LTC6991

TimerBlox: Resettable, Low Frequency Oscillator

FEATURES

- Period Range: 1ms to 9.5 Hours
- Configured with 1 to 3 Resistors
- <1.5% Maximum Frequency Error
- Output Reset Function
- 2.25V to 5.5V Single Supply Operation
- 55µA to 80µA Supply Current
- (2ms to 9.5hr Clock Period)
- 500µs Start-Up Time
- CMOS Output Driver Sources/Sinks 20mA
- –55°C to 125°C Operating Temperature Range
- Available in Low Profile (1mm) SOT-23 (ThinSOT™) and 2mm × 3mm DFN Packages

DESCRIPTION

The LTC®6991 is a silicon oscillator with a programmable period range of 1.024ms to 9.54 hours (29.1µHz to 977Hz), specifically intended for long duration timing events. The LTC6991 is part of the TimerBlox® family of versatile silicon timing devices.

A single resistor, $R_{SET}$, programs the LTC6991’s internal master oscillator frequency. The output clock period is determined by this master oscillator and an internal frequency divider, $N_{DIV}$, programmable to eight settings from 1 to $2^{21}$.

$$t_{OUT} = \frac{N_{DIV} \cdot R_{SET}}{50k\Omega} \cdot 1.024\text{ms}, \quad N_{DIV} = 1, 8, 64, \ldots, 2^{21}$$

In normal operation, the LTC6991 oscillates with a 50% duty cycle. A reset function is provided to truncate the pulse (reducing the duty cycle). The reset pin can also be used to prevent the output from oscillating.

The RST and OUT pins can be configured for active-low or active-high operation using a polarity function.

<table>
<thead>
<tr>
<th>POL BIT</th>
<th>RST PIN</th>
<th>OUTPUT STATE</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>Oscillating</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>0 (reset)</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>1 (reset)</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>Oscillating</td>
</tr>
</tbody>
</table>

For easy configuration of the LTC6991, download the TimerBlox Designer tool at www.linear.com/timerblox.

APPLICATIONS

- “Heartbeat” Timers
- Watchdog Timers
- Intervalometers
- Periodic “Wake-Up” Call
- High Vibration, High Acceleration Environments
- Portable and Battery-Powered Equipment

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TYPICAL APPLICATION

Low Frequency Pulse Generator

Clock Period Range over Eight Divider Settings

For more information www.linear.com/LTC6991
**ABSOLUTE MAXIMUM RATINGS** (Note 1)

Supply Voltage ($V^+$ to GND) .......................... 6V
Maximum Voltage on Any Pin .......................... ($GND - 0.3V \leq V_{PIN} \leq (V^+ + 0.3V)$)

Operating Temperature Range (Note 2)
- LTC6991C ........................................... -40°C to 85°C
- LTC6991I ........................................... -40°C to 85°C
- LTC6991H ........................................... -40°C to 125°C
- LTC6991MP ......................................... -55°C to 125°C

Specified Temperature Range (Note 3)
- LTC6991C ........................................... 0°C to 70°C
- LTC6991I ........................................... -40°C to 85°C
- LTC6991H ........................................... -40°C to 125°C
- LTC6991MP ......................................... -55°C to 125°C

Junction Temperature .................................. 150°C

Storage Temperature Range ............................ -65°C to 150°C

Lead Temperature (Soldering, 10 sec) ................. 300°C

**PIN CONFIGURATION**

<table>
<thead>
<tr>
<th>TOP VIEW</th>
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<td></td>
</tr>
<tr>
<td>OUT</td>
<td>GND</td>
<td>RST</td>
<td>V+</td>
<td>DIV</td>
<td>SET</td>
<td></td>
</tr>
</tbody>
</table>

DDB PACKAGE
6-LEAD (2mm × 3mm) PLASTIC DFN

$T_{\text{MAX}} = 150°C$, $\theta_{JA} = 64°C/W$, $\theta_{JC} = 10.6°C/W$
EXPOSED PAD (PIN 7) CONNECTED TO GND, PCB CONNECTION OPTIONAL

<table>
<thead>
<tr>
<th>S6 PACKAGE</th>
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<td></td>
<td></td>
</tr>
<tr>
<td>RST</td>
<td>GND</td>
<td>V+</td>
<td>DIV</td>
<td>SET</td>
<td>OUT</td>
<td></td>
</tr>
</tbody>
</table>

6-LEAD PLASTIC TSOT-23

$T_{\text{MAX}} = 150°C$, $\theta_{JA} = 192°C/W$, $\theta_{JC} = 51°C/W$

**ORDER INFORMATION**

<table>
<thead>
<tr>
<th>TAPE AND REEL (MINI)</th>
<th>TAPE AND REEL</th>
<th>PART MARKING*</th>
<th>PACKAGE DESCRIPTION</th>
<th>SPECIFIED TEMPERATURE RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>LTC6991CDCB#TRMPBF</td>
<td>LTC6991CDCB#TRPBF</td>
<td>LDWZ</td>
<td>6-Lead (2mm × 3mm) Plastic DFN</td>
<td>0°C to 70°C</td>
</tr>
<tr>
<td>LTC6991IDCB#TRMPBF</td>
<td>LTC6991IDCB#TRPBF</td>
<td>LDWZ</td>
<td>6-Lead (2mm × 3mm) Plastic DFN</td>
<td>-40°C to 85°C</td>
</tr>
<tr>
<td>LTC6991HDCB#TRMPBF</td>
<td>LTC6991HDCB#TRPBF</td>
<td>LDWZ</td>
<td>6-Lead (2mm × 3mm) Plastic DFN</td>
<td>-40°C to 125°C</td>
</tr>
<tr>
<td>LTC6991CS6#TRMPBF</td>
<td>LTC6991CS6#TRPBF</td>
<td>LTDWY</td>
<td>6-Lead Plastic TSOT-23</td>
<td>0°C to 70°C</td>
</tr>
<tr>
<td>LTC6991IS6#TRMPBF</td>
<td>LTC6991IS6#TRPBF</td>
<td>LTDWY</td>
<td>6-Lead Plastic TSOT-23</td>
<td>-40°C to 85°C</td>
</tr>
<tr>
<td>LTC6991HS6#TRMPBF</td>
<td>LTC6991HS6#TRPBF</td>
<td>LTDWY</td>
<td>6-Lead Plastic TSOT-23</td>
<td>-40°C to 125°C</td>
</tr>
<tr>
<td>LTC6991MPS6#TRMPBF</td>
<td>LTC6991MPS6#TRPBF</td>
<td>LTDWY</td>
<td>6-Lead Plastic TSOT-23</td>
<td>-55°C to 125°C</td>
</tr>
</tbody>
</table>

TRM = 500 pieces. *Temperature grades are identified by a label on the shipping container.
Consult ADI Marketing for parts specified with wider operating temperature ranges.
Consult ADI Marketing for information on lead based finish parts.
For more information on lead free part marking, go to: http://www.linear.com/leadfree/
For more information on tape and reel specifications, go to: http://www.linear.com/tapeandreel/. Some packages are available in 500 unit reels through designated sales channels with #TRMPBF suffix.

