LTC2508-32
32-Bit Oversampling ADC with Configurable Digital Filter

FEATURES
- ±0.5 ppm INL (Typ)
- 145 dB Dynamic Range (Typ) at 61 sps
- 131 dB Dynamic Range (Typ) at 4 ksps
- Guaranteed 32-Bits No Missing Codes
- Configurable Digital Filter with Synchronization
- Relaxed Anti-Aliasing Filter Requirements
- Dual Output 32-Bit SAR ADC
- 32-Bit Digitally Filtered Low Noise Output
- 14-Bit Differential + 8-Bit Common Mode 1 Msps No Latency Output
- Wide Input Common Mode Range
- Guaranteed Operation to 85°C
- 1.8V to 5V SPI-Compatible Serial I/O
- Low Power: 24mW at 1 Msps
- 24-Lead 7mm × 4mm DFN Package

APPLICATIONS
- Seismology
- Energy Exploration
- Automated Test Equipment (ATE)
- High Accuracy Instrumentation

DESCRIPTION
The LTC®2508-32 is a low noise, low power, high performance 32-bit ADC with an integrated configurable digital filter. Operating from a single 2.5V supply, the LTC2508-32 features a fully differential input range up to ±VREF, with VREF ranging from 2.5V to 5.1V. The LTC2508-32 supports a wide common mode range from 0V to VREF simplifying analog signal conditioning requirements.

The LTC2508-32 simultaneously provides two output codes: (1) a 32-bit digitally filtered high precision low noise code, and (2) a 22-bit no latency composite code. The configurable digital filter reduces measurement noise by lowpass filtering and down-sampling the stream of data from the SAR ADC core, giving the 32-bit filtered output code. The 22-bit composite code consists of a 14-bit code representing the differential voltage and an 8-bit code representing the common mode voltage. The 22-bit composite code is available each conversion cycle, with no cycle of latency.

The digital filter can be easily configured for 4 different down-sampling factors by pin strapping. The configurations provide a dynamic range of 131dB at 3.9ksps and 145dB at 61sp. The digital lowpass filter relaxes the requirements for analog anti-aliasing. Multiple LTC2508-32 devices can be easily synchronized using the SYNC pin.

TYPICAL APPLICATION

![TYPICAL APPLICATION Diagram]

Integral Nonlinearity vs Input Voltage

For more information www.linear.com/LTC2508-32
LTC2508-32

ABSOLUTE MAXIMUM RATINGS
(Notes 1, 2)
Supply Voltage (V_{DD}) .......................... 2.8V
Supply Voltage (OV_{DD}) ......................... 6V
Reference Input (REF) ......................... 6V
Analog Input Voltage (Note 3)
\[ V_{IN^+}, V_{IN^-} \] .......................... (GND – 0.3V) to (REF + 0.3V)
Digital Input Voltage
(Note 3) ........................................... (GND – 0.3V) to (OV_{DD} + 0.3V)
Digital Output Voltage
(Note 3) ........................................... (GND – 0.3V) to (OV_{DD} + 0.3V)
Power Dissipation .................................. 500mW
Operating Temperature Range
LTC2508C-32 ...................................... 0°C to 70°C
LTC2508I-32 ...................................... –40°C to 85°C
Storage Temperature Range ............. –65°C to 150°C

PIN CONFIGURATION

ORDER INFORMATION
http://www.linear.com/product/LTC2508-32#orderinfo

LEAD FREE FINISH | TAPE AND REEL | PART MARKING* | PACKAGE DESCRIPTION | TEMPERATURE RANGE
--- | --- | --- | --- | ---
LTC2508CDKD-32#PBF | LTC2508CDKD-32#TRPBF | 250832 | 24-Lead (7mm × 4mm) Plastic DFN | 0°C to 70°C
LTC2508IDKD-32#PBF | LTC2508IDKD-32#TRPBF | 250832 | 24-Lead (7mm × 4mm) Plastic DFN | –40°C to 85°C

Consult LTC Marketing for parts specified with wider operating temperature ranges. * The temperature grade is identified by a label on the shipping container.

For more information on lead free part marking, go to: http://www.linear.com/leadfree/
For more information on tape and reel specifications, go to: http://www.linear.com/tapeandreel/. Some packages are available in 500 unit reels through designated sales channels with #TRMPBF suffix.

