which results in space and cost savings.

Figure 1 shows an improved HART FSK transmit circuitry design, which has benefits in terms of reduced space and cost. In this circuit, the AD5700 HART modem has enough drive strength to drive the ±500 mV FSK signals directly onto the current loop without the need for an external buffer.

When the modem is not transmitting, the AD5700’s FSK output is biased to ±0.75 V with an impedance of 70 kΩ. R2 and R3 provide a stronger ±0.75 V bias, with an impedance of R2 and R3 = 1.7 kΩ. The high-pass filter formed by the this 1.7 kΩ and C1 ensures that the worst-case 4 mA to 20 mA input signal, which is ±16 mA at 25 Hz across the 200 Ω Rsense, only results in the HART modems FSK output being driven to between 0 V and 1.5 V. This means that the whole input can be run from unipolar supplies as low as 1.62 V, with 1.62 V being the minimum supply for the HART modem.

Another consideration is the input impedance, which should be greater than 230 Ω. It is to ensure a large enough input impedance that the 250 Ω input resistor has been split into 50 Ω and 200 Ω. The ac input impedance is R1 + (Rsense || R2 || R3) = 230 Ω. If needed, this impedance can be increased by increasing the values of the 0.75 bias resistors, R2 and R3. The additional 50 Ω in the FSK transmit path will attenuate the FSK signals somewhat, but the voltages will still meet the requirements of the HART specification.

As the current loop is slewing there will be some current flow through C1, R2, and R3. These signals are either sinusoidal or trapezoidal waveforms. A good buffer with enough drive strength is required at the output of the HART modem as the Rsense represents a low impedance and there may also be significant capacitance on the current loop cabling. When the HART is not transmitting, the buffer output would present a low impedance to the loop, which could compromise the 4 mA to 20 mA signaling. For this reason the switch (SW1) is used in series with the buffer output to provide a high impedance when not transmitting.

The 4 mA to 20 mA loop can swing between 1 V and 5 V while SW1 is open. As this change is ac-coupled to SW1, the switch could see up to ±4 V at its input. For this reason a bipolar supply of ±5 V or greater would be required for the switch, or alternately an opto switch could be used. A tristate buffer is another option, though again this buffer would require bipolar supplies. Another option is to use transformer isolation. Given the HART signal frequencies, an audio transformer would be required, which is likely to be bulky and consume a large amount of board area.
This improved circuit (shown in Figure 2) has eliminated the need for a buffer and a switch, as well as eliminating the need for a bipolar power supply. These three factors provide significant space and cost savings for a system over the traditional HART FSK transmit circuitry.

Circuitry for the HART FSK input is shown in Figure 3. This provides a band-pass filter to reject the low frequency analog signaling as well as provide immunity from higher frequency interferers. The filter shown is specifically tailored for the AD5700 and will vary for different HART modems. One feature of this band-pass filter is the 150 kΩ input impedance provided by R1, which provides an inherent high level of protection from transient events.

Figure 3. HART FSK input.

Circuitry for the 4 mA to 20 mA current measurement is shown in Figure 4. The 200 Ω Rsense resistor converts the 4 mA to 20 mA signals to a 0.8 V to 4 V signal to be converted by the ADC. This is followed by a double pole low-pass filter R2, C1, R3, C2 to reject the HART FSK signals. This signal is then fed to an ADC for conversion.

Figure 4. Current measurement circuitry.

The circuitry described in this article has been built and tested and is available as a reference circuit for a PLC/DCS quad-channel voltage and current input with HART compatibility—CN0364. The circuitry described in this article is fully implemented on this board, with the one addition that the board also supports multiplexing the HART between the four input channels. For testing the relevant channels, the FSK transmit switch can be left open or closed, when left open the circuit would be identical to that in Figure 2. Documentation for this reference design is freely available at www.analog.com/CN0364, and hardware is also available for purchase.

This article has outlined how to implement hardware for a HART enabled analog input. It has also shown an improved HART FSK transmit circuit using the AD5700 HART modem. This improved circuit eliminates the need for any external buffers or switches saving both board space and cost. It also eliminates the need for bipolar supplies, which saves space, cost, and power supply complexity.

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