For more information www.linear.com/LTC6991
**ELECTRICAL CHARACTERISTICS**

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at \( T_A = 25^\circ \text{C} \). Test conditions are \( V^+ = 2.25 \text{V} \) to 5.5V, \( \text{RST} = 0 \text{V} \), DIVCODE = 0 to 15 \((\text{NDIV} = 1 \text{ to } 2^{2^1})\), \( \text{RSET} = 50 \text{k} \text{Ω} \text{ to } 800 \text{k} \text{Ω} \), \( \text{RLOAD} = 5 \text{k} \), \( \text{CLOAD} = 5 \text{pF} \) unless otherwise noted.

<table>
<thead>
<tr>
<th>SYMBOL</th>
<th>PARAMETER</th>
<th>CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>tOUT</td>
<td>Output Clock Period</td>
<td>1.024m</td>
<td>34,360</td>
<td>Seconds</td>
<td></td>
<td></td>
</tr>
<tr>
<td>fOUT</td>
<td>Output Frequency</td>
<td>29.1µ</td>
<td>977</td>
<td>Hz</td>
<td></td>
<td></td>
</tr>
<tr>
<td>ΔfOUT</td>
<td>Frequency Accuracy (Note 4)</td>
<td>( 29.1 \text{µHz} \leq f_{\text{OUT}} \leq 977 \text{Hz} )</td>
<td>●</td>
<td>±0.8</td>
<td>±1.5</td>
<td>%</td>
</tr>
<tr>
<td>ΔfOUT/△T</td>
<td>Frequency Drift Over Temperature</td>
<td>●</td>
<td>±0.005</td>
<td>%/°C</td>
<td></td>
<td></td>
</tr>
<tr>
<td>ΔfOUT/△V+</td>
<td>Frequency Drift Over Supply</td>
<td>( V^+ = 4.5 \text{V} ) to 5.5V ( V^+ = 2.25 \text{V} ) to 4.5V</td>
<td>●</td>
<td>0.23</td>
<td>0.55</td>
<td>%/V</td>
</tr>
<tr>
<td></td>
<td></td>
<td>●</td>
<td>0.06</td>
<td>0.16</td>
<td>%/V</td>
<td></td>
</tr>
<tr>
<td>tS</td>
<td>Frequency Change Settling Time (Note 9)</td>
<td>1 Cycle</td>
<td></td>
<td></td>
<td></td>
<td></td>
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<tr>
<td>CLOAD</td>
<td>Output Clock Load Capacitance</td>
<td>5pF</td>
<td></td>
<td></td>
<td></td>
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<tr>
<td>VSET</td>
<td>Voltage at SET Pin</td>
<td>●</td>
<td>0.97</td>
<td>1.00</td>
<td>1.03</td>
<td>V</td>
</tr>
<tr>
<td>ΔVSET/△T</td>
<td>VSET Drift Over Temperature</td>
<td>●</td>
<td>±75</td>
<td>µV/°C</td>
<td></td>
<td></td>
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<tr>
<td>RSET</td>
<td>Frequency-Setting Resistor</td>
<td>●</td>
<td>50</td>
<td>800</td>
<td>kΩ</td>
<td></td>
</tr>
<tr>
<td>VDIV</td>
<td>DIV Pin Voltage</td>
<td>●</td>
<td>0</td>
<td>( V^+ )</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>ΔVDIV/△V+</td>
<td>DIV Pin Valid Code Range (Note 5)</td>
<td>Deviation from Ideal ( V_{\text{DIV}}/V^+ = (\text{DIVCODE} + 0.5)/16 )</td>
<td>●</td>
<td>±1.5</td>
<td>%</td>
<td></td>
</tr>
<tr>
<td>IS</td>
<td>Frequency Change Settling Time (Note 9)</td>
<td>1 Cycle</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Power Supply</td>
<td></td>
<td></td>
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<td></td>
</tr>
<tr>
<td>V+</td>
<td>Operating Supply Voltage Range</td>
<td>●</td>
<td>2.25</td>
<td>5.5</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Power-On Reset Voltage</td>
<td>●</td>
<td>1.95</td>
<td>V</td>
<td></td>
<td></td>
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<tr>
<td>IS</td>
<td>Supply Current</td>
<td>( R_L = \infty, \text{RSET} = 50 \text{k} ) ( V^+ = 5.5 \text{V} ) ( V^+ = 2.25 \text{V} )</td>
<td>●</td>
<td>105</td>
<td>135</td>
<td>µA</td>
</tr>
<tr>
<td></td>
<td></td>
<td>( R_L = \infty, \text{RSET} = 100 \text{k} ) ( V^+ = 5.5 \text{V} ) ( V^+ = 2.25 \text{V} )</td>
<td>●</td>
<td>100</td>
<td>130</td>
<td>µA</td>
</tr>
<tr>
<td></td>
<td></td>
<td>( R_L = \infty, \text{RSET} = 800 \text{k} ) ( V^+ = 5.5 \text{V} ) ( V^+ = 2.25 \text{V} )</td>
<td>●</td>
<td>65</td>
<td>85</td>
<td>µA</td>
</tr>
</tbody>
</table>
## ELECTRICAL CHARACTERISTICS

The \* denotes the specifications which apply over the full operating temperature range, otherwise specifications are at \( T_A = 25^\circ C \). Test conditions are \( V^+ = 2.25V \) to 5.5V, \( RST = 0V \), \( DIVCODE = 0 \) to 15 \( (N_{DIV} = 1 \) to \( 2^2) \), \( RSET = 50 \) to \( 800k \), \( RLOAD = \infty \), \( CLOAD = 5\)pF unless otherwise noted.