ELECTRICAL CHARACTERISTICS
The \( \bullet \) denotes the specifications which apply over the full operating temperature range, otherwise specifications are at \( T_A = 25°C \). (Note 4)

<table>
<thead>
<tr>
<th>SYMBOL</th>
<th>PARAMETER</th>
<th>CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>( V_{IN^+} )</td>
<td>Absolute Input Range (IN^+)</td>
<td>(Note 5)</td>
<td>( 0 )</td>
<td>( V_{REF} )</td>
<td>( V )</td>
<td></td>
</tr>
<tr>
<td>( V_{IN^-} )</td>
<td>Absolute Input Range (IN^-)</td>
<td>(Note 5)</td>
<td>( 0 )</td>
<td>( V_{REF} )</td>
<td>( V )</td>
<td></td>
</tr>
<tr>
<td>( V_{IN^+} - V_{IN^-} )</td>
<td>Input Differential Voltage Range ( V_{IN} = V_{IN^+} - V_{IN^-} )</td>
<td>( -V_{REF} )</td>
<td>( V_{REF} )</td>
<td>( V )</td>
<td></td>
<td></td>
</tr>
<tr>
<td>( V_{CM} )</td>
<td>Common-Mode Input Range</td>
<td>( 0 )</td>
<td>( V_{REF} )</td>
<td>( V )</td>
<td></td>
<td></td>
</tr>
<tr>
<td>( I_{IN} )</td>
<td>Analog Input Leakage Current</td>
<td>Sample Mode Hold Mode</td>
<td>10</td>
<td>nA</td>
<td></td>
<td></td>
</tr>
<tr>
<td>( C_{IN} )</td>
<td>Analog Input Capacitance</td>
<td></td>
<td>45</td>
<td>pF</td>
<td></td>
<td></td>
</tr>
<tr>
<td>( CMRR )</td>
<td>Input Common Mode Rejection Ratio</td>
<td>Filtered Output ( V_{IN^+} = 4.5V_{P-P}, 200Hz \text{ Sine} )</td>
<td>128</td>
<td>dB</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

For more information www.linear.com/LTC2508-32
### Converter Characteristics for Filtered Output (SDOA)

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25°C$. (Note 4)

<table>
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<tr>
<th>SYMBOL</th>
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<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
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</thead>
<tbody>
<tr>
<td></td>
<td>Resolution</td>
<td>●</td>
<td>32</td>
<td></td>
<td></td>
<td>Bits</td>
</tr>
<tr>
<td></td>
<td>No Missing Codes</td>
<td>●</td>
<td>32</td>
<td></td>
<td></td>
<td>Bits</td>
</tr>
<tr>
<td></td>
<td>DF</td>
<td>●</td>
<td>256</td>
<td>16384</td>
<td></td>
<td>ppm</td>
</tr>
<tr>
<td></td>
<td>Transition Noise</td>
<td>DF = 256 (Note 6)</td>
<td>0.095</td>
<td>0.055</td>
<td>0.03</td>
<td>ppm</td>
</tr>
<tr>
<td></td>
<td></td>
<td>DF = 1024</td>
<td></td>
<td></td>
<td></td>
<td>ppm</td>
</tr>
<tr>
<td></td>
<td></td>
<td>DF = 4096</td>
<td></td>
<td></td>
<td></td>
<td>ppm</td>
</tr>
<tr>
<td></td>
<td></td>
<td>DF = 16384</td>
<td></td>
<td></td>
<td></td>
<td>ppm</td>
</tr>
<tr>
<td></td>
<td>INL</td>
<td>●</td>
<td>–3.5</td>
<td>0.5</td>
<td>3.5</td>
<td>ppm</td>
</tr>
<tr>
<td></td>
<td>ZSE</td>
<td>●</td>
<td>–13</td>
<td>0</td>
<td>13</td>
<td>ppm</td>
</tr>
<tr>
<td></td>
<td>Zero-Scale Error Drift</td>
<td>±14</td>
<td>ppm/°C</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>FSE</td>
<td>●</td>
<td>–100</td>
<td>±10</td>
<td>100</td>
<td>ppm/°C</td>
</tr>
<tr>
<td></td>
<td>Full-Scale Error Drift</td>
<td>±0.05</td>
<td>ppm/°C</td>
<td></td>
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</tbody>
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### Dynamic Accuracy for Filtered Output (SDOA)

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25°C$ and $A_{IN} = –20$dBFS. (Notes 4, 10)

<table>
<thead>
<tr>
<th>SYMBOL</th>
<th>PARAMETER</th>
<th>CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
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</thead>
<tbody>
<tr>
<td></td>
<td>DR</td>
<td>Dynamic Range</td>
<td>$V_{REF} = 5V, DF = 256$  $IN^+ = IN^- = V_{CM}, V_{REF} = 2.5V, DF = 1024$  $IN^+ = IN^- = V_{CM}, V_{REF} = 5V, DF = 4096$  $IN^+ = IN^- = V_{CM}, V_{REF} = 5V, DF = 16384$</td>
<td>● 125</td>
<td>131</td>
<td></td>
</tr>
<tr>
<td></td>
<td>THD</td>
<td>Total Harmonic Distortion</td>
<td>$f_{IN} = 200$Hz, $V_{REF} = 2.5V, DF = 256$  $f_{IN} = 200$Hz, $V_{REF} = 5V, DF = 256$</td>
<td>● –118</td>
<td>–118</td>
<td>–108</td>
</tr>
<tr>
<td></td>
<td>SFDR</td>
<td>Spurious Free Dynamic Range</td>
<td>$f_{IN} = 200$Hz, $V_{REF} = 2.5V, DF = 256$  $f_{IN} = 200$Hz, $V_{REF} = 5V, DF = 256$</td>
<td>● 108</td>
<td>118</td>
<td>118</td>
</tr>
<tr>
<td></td>
<td>–3dB Input Bandwidth</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>MHz</td>
</tr>
<tr>
<td></td>
<td>Aperture Delay</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>ps</td>
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<tr>
<td></td>
<td>Aperture Jitter</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>DS RMS</td>
</tr>
<tr>
<td></td>
<td>Transient Response</td>
<td>Full-Scale Step</td>
<td></td>
<td></td>
<td>125</td>
<td>ns</td>
</tr>
</tbody>
</table>

For more information [www.linear.com/LTC2508-32](http://www.linear.com/LTC2508-32)
## Converter Characteristics for No Latency Output (SDOB)

The *denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25°C$. (Note 4)

<table>
<thead>
<tr>
<th>SYMBOL</th>
<th>PARAMETER</th>
<th>CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
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<tr>
<td></td>
<td>Resolution:</td>
<td>Differential</td>
<td>14</td>
<td></td>
<td></td>
<td>Bits</td>
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<td></td>
<td></td>
<td>Common Mode</td>
<td>8</td>
<td></td>
<td></td>
<td>Bits</td>
</tr>
<tr>
<td></td>
<td>No Missing Codes:</td>
<td>Differential</td>
<td>14</td>
<td></td>
<td></td>
<td>Bits</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Common Mode</td>
<td>8</td>
<td></td>
<td></td>
<td>Bits</td>
</tr>
<tr>
<td></td>
<td>Transition Noise</td>
<td>Differential</td>
<td>1</td>
<td></td>
<td></td>
<td>LSB_RMS</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Common Mode</td>
<td>1</td>
<td></td>
<td></td>
<td>LSB_RMS</td>
</tr>
<tr>
<td></td>
<td>INL</td>
<td>Integral Linearity Error</td>
<td>Differential</td>
<td>±0.1</td>
<td>±0.1</td>
<td>LSB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Common Mode</td>
<td>±0.1</td>
<td>±0.1</td>
<td>LSB</td>
<td></td>
</tr>
<tr>
<td></td>
<td>DNL</td>
<td>Differential Linearity Error</td>
<td>Differential</td>
<td>±1</td>
<td>±1</td>
<td>LSB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Common Mode</td>
<td>±1</td>
<td>±1</td>
<td>LSB</td>
<td></td>
</tr>
<tr>
<td></td>
<td>ZSE</td>
<td>Zero Scale Error</td>
<td>Differential</td>
<td>±1</td>
<td>±1</td>
<td>LSB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Common Mode</td>
<td>±1</td>
<td>±1</td>
<td>LSB</td>
<td></td>
</tr>
<tr>
<td></td>
<td>FSE</td>
<td>Zero Scale Error</td>
<td>Differential</td>
<td>±1</td>
<td>±1</td>
<td>LSB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Common Mode</td>
<td>±1</td>
<td>±1</td>
<td>LSB</td>
<td></td>
</tr>
</tbody>
</table>

## Reference Input

The *denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25°C$. (Notes 4, 9)