<table>
<thead>
<tr>
<th>SYMBOL</th>
<th>PARAMETER</th>
<th>CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Digital I/O</td>
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<td></td>
<td>RST Pin Input Capacitance</td>
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<td>2.5</td>
<td></td>
<td></td>
<td>pF</td>
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<td></td>
<td>RST Pin Input Current</td>
<td>( RST = 0V ) to ( V^+ )</td>
<td></td>
<td>( \pm 10 )</td>
<td></td>
<td>nA</td>
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<td></td>
<td>( V_{IH} )</td>
<td>High Level RST Pin Input Voltage</td>
<td></td>
<td>( 0.7 \cdot V^+ )</td>
<td></td>
<td>V</td>
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<tr>
<td></td>
<td>( V_{IL} )</td>
<td>Low Level RST Pin Input Voltage</td>
<td></td>
<td>( 0.3 \cdot V^+ )</td>
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<td>V</td>
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<td></td>
<td>( I_{OUT(MAX)} )</td>
<td>Output Current</td>
<td>( V^+ = 2.7V ) to 5.5V</td>
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<td>( \pm 20 )</td>
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<td></td>
<td>( V_{OH} )</td>
<td>High Level Output Voltage (Note 7)</td>
<td>( V^+ = 5.5V )</td>
<td>( I_{OUT} = –1mA )</td>
<td>( 5.45 )</td>
<td>( 5.48 )</td>
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<tr>
<td></td>
<td></td>
<td></td>
<td>( I_{OUT} = –16mA )</td>
<td>( 4.84 )</td>
<td>( 5.15 )</td>
<td>V</td>
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<td></td>
<td>( V^+ = 3.3V )</td>
<td>( I_{OUT} = –1mA )</td>
<td>( 3.24 )</td>
<td>( 3.27 )</td>
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<tr>
<td></td>
<td></td>
<td></td>
<td>( I_{OUT} = –10mA )</td>
<td>( 2.75 )</td>
<td>( 2.99 )</td>
<td>V</td>
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<td></td>
<td></td>
<td></td>
<td>( V^+ = 2.25V )</td>
<td>( I_{OUT} = –1mA )</td>
<td>( 1.21 )</td>
<td>( 2.21 )</td>
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<td></td>
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<td>( I_{OUT} = –8mA )</td>
<td>( 1.58 )</td>
<td>( 1.88 )</td>
<td>V</td>
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<td></td>
<td>( V_{OL} )</td>
<td>Low Level Output Voltage (Note 7)</td>
<td>( V^+ = 5.5V )</td>
<td>( I_{OUT} = 1mA )</td>
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<td>( 0.02 )</td>
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<td>( I_{OUT} = 16mA )</td>
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<td>( 0.26 )</td>
<td>( 0.54 )</td>
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<td>( V^+ = 3.3V )</td>
<td>( I_{OUT} = 1mA )</td>
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<td>( 0.03 )</td>
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<td>( I_{OUT} = 10mA )</td>
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<td>( 0.22 )</td>
<td>( 0.46 )</td>
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<td>( V^+ = 2.25V )</td>
<td>( I_{OUT} = 1mA )</td>
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<td>( 0.03 )</td>
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<td></td>
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<td>( I_{OUT} = 8mA )</td>
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<td>( 0.26 )</td>
<td>( 0.54 )</td>
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<tr>
<td></td>
<td>( t_{RST} )</td>
<td>Reset Propagation Delay</td>
<td>( V^+ = 5.5V )</td>
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<td>16</td>
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<td></td>
<td>( V^+ = 3.3V )</td>
<td></td>
<td>24</td>
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<td>( V^+ = 2.25V )</td>
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<td>40</td>
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<td>( t_{WIDTH} )</td>
<td>Minimum Input Pulse Width</td>
<td>( V^+ = 3.3V )</td>
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<td>5</td>
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<td>( t_{R} )</td>
<td>Output Rise Time (Note 8)</td>
<td>( V^+ = 5.5V )</td>
<td></td>
<td>1.1</td>
<td></td>
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<td></td>
<td>( V^+ = 3.3V )</td>
<td></td>
<td>1.7</td>
<td></td>
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<td></td>
<td>( V^+ = 2.25V )</td>
<td></td>
<td>2.7</td>
<td></td>
</tr>
<tr>
<td></td>
<td>( t_{F} )</td>
<td>Output Fall Time (Note 8)</td>
<td>( V^+ = 5.5V )</td>
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<td>1.0</td>
<td></td>
</tr>
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<td></td>
<td>( V^+ = 3.3V )</td>
<td></td>
<td>1.6</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>( V^+ = 2.25V )</td>
<td></td>
<td>2.4</td>
<td></td>
</tr>
</tbody>
</table>

**Note 1:** Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

**Note 2:** The LTC6991C is guaranteed functional over the operating temperature range of \(-40^\circ C \) to \( 85^\circ C \).

**Note 3:** The LTC6991C is guaranteed to meet specified performance from \( 0^\circ C \) to \( 70^\circ C \). The LTC6991 is designed, characterized and expected to meet specified performance from \(-40^\circ C \) to \( 85^\circ C \) but it is not tested or QA sampled at these temperatures. The LTC69911 is guaranteed to meet specified performance from \(-40^\circ C \) to \( 85^\circ C \). The LTC6991H is guaranteed to meet specified performance from \(-40^\circ C \) to \( 125^\circ C \). The LTC6991MP is guaranteed to meet specified performance from \(-55^\circ C \) to \( 125^\circ C \).

**Note 4:** Frequency accuracy is defined as the deviation from the \( f_{OUT} \) equation, assuming \( RSET \) is used to program the frequency.

**Note 5:** See Operation section, Table 1 and Figure 2 for a full explanation of how the DIV pin voltage selects the value of DIVCODE.

**Note 6:** The RST pin has hysteresis to accommodate slow rising or falling signals. The threshold voltages are proportional to \( V^+ \). Typical values can be estimated at any supply voltage using \( V_{RST(RISING)} = 0.55 \cdot V^+ + 185mV \) and \( V_{RST(FALLING)} = 0.48 \cdot V^+ - 155mV \).

**Note 7:** To conform to the Logic IC Standard, current out of a pin is arbitrarily given a negative value.

**Note 8:** Output rise and fall times are measured between the 10% and the 90% power supply levels with 5pF output load. These specifications are based on characterization.

**Note 9:** Settling time is the amount of time required for the output to settle within \( \pm 1\% \) of the final frequency after a 0.5x or 2x change in \( I_{SET} \).

**Note 10:** Jitter is the ratio of the deviation of the period to the mean of the period. This specification is based on characterization and is not 100% tested.

**Note 11:** Long-term drift of silicon oscillators is primarily due to the movement of ions and impurities within the silicon and is tested at 30°C under otherwise nominal operating conditions. Long-term drift is specified as ppm/√kHz due to the typically nonlinear nature of the drift. To calculate drift for a set time period, translate that time into thousands of hours, take the square root and multiply by the typical drift number. For instance, a year is 8.77kHz and would yield a drift of 266ppm at 90ppm/√kHz. Drift without power applied to the device may be approximated as 1/10th of the drift with power, or 9ppm/√kHz for a 90ppm/√kHz device.

[45x727]LTC6991

For more information www.linear.com/LTC6991
TYPICAL PERFORMANCE CHARACTERISTICS

$V^* = 3.3V, R_{SET} = 200k, T_A = 25°C$ unless otherwise noted.

- **Frequency Error vs Temperature**
  - $R_{SET} = 50k$
  - 3 PARTS
  - GUARANTEED MAX OVER TEMPERATURE
  - GUARANTEED MIN OVER TEMPERATURE

- **Frequency Error vs $R_{SET}$**
  - 3 PARTS
  - GUARANTEED MAX OVER TEMPERATURE
  - GUARANTEED MIN OVER TEMPERATURE

- **Frequency Error vs Temperature**
  - $R_{SET} = 200k$
  - 3 PARTS
  - GUARANTEED MAX OVER TEMPERATURE
  - GUARANTEED MIN OVER TEMPERATURE

- **Frequency Error vs Temperature**
  - $R_{SET} = 800k$
  - 3 PARTS
  - GUARANTEED MAX OVER TEMPERATURE
  - GUARANTEED MIN OVER TEMPERATURE

- **Frequency Drift vs Supply Voltage**
  - REFERENCED TO $V^* = 4.5V$
  - $R_{SET} = 50k$
  - $R_{SET} = 200k$
  - $R_{SET} = 800k$

- **Typical $V_{SET}$ Distribution**
  - 2 LOTS
  - DFN AND SOT-23
  - 1274 UNITS

- **$V_{SET}$ Drift vs $I_{SET}$**
  - REFERENCED TO $I_{SET} = 10µA$

- **$V_{SET}$ Drift vs Supply**
  - REFERENCED TO $V^* = 4V$

- **$V_{SET}$ vs Temperature**
  - 3 PARTS
TYPICAL PERFORMANCE CHARACTERISTICS

$V^+ = 3.3V, R_{SET} = 200k, T_A = 25^\circ C$ unless otherwise noted.

- **Supply Current vs Supply Voltage**
- **Supply Current vs Temperature**
- **Supply Current vs RSET Pin Voltage**
- **RST Threshold Voltage vs Supply Voltage**
- **RST Propagation Delay ($t_{RST}$) vs Supply Voltage**
- **Rise and Fall Time vs Supply Voltage**
- **Typical Frequency Error vs Time (Long-Term Drift)**

For more information [www.linear.com/LTC6991](http://www.linear.com/LTC6991)
**TYPICAL PERFORMANCE CHARACTERISTICS**

\[ V^+ = 3.3V, \ R_{SET} = 200k, \ T_A = 25^\circ C \] unless otherwise noted.

![Output Resistance vs Supply Current](image)

**PIN FUNCTIONS** *(DCB/S6)*

**V\(^+\)** *(Pin 1/Pin 5)*: Supply Voltage *(2.25V to 5.5V)*. This supply should be kept free from noise and ripple. It should be bypassed directly to the GND pin with a 0.1\(\mu\)F capacitor.

**DIV** *(Pin 2/Pin 4)*: Programmable Divider and Polarity Input. A \(V^+\) referenced A/D converter monitors the DIV pin voltage (\(V_{DIV}\)) to determine a 4-bit result (DIVCODE). \(V_{DIV}\) may be generated by a resistor divider between \(V^+\) and GND. Use 1\% resistors to ensure an accurate result. The DIV pin and resistors should be shielded from the OUT pin or any other traces that have fast edges. Limit the capacitance on the DIV pin to less than 100\(\mu\)F so that \(V_{DIV}\) settles quickly. The MSB of DIVCODE (POL) determines the polarity of the RST and OUT pins. If POL = 0, RST is active-high, and forces OUT low. If POL = 1, RST is active-low and forces OUT high.

**SET** *(Pin 3/Pin 3)*: Frequency-Setting Input. The voltage on the SET pin (\(V_{SET}\)) is regulated to 1\(V\) above GND. The amount of current sourced from the SET pin (\(I_{SET}\)) programs the master oscillator frequency. The \(I_{SET}\) current range is 1.25\(\mu\)A to 20\(\mu\)A. The output oscillation will stop if \(I_{SET}\) drops below approximately 500nA. A resistor connected between SET and GND is the most accurate way to set the frequency. For best performance, use a precision metal or thin film resistor of 0.5\% or better tolerance and 50ppm/°C or better temperature coefficient. For lower accuracy applications an inexpensive 1\% thick film resistor may be used.

Limit the capacitance on the SET pin to less than 10\(\mu\)F to minimize jitter and ensure stability. Capacitance less than 100\(\mu\)F maintains the stability of the feedback circuit regulating the \(V_{SET}\) voltage.

**RST** *(Pin 4/Pin 1)*: Output Reset. The behavior of the RST pin is dependent on the polarity bit (POL). The POL bit is configured via the DIVCODE setting. When POL = 0, setting RST high forces OUT low and setting RST low allows the output to oscillate. When POL = 1, RST is active low. In that case, setting RST low forces OUT high and setting RST high allows the output to oscillate.
**PIN FUNCTIONS**  (DCB/S6)

**GND (Pin 5/Pin 2):** Ground. Tie to a low inductance ground plane for best performance.

**OUT (Pin 6/Pin 6):** Oscillator Output. The OUT pin swings from GND to V+ with an output resistance of approximately 30Ω. When driving an LED or other low impedance load a series output resistor should be used to limit source/sink current to 20mA.