<table>
<thead>
<tr>
<th>SYMBOL</th>
<th>PARAMETER</th>
<th>CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{REF}$</td>
<td>Reference Voltage</td>
<td>(Note 5)</td>
<td>2.5</td>
<td>5.1</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>$I_{REF}$</td>
<td>Reference Input Current</td>
<td>(Note 11)</td>
<td>0.7</td>
<td>1</td>
<td></td>
<td>mA</td>
</tr>
</tbody>
</table>

## Digital Inputs and Digital Outputs

The *denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25°C$. (Note 4)

<table>
<thead>
<tr>
<th>SYMBOL</th>
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<th>CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{IH}$</td>
<td>High Level Input Voltage</td>
<td></td>
<td>0.8•$V_{DD}$</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$V_{IL}$</td>
<td>Low Level Input Voltage</td>
<td></td>
<td>0.2•$V_{DD}$</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$I_{IN}$</td>
<td>Digital Input Current</td>
<td>$V_{IN} = 0V$ to $V_{DD}$</td>
<td>–10</td>
<td>10</td>
<td>µA</td>
<td></td>
</tr>
<tr>
<td>$C_{IN}$</td>
<td>Digital Input Capacitance</td>
<td></td>
<td>5</td>
<td>pF</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$V_{OH}$</td>
<td>High Level Output Voltage</td>
<td>$I_O = –500µA$</td>
<td>OVDD–0.2</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$V_{OL}$</td>
<td>Low Level Output Voltage</td>
<td>$I_O = 500µA$</td>
<td>0.2</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$I_{OZ}$</td>
<td>Hi-Z Output Leakage Current</td>
<td>$V_{OUT} = 0V$ to $V_{DD}$</td>
<td>–10</td>
<td>10</td>
<td>µA</td>
<td></td>
</tr>
<tr>
<td>$I_{SOURCE}$</td>
<td>Output Source Current</td>
<td>$V_{OUT} = 0V$</td>
<td>–10</td>
<td>mA</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$I_{SINK}$</td>
<td>Output Sink Current</td>
<td>$V_{OUT} = V_{DD}$</td>
<td>10</td>
<td>mA</td>
<td></td>
<td></td>
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# Power Requirements

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25°C$. (Note 4)

<table>
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<th>MAX</th>
<th>UNITS</th>
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</thead>
<tbody>
<tr>
<td>$V_{DD}$</td>
<td>Supply Voltage</td>
<td>●</td>
<td>2.375</td>
<td>2.5</td>
<td>2.625</td>
<td>V</td>
</tr>
<tr>
<td>$OV_{DD}$</td>
<td>Supply Voltage</td>
<td>●</td>
<td>1.71</td>
<td>5.25</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>$I_{VDD}$</td>
<td>Supply Current</td>
<td>1Msps Sample Rate (C_L = 20pF)</td>
<td></td>
<td>9.5</td>
<td>13</td>
<td>mA</td>
</tr>
<tr>
<td>$I_{OVDD}$</td>
<td>Supply Current</td>
<td>Conversion Done ($I_{VDD} + I_{OVDD} + I_{REF}$)</td>
<td></td>
<td>1</td>
<td>350</td>
<td>µA</td>
</tr>
<tr>
<td>$P_D$</td>
<td>Power Dissipation</td>
<td>1Msps Sample Rate ($I_{VDD}$)</td>
<td></td>
<td>24</td>
<td>32.5</td>
<td>mW</td>
</tr>
<tr>
<td></td>
<td>Power Down Mode</td>
<td>Conversion Done ($I_{VDD} + I_{OVDD} + I_{REF}$)</td>
<td></td>
<td>15</td>
<td>875</td>
<td>µW</td>
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# ADC Timing Characteristics

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25°C$. (Note 4)