---

**BLOCK DIAGRAM**  (S6 package pin numbers shown)

![Block Diagram](image-url)
OPERATION

The LTC6991 is built around a master oscillator with a 1MHz maximum frequency. The oscillator is controlled by the SET pin current (ISET) and voltage (VSET), with a 1MHz • 50k conversion factor that is accurate to ±0.8% under typical conditions.

\[
\frac{1}{f_{\text{MASTER}}} = \frac{1}{1\text{MHz} \cdot 50k\Omega \cdot \frac{I_{\text{SET}}}{V_{\text{SET}}}}.
\]

A feedback loop maintains VSET at 1V ±30mV, leaving ISET as the primary means of controlling the output frequency. The simplest way to generate ISET is to connect a resistor (RSET) between SET and GND, such that ISET = VSET/RSET. The master oscillator equation reduces to:

\[
\frac{1}{f_{\text{MASTER}}} = \frac{1}{1\text{MHz} \cdot 50k\Omega} \cdot \frac{1}{R_{\text{SET}}}.
\]

From this equation, it is clear that VSET drift will not affect the output frequency when using a single program resistor (RSET). Error sources are limited to RSET tolerance and the inherent frequency accuracy ∆fOUT of the LTC6991.

RSET may range from 50k to 800k (equivalent to ISET between 1.25µA and 20µA).

Before reaching the OUT pin, the oscillator frequency passes through a fixed ÷1024 divider. The LTC6991 also includes a programmable frequency divider which can further divide the frequency by 1, 8, 64, 512, 4096, 215, 218 or 221. The divider ratio NDIV is set by a resistor divider attached to the DIV pin.

\[
\frac{1}{f_{\text{OUT}}} = \frac{1}{1\text{MHz} \cdot 50k\Omega} \cdot \frac{1}{N_{\text{DIV}}} \cdot \frac{I_{\text{SET}}}{V_{\text{SET}}},
\]

or

\[
f_{\text{OUT}} = \frac{1}{50k\Omega} \cdot \frac{1}{1024} \cdot \frac{N_{\text{DIV}}}{V_{\text{SET}}},
\]

or

\[
t_{\text{OUT}} = \frac{1}{50k\Omega} \cdot \frac{1}{1024} \cdot \frac{N_{\text{DIV}}}{I_{\text{SET}}} \cdot 1.024\text{ms}
\]

with RSET in place of VSET/ISET the equation reduces to:

\[
t_{\text{OUT}} = \frac{N_{\text{DIV}} \cdot R_{\text{SET}}}{50k\Omega} \cdot 1.024\text{ms}
\]

DIVCODE

The DIV pin connects to an internal, V+ referenced 4-bit A/D converter that determines the DIVCODE value. DIVCODE programs two settings on the LTC6991:

1. DIVCODE determines the output frequency divider setting, NDIV.
2. DIVCODE determines the polarity of the RST and OUT pins, via the POL bit.

VDIV may be generated by a resistor divider between V+ and GND as shown in Figure 1.

![Figure 1. Simple Technique for Setting DIVCODE](image)

Table 1 offers recommended 1% resistor values that accurately produce the correct voltage division as well as the corresponding NDIV and POL values for the recommended resistor pairs. Other values may be used as long as:

1. The VDIV/V+ ratio is accurate to ±1.5% (including resistor tolerances and temperature effects)
2. The driving impedance (R1||R2) does not exceed 500kΩ.

If the voltage is generated by other means (i.e., the output of a DAC) it must track the V+ supply voltage. The last column in Table 1 shows the ideal ratio of VDIV to the supply voltage, which can also be calculated as:

\[
\frac{V_{\text{DIV}}}{V^+} = \frac{\text{DIVCODE} + 0.5}{16} \pm 1.5\%
\]

For example, if the supply is 3.3V and the desired DIVCODE is 4, VDIV = 0.281 • 3.3V = 928mV ± 50mV.

Figure 2 illustrates the information in Table 1, showing that NDIV is symmetric around the DIVCODE midpoint.
### Table 1. DIVCODE Programming

<table>
<thead>
<tr>
<th>DIVCODE</th>
<th>POL</th>
<th>N&lt;sub&gt;DIV&lt;/sub&gt;</th>
<th>RECOMMENDED t&lt;sub&gt;OUT&lt;/sub&gt;</th>
<th>R1 (kΩ)</th>
<th>R2 (kΩ)</th>
<th>V&lt;sub&gt;DIV&lt;/sub&gt;/V+</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>1</td>
<td>1.024ms to 16.384ms</td>
<td>Open</td>
<td>Short</td>
<td>≤0.03125 ±0.015</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>8</td>
<td>8.192ms to 131ms</td>
<td>976</td>
<td>102</td>
<td>0.09375 ±0.015</td>
</tr>
<tr>
<td>2</td>
<td>0</td>
<td>64</td>
<td>65.5ms to 1.05sec</td>
<td>976</td>
<td>182</td>
<td>0.15625 ±0.015</td>
</tr>
<tr>
<td>3</td>
<td>0</td>
<td>512</td>
<td>524ms to 8.39sec</td>
<td>1000</td>
<td>280</td>
<td>0.21875 ±0.015</td>
</tr>
<tr>
<td>4</td>
<td>0</td>
<td>4,096</td>
<td>4.19sec to 67.1sec</td>
<td>1000</td>
<td>392</td>
<td>0.28125 ±0.015</td>
</tr>
<tr>
<td>5</td>
<td>0</td>
<td>32,768</td>
<td>33.6sec to 537sec</td>
<td>1000</td>
<td>523</td>
<td>0.34375 ±0.015</td>
</tr>
<tr>
<td>6</td>
<td>0</td>
<td>262,144</td>
<td>268sec to 4,295sec</td>
<td>1000</td>
<td>681</td>
<td>0.40625 ±0.015</td>
</tr>
<tr>
<td>7</td>
<td>0</td>
<td>2,097,152</td>
<td>2,147sec to 34,360sec</td>
<td>1000</td>
<td>887</td>
<td>0.46875 ±0.015</td>
</tr>
<tr>
<td>8</td>
<td>1</td>
<td>2,097,152</td>
<td>2,147sec to 34,360sec</td>
<td>887</td>
<td>1000</td>
<td>0.53125 ±0.015</td>
</tr>
<tr>
<td>9</td>
<td>1</td>
<td>262,144</td>
<td>268sec to 4,295sec</td>
<td>681</td>
<td>1000</td>
<td>0.59375 ±0.015</td>
</tr>
<tr>
<td>10</td>
<td>1</td>
<td>32,768</td>
<td>33.6sec to 537sec</td>
<td>523</td>
<td>1000</td>
<td>0.65625 ±0.015</td>
</tr>
<tr>
<td>11</td>
<td>1</td>
<td>4,096</td>
<td>4.19sec to 67.1sec</td>
<td>392</td>
<td>1000</td>
<td>0.71875 ±0.015</td>
</tr>
<tr>
<td>12</td>
<td>1</td>
<td>512</td>
<td>524ms to 8.39sec</td>
<td>280</td>
<td>1000</td>
<td>0.78125 ±0.015</td>
</tr>
<tr>
<td>13</td>
<td>1</td>
<td>64</td>
<td>65.5ms to 1.05sec</td>
<td>182</td>
<td>976</td>
<td>0.84375 ±0.015</td>
</tr>
<tr>
<td>14</td>
<td>1</td>
<td>8</td>
<td>8.192ms to 131ms</td>
<td>102</td>
<td>976</td>
<td>0.90625 ±0.015</td>
</tr>
<tr>
<td>15</td>
<td>1</td>
<td>1</td>
<td>1.024ms to 16.384ms</td>
<td>Short</td>
<td>Open</td>
<td>≥0.96875 ±0.015</td>
</tr>
</tbody>
</table>