<table>
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<tr>
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<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>$f_{SMPL}$</td>
<td>Maximum Sampling Frequency</td>
<td>●</td>
<td>1</td>
<td>1</td>
<td>Msps</td>
<td></td>
</tr>
<tr>
<td>$f_{DRA}$</td>
<td>Output Data Rate at SDOA</td>
<td>●</td>
<td>3.9</td>
<td>3.9</td>
<td>ksp</td>
<td></td>
</tr>
<tr>
<td>$f_{DRB}$</td>
<td>Output Data Rate at SDOB</td>
<td>●</td>
<td>1</td>
<td>1</td>
<td>Msps</td>
<td></td>
</tr>
<tr>
<td>$t_{CONV}$</td>
<td>Conversion Time</td>
<td>●</td>
<td>578</td>
<td>652</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{ACQ}$</td>
<td>Acquisition Time</td>
<td>$t_{ACQ} = t_{CYC} - t_{CONV} - t_{BUSYLH}$ (Note 8)</td>
<td>●</td>
<td>335</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{CYC}$</td>
<td>Time Between Conversions</td>
<td>●</td>
<td>1000</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{MCLKH}$</td>
<td>MCLK High Time</td>
<td>●</td>
<td>20</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{MCLKL}$</td>
<td>Minimum Low Time for MCLK</td>
<td>●</td>
<td>20</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{BUSYLH}$</td>
<td>MCLK$^\uparrow$ to BUSY$^\uparrow$ Delay</td>
<td>$C_L = 20pF$</td>
<td>●</td>
<td>13</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{DRLLH}$</td>
<td>MCLK to DRL$^\uparrow$ Delay</td>
<td>$C_L = 20pF$</td>
<td>●</td>
<td>18</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{QUIET}$</td>
<td>SCKA, SCKB Quiet Time from MCLK$^\uparrow$</td>
<td>(Note 8)</td>
<td>●</td>
<td>10</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{SCKA}$</td>
<td>SCKA Period</td>
<td>(Notes 12, 13)</td>
<td>●</td>
<td>10</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{SCKAH}$</td>
<td>SCKA High Time</td>
<td>●</td>
<td>4</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{SCKAL}$</td>
<td>SCKA Low Time</td>
<td>●</td>
<td>4</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{SDOA}$</td>
<td>SDOA Data Valid Delay from SCKA$^\uparrow$</td>
<td>$C_L = 20pF, OV_{DD} = 5.25V$</td>
<td>●</td>
<td>8.5</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{SDOADRLL}$</td>
<td>SDOA Data Valid Delay from DRL$\downarrow$</td>
<td>$C_L = 20pF$</td>
<td>●</td>
<td>8.5</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{ENAA}$</td>
<td>Bus Enable Time After RDLA$\downarrow$</td>
<td>(Note 12)</td>
<td>●</td>
<td>16</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{DISA}$</td>
<td>Bus Relinquish Time After RDLA$\uparrow$</td>
<td>(Note 12)</td>
<td>●</td>
<td>13</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{SCKB}$</td>
<td>SCKB Period</td>
<td>(Notes 12, 13)</td>
<td>●</td>
<td>10</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{SCKBH}$</td>
<td>SCKB High Time</td>
<td>●</td>
<td>4</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{SCKBL}$</td>
<td>SCKB Low Time</td>
<td>●</td>
<td>4</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{SDOB}$</td>
<td>SDOB Data Valid Delay from SCKB$^\uparrow$</td>
<td>$C_L = 20pF, OV_{DD} = 5.25V$</td>
<td>●</td>
<td>8.5</td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>$t_{HSDOB}$</td>
<td>SDOB Data Remains Valid Delay from SCKB$^\uparrow$</td>
<td>$C_L = 20pF, OV_{DD} = 5.25V$</td>
<td>●</td>
<td>1</td>
<td>ns</td>
<td></td>
</tr>
</tbody>
</table>
ADC TIMING CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25\,^\circ C$. (Note 4)

<table>
<thead>
<tr>
<th>SYMBOL</th>
<th>PARAMETER</th>
<th>CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>$t_{DSOBBUSY}$</td>
<td>SDOB Data Valid Delay from BUSY↓</td>
<td>$C_L = 20\text{pF}$ (Note 8)</td>
<td>●</td>
<td>5 ns</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$t_{ENB}$</td>
<td>Bus Enable Time After RDLB↓</td>
<td>(Note 12)</td>
<td>●</td>
<td>16 ns</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$t_{DISB}$</td>
<td>Bus Relinquish Time After RDLB↑</td>
<td>(Note 12)</td>
<td>●</td>
<td>13 ns</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Note 1:** Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

**Note 2:** All voltage values are with respect to ground.

**Note 3:** When these pin voltages are taken below ground or above REF or $OV_{DD}$, they will be clamped by internal diodes. This product can handle input currents up to 100mA below ground or above REF or $OV_{DD}$ without latch-up.