### Figure 2. Frequency Range and POL Bit vs DIVCODE
**OPERATION**

**RST Pin and Polarity (POL) Bit**

The RST pin controls the state of the LTC6991’s output as seen on the OUT pin. The active/inactive voltage levels depend on the POL bit setting.

**Table 2. Output States**

<table>
<thead>
<tr>
<th>POL BIT</th>
<th>RST PIN</th>
<th>OUTPUT STATE</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>Oscillating</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>0 (reset)</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1 (reset)</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>Oscillating</td>
</tr>
</tbody>
</table>

Each period of the LTC6991’s internal oscillator clocks the output state latch (see Block Diagram). The reset pin (RST) can reset or hold off the output latch. The active state of the reset pin is determined by the polarity function (POL). Similarly, the output latch is followed by a buffer that can invert the output. The output polarity is also controlled by the POL bit.

If POL = 0, the reset pin is active high and the output latch is not inverted. Therefore, pulling the RST pin high will reset the output latch and force the OUT pin low. Pulling RST low will allow the output to oscillate, with the next rising edge dependent on the internal oscillator.

If POL = 1, the reset pin is active low and the output latch is inverted. Therefore, pulling the RST pin low will reset the output latch and force the OUT pin high. Pulling RST high will allow the output to oscillate, with the next falling edge dependent on the internal oscillator.

Note that the master oscillator frequency and phase are not affected by the RST pin; The LTC6991 continues to oscillate, internally, even when RST is active. While the reset function can block an output pulse, its exact placement in time can only be changed by power cycling the LTC6991.

![Figure 3. RST Timing Diagram (POL = 0)](image)

![Figure 4. RST Timing Diagram (POL = 1)](image)
**OPERATION**

**Changing DIVCODE After Start-Up**

Following start-up, the A/D converter will continue monitoring $V_{DIV}$ for changes. The LTC6991 will respond to DIVCODE changes in less than one cycle.

$$t_{DIVCODE} < 500 \cdot t_{MASTER} < t_{OUT}$$

The output may have an inaccurate pulse width during the frequency transition. But the transition will be glitch-free and no high or low pulse can be shorter than the master clock period. A digital filter is used to guarantee the DIVCODE has settled to a new value before making changes to the output.

**Start-Up Time**

When power is first applied, the power-on reset (POR) circuit will initiate the start-up time, $t_{START}$. The OUT pin is held low during this time. The typical value for $t_{START}$ ranges from 0.5ms to 8ms depending on the master oscillator frequency (independent of $N_{DIV}$):

$$t_{START(TYP)} = 500 \cdot t_{MASTER}$$

During start-up, the DIV pin A/D converter must determine the correct DIVCODE before the output is enabled.

The start-up time may increase if the supply or DIV pin voltages are not stable. For this reason, it is recommended to minimize the capacitance on the DIV pin so it will properly track $V^+$. Less than 100pF will not affect performance.

**Start-Up Behavior**

When first powered up, the output is held low. If the polarity is set for non-inversion (POL = 0) and the output is enabled (RST = 0) at the end of the start-up time, OUT will begin oscillating. If the output is being reset (RST = 1) at the end of the start-up time, the first pulse will be skipped. Subsequent pulses will also be skipped until RST = 0.

In inverted operation (POL = 1), the start-up sequence is similar. However, the LTC6991 does not know the correct DIVCODE setting when first powered up, so the output defaults low. At the end of $t_{START}$, the value of DIVCODE is recognized and OUT goes high (inactive) because POL = 1. If RST = 1 (inactive) then OUT will quickly fall after a single $t_{MASTER}$ cycle. If RST = 0 at the end of the start-up time, the output is held in reset and remains high.

Figures 7 to 10 detail the four possible start-up sequences.
**Figure 7. Start-Up Timing Diagram (RST = 0, POL = 0)**

**Figure 8. Start-Up Timing Diagram (RST = 1, POL = 0)**

**Figure 9. Start-Up Timing Diagram (RST = 0, POL = 1)**

**Figure 10. Start-Up Timing Diagram (RST = 1, POL = 1)**
APPLICATIONS INFORMATION

Basic Operation

The simplest and most accurate method to program the LTC6991 is to use a single resistor, \( R_{\text{SET}} \), between the SET and GND pins. The design procedure is a 3-step process. First select the POL bit setting and \( N_{\text{DIV}} \) value, then calculate the value for the \( R_{\text{SET}} \) resistor.

Alternatively, Linear Technology offers the easy to use TimerBlox Designer tool to quickly design any LTC6991 based circuit. Download the free TimerBlox Designer software at www.linear.com/timerblox.

Step 1: Select the POL Bit Setting

The LTC6991 can operate in normal (active-high) or inverted (active-low) modes, depending on the setting of the POL bit. The best choice depends on the application.

Step 2: Select the \( N_{\text{DIV}} \) Frequency Divider Value

As explained earlier, the voltage on the DIV pin sets the DIVCODE which determines both the POL bit and the \( N_{\text{DIV}} \) value. For a given output clock period, \( N_{\text{DIV}} \) should be selected to be within the following range.

\[
16.384\,\text{ms} \leq N_{\text{DIV}} \leq 1.024\,\text{ms} \tag{1}
\]

To minimize supply current, choose the lowest \( N_{\text{DIV}} \) value (generally recommended). Alternatively, use Table 1 as a guide to select the best \( N_{\text{DIV}} \) value for the given application.

With POL already chosen, this completes the selection of DIVCODE. Use Table 1 to select the proper resistor divider or \( V_{\text{DIV}}/V^+ \) ratio to apply to the DIV pin.

Step 3: Calculate and Select \( R_{\text{SET}} \)

The final step is to calculate the correct value for \( R_{\text{SET}} \) using the following equation.

\[
R_{\text{SET}} = \frac{50k}{1.024\,\text{ms}} \cdot \frac{t_{\text{OUT}}}{N_{\text{DIV}}} \tag{2}
\]

Select the standard resistor value closest to the calculated value.

Example: Design a 1Hz oscillator with minimum power consumption and active-high reset input.

Step 1: Select the POL Bit Setting

For noninverted (active-high) functionality, choose POL = 0.

Step 2: Select the \( N_{\text{DIV}} \) Frequency Divider Value

Choose an \( N_{\text{DIV}} \) value that meets the requirements of Equation (1), using \( t_{\text{OUT}} = 1000\,\text{ms} \):

\[
61.04 \leq N_{\text{DIV}} \leq 976.6
\]

Potential settings for \( N_{\text{DIV}} \) include 64 and 512. \( N_{\text{DIV}} = 64 \) is the best choice, as it minimizes supply current by using a large \( R_{\text{SET}} \) resistor. POL = 0 and \( N_{\text{DIV}} = 64 \) requires DIVCODE = 2. Using Table 1, choose \( R1 = 976k \) and \( R2 = 182k \) values to program DIVCODE = 2.

Step 3: Select \( R_{\text{SET}} \)

Calculate the correct value for \( R_{\text{SET}} \) using Equation (2).

\[
R_{\text{SET}} = \frac{50k}{1.024\,\text{ms}} \cdot \frac{1000\,\text{ms}}{64} = 763k
\]

Since 763k is not available as a standard 1% resistor, substitute 768k if a ~0.7% frequency shift is acceptable. Otherwise, select a parallel or series pair of resistors such as 576k + 187k to attain a more precise resistance.

The completed design is shown in Figure 11.

Example: Design a 1Hz oscillator with minimum power consumption and active-high reset input.
**APPLICATIONS INFORMATION**

**LTC6991 as “Wake-Up Timer”**

The output latch reset function provided by the RST pin allows the LTC6991 to enable a larger system at regular intervals. The on-time can be controlled by the system. This allows the system to shut itself down immediately after performing its tasks, reducing power consumption.

Figure 12 shows an example using “black boxes” for a switching regulator and the system being duty-cycled. In some cases, an RC filter may be necessary at the RST input to filter start-up glitches from the system as it is powered on.

If the LTC6991 is enabling a switching regulator that can operate on supplies greater than 5.5V, it will be necessary to limit the supply voltage provided to the LTC6991. If the LTC6991 output is not heavily loaded, and if a large RSET resistor is used, the supply current will not be much larger than 100µA, so a simple regulator circuit can be constructed using a Zener diode.

![Diagram of LTC6991 as Wake-Up Timer](image-url)

Figure 12. Powering Up a System Once an Hour
Self-Resetting Circuits

The RST pin has hysteresis to accommodate slow-changing input voltages. Furthermore, the trip points are proportional to the supply voltage (see Note 6 and the RST Threshold Voltage vs Supply Voltage curve in Typical Performance Characteristics). This allows an RC time constant at the RST input to generate a delay that is nearly independent of the supply voltage.

A simple application of this technique allows the LTC6991 output to reset itself, producing a well-controlled pulse once each cycle. Figure 13a and Figure 13b show circuits that produce approximately 1µs pulses once a minute. The only difference is in the POL bit setting, which controls whether the pulse is positive or negative.

Voltage Controlled Frequency

With one additional resistor, the LTC6991 output frequency can be manipulated by an external voltage. As shown in Figure 14, voltage $V_{CTRL}$ sources/sinks a current through $R_{VCO}$ to vary the $I_{SET}$ current, which in turn modulates the output frequency as described in Equation (3).

$$f_{OUT} = \frac{1 \text{MHz} \cdot 50k\Omega}{1024 \cdot N_{DIV} \cdot R_{VCO}} \cdot \left(1 - \frac{R_{VCO}}{R_{SET}} \cdot \frac{V_{CTRL}}{V_{SET}}\right)$$  (3)
**APPLICATIONS INFORMATION**

**Digital Frequency Control**

The control voltage can be generated by a DAC (digital-to-analog converter), resulting in a digitally-controlled frequency. Many DACs allow for the use of an external reference. If such a DAC is used to provide the VCTRL voltage, the VSET dependency can be eliminated by buffering VSET and using it as the DAC's reference voltage, as shown in Figure 15. The DAC's output voltage now tracks any VSET variation and eliminates it as an error source.

The SET pin cannot be tied directly to the reference input of the DAC because the current drawn by the DAC's REF input would affect the frequency.

**ISET Extremes (Master Oscillator Frequency Extremes)**

When operating with ISET outside of the recommended 1.25µA to 20µA range, the master oscillator operates outside of the 62.5kHz to 1MHz range in which it is most accurate.

The oscillator can still function with reduced accuracy for ISET < 1.25µA. At approximately 500nA, the oscillator output will be frozen in its current state. The output could halt in a high or low state. This avoids introducing short pulses when frequency modulating a very low frequency output.

At the other extreme, it is not recommended to operate the master oscillator beyond 2MHz because the accuracy of the DIV pin ADC will suffer.

**Frequency Modulation and Settling Time**

The LTC6991 will respond to changes in ISET up to a −3dB bandwidth of 0.4 • fOUT.

Following a 2× or 0.5× step change in ISET, the output frequency takes less than one cycle to settle to within 1% of the final value.

**Power Supply Current**

The power supply current varies with frequency, supply voltage and output loading. It can be estimated under any condition using the following equation. This equation ignores CLOAD (valid for CLOAD < 1nF) and assumes the output has 50% duty cycle.

\[
I_{S(TYP)} \approx V^+ \cdot f_{MASTER} \cdot 7.8pF + \frac{V^+}{420k\Omega} + \frac{V^+}{2 \cdot R_{LOAD}} + 1.8 \cdot I_{SET} + 50\mu A
\]

For more information [www.linear.com/LTC6991](http://www.linear.com/LTC6991)
Supply Bypassing and PCB Layout Guidelines

The LTC6991 is a 2.2% accurate silicon oscillator when used in the appropriate manner. The part is simple to use and by following a few rules, the expected performance is easily achieved. Adequate supply bypassing and proper PCB layout are important to ensure this.

Figure 16 shows example PCB layouts for both the TSOT-23 and DFN packages using 0603 sized passive components. The layouts assume a two layer board with a ground plane layer beneath and around the LTC6991. These layouts are a guide and need not be followed exactly.

1. Connect the bypass capacitor, C1, directly to the V+ and GND pins using a low inductance path. The connection from C1 to the V+ pin is easily done directly on the top layer. For the DFN package, C1’s connection to GND is also simply done on the top layer. For the TSOT-23, OUT can be routed through the C1 pads to allow a good C1 GND connection. If the PCB design rules do not allow that, C1’s GND connection can be accomplished through multiple vias to the ground plane. Multiple vias for both the GND pin connection to the ground plane and the C1 connection to the ground plane are recommended to minimize the inductance. Capacitor C1 should be a 0.1µF ceramic capacitor.

2. Place all passive components on the top side of the board. This minimizes trace inductance.

3. Place R_SET as close as possible to the SET pin and make a direct, short connection. The SET pin is a current summing node and currents injected into this pin directly modulate the operating frequency. Having a short connection minimizes the exposure to signal pickup.

4. Connect R_SET directly to the GND pin. Using a long path or vias to the ground plane will not have a significant affect on accuracy, but a direct, short connection is recommended and easy to apply.

5. Use a ground trace to shield the SET pin. This provides another layer of protection from radiated signals.

6. Place R1 and R2 close to the DIV pin. A direct, short connection to the DIV pin minimizes the external signal coupling.
TYPICAL APPLICATIONS

5 Second On/Off Timed Relay Driver

1.5ms Radio Control Servo Reference Pulse Generator

Cycling (10 Seconds On/Off) Symmetrical Power Supplies

For more information www.linear.com/LTC6991
TYPICAL APPLICATIONS

Isolated AC Load Flasher

Interval (Wiper) Timer
PACKAGE DESCRIPTION

Please refer to http://www.linear.com/product/LTC6991#packaging for the most recent package drawings.

DCB Package
6-Lead Plastic DFN (2mm × 3mm)
(Reference LTC DWG # 05-08-1715 Rev A)

NOTE:
1. DRAWING TO BE MADE A JEDEC PACKAGE OUTLINE M0-229 VARIATION OF (TBD)
2. DRAWING NOT TO SCALE
3. ALL DIMENSIONS ARE IN MILLIMETERS
4. DIMENSIONS OF EXPOSED PAD ON BOTTOM OF PACKAGE DO NOT INCLUDE MOLD FLASH. MOLD FLASH, IF PRESENT, SHALL NOT EXCEED 0.15mm ON ANY SIDE
5. EXPOSED PAD SHALL BE SOLDER PLATED
6. SHADED AREA IS ONLY A REFERENCE FOR PIN 1 LOCATION ON THE TOP AND BOTTOM OF PACKAGE

For more information www.linear.com/LTC6991
PACKAGE DESCRIPTION

Please refer to http://www.linear.com/product/LTC6991#packaging for the most recent package drawings.

S6 Package
6-Lead Plastic TSOT-23
(Reference LTC DWG # 05-08-1636)

NOTE:
1. DIMENSIONS ARE IN MILLIMETERS
2. DRAWING NOT TO SCALE
3. DIMENSIONS ARE INCLUSIVE OF PLATING
4. DIMENSIONS ARE EXCLUSIVE OF MOLD FLASH AND METAL BURR
5. MOLD FLASH SHALL NOT EXCEED 0.054mm
6. JEDEC PACKAGE REFERENCE IS MO-193
## REVISION HISTORY

<table>
<thead>
<tr>
<th>REV</th>
<th>DATE</th>
<th>DESCRIPTION</th>
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| A   | 7/11  | Updated Description, Typical Application, and Order Information sections  
Added additional information to $\Delta f_{\text{OUT}}/\Delta V^*$ and included Note 11 in Electrical Characteristics section  
Added Typical Frequency Error vs Time curve to Typical Performance Characteristics section  
Added text to Basic Operation paragraph in Applications Information section | 1, 2, 3, 4, 6, 14 |
| B   | 1/12  | Added MP grade                                                                                                                                                                                                   | 1, 2, 4     |
| C   | 1/18  | Corrected $I_{\text{OUT(\text{MAX)}}}$ parameter typo. Corrected Figure number.                                                                                                                                  | 4, 17, 18   |
**RELATED PARTS**

<table>
<thead>
<tr>
<th>PART NUMBER</th>
<th>DESCRIPTION</th>
<th>COMMENTS</th>
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<tbody>
<tr>
<td>LTC1799</td>
<td>1MHz to 33MHz ThinSOT Silicon Oscillator</td>
<td>Wide Frequency Range</td>
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<tr>
<td>LTC6900</td>
<td>1MHz to 20MHz ThinSOT Silicon Oscillator</td>
<td>Low Power, Wide Frequency Range</td>
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<tr>
<td>LTC6906/LTC6907</td>
<td>10kHz to 1MHz or 40kHz ThinSOT Silicon Oscillators</td>
<td>Micropower, ( I_{\text{SUPPLY}} = 35\mu\text{A} ) at 400kHz</td>
</tr>
<tr>
<td>LTC6930</td>
<td>Fixed Frequency Oscillator, 32.768kHz to 8.192MHz</td>
<td>0.09% Accuracy, 110( \mu \text{s} ) Start-Up Time, 105( \mu \text{A} ) at 32kHz</td>
</tr>
<tr>
<td>LTC6990</td>
<td>TimerBlox: Voltage-Controlled Silicon Oscillator</td>
<td>Fixed-Frequency or Voltage-Controlled Operation</td>
</tr>
<tr>
<td>LTC6992</td>
<td>TimerBlox: Voltage-Controlled Pulse Width Modulator (PWM)</td>
<td>Simple PWM with Wide Frequency Range</td>
</tr>
<tr>
<td>LTC6993</td>
<td>TimerBlox: Monostable Pulse Generator (One Shot)</td>
<td>Resistor Programmable Pulse Width of 1( \mu \text{s} ) to 34sec</td>
</tr>
<tr>
<td>LTC6994</td>
<td>TimerBlox: Delay Block/Debouncer</td>
<td>Delays Rising, Falling or Both Edges 1( \mu \text{s} ) to 34sec</td>
</tr>
</tbody>
</table>

**TYPICAL APPLICATION**

Intervalometer for Time-Lapse Photography

![Circuit Diagram](https://www.linear.com/LTC6991/relatedparts.png)