**Note 4:** $V_{DD} = 2.5V$, $OV_{DD} = 2.5V$, $REF = 5V$, $V_{CM} = 2.5V$, $f_{SMPL} = 1\text{MHz}$, $DF = 256$.

**Note 5:** Recommended operating conditions.

**Note 6:** Transition noise is defined as the noise level of the ADC with $IN^+$ and $IN^-$ shorted.

**Note 7:** Integral nonlinearity is defined as the deviation of a code from a straight line passing through the actual endpoints of the transfer curve. The deviation is measured from the center of the quantization band.

**Note 8:** Guaranteed by design, not subject to test.

**Note 9:** Bipolar zero-scale error is the offset voltage measured from $0.5\text{LSB}$ when the output code flickers between $0000\,0000\,0000\,0000\,0000\,0000\,0000$ and $1111\,1111\,1111\,1111\,1111\,1111\,1111\,1111$. Full-scale bipolar error is the worst-case of $-\text{FS}$ or $+\text{FS}$ untrimmed deviation from ideal first and last code transitions and includes the effect of offset error.

**Note 10:** All specifications in dB are referred to a full-scale ±5V input with a 5V reference voltage.

**Note 11:** $f_{SMPL} = 1\text{MHz}$, $I_{REF}$ varies proportionally with sample rate.

**Note 12:** Parameter tested and guaranteed at $OV_{DD} = 1.71V$, $OV_{DD} = 2.5V$ and $OV_{DD} = 5.25V$.

**Note 13:** $t_{SCKA}$, $t_{SCKB}$ of 10ns maximum allows a shift clock frequency up to 100MHz for rising edge capture.

![Figure 1. Voltage Levels for Specifications](image)
TYPICAL PERFORMANCE CHARACTERISTICS

REF = 5V, f<sub>SMPL</sub> = 1Msps, DF = 256, Filtered Output, unless otherwise noted.

Integral Nonlinearity vs Input Voltage

DC Histogram, DF = 256

INL ERROR (ppm)

DC Histogram, DF = 1024

INL ERROR (ppm)

DC Histogram, DF = 4096

INL ERROR (ppm)

DC Histogram, DF = 16384

INL ERROR (ppm)

128k Point FFT f<sub>SMPL</sub> = 1Msps, f<sub>IN</sub> = 200Hz, DF = 256

128k Point FFT f<sub>SMPL</sub> = 1Msps, f<sub>IN</sub> = 50Hz, DF = 1024

32k Point FFT f<sub>SMPL</sub> = 1Msps, f<sub>IN</sub> = 10Hz, DF = 4096

AMPLITUDE (dBFS)

FREQUENCY (Hz)

FREQUENCY (Hz)

FREQUENCY (Hz)

For more information www.linear.com/LTC2508-32
TYPICAL PERFORMANCE CHARACTERISTICS  \( T_A = 25^\circ\text{C}, V_{\text{DD}} = 2.5\text{V}, V_{\text{DD}} = 2.5\text{V}, V_{\text{CM}} = 2.5\text{V}, \)

REF = 5V, \( f_{\text{SMPL}} = 1\text{MSPs}, \) DF = 256, Filtered Output, unless otherwise noted.

8k Point FFT \( f_{\text{SMPL}} = 1\text{Msps}, \) \( f_{\text{IN}} = 10\text{Hz}, \) DF = 16384

Dynamic Range, Transition Noise vs DF

Frequency Response, DF = 256, 1024, 4096, 16384

SNR, SINAD vs Input level, \( f_{\text{IN}} = 200\text{Hz} \)

Dynamic Range vs Reference Voltage, \( f_{\text{IN}} = 200\text{Hz}, A_{\text{IN}} = -20\text{dBFS} \)

THD, Harmonics vs Reference Voltage, \( f_{\text{IN}} = 200\text{Hz}, A_{\text{IN}} = -1\text{dBFS} \)

Dynamic Range vs Temperature, \( f_{\text{IN}} = 100\text{Hz}, A_{\text{IN}} = -20\text{dBFS} \)

Shutdown Current vs Temperature

THD, Harmonics vs Temperature, \( f_{\text{IN}} = 200\text{Hz}, A_{\text{IN}} = -1\text{dBFS} \)

For more information www.linear.com/LTC2508-32
TYPICAL PERFORMANCE CHARACTERISTICS

$T_A = 25^\circ C$, $V_{DD} = 2.5V$, $OV_{DD} = 2.5V$, $V_{CM} = 2.5V$, 

REF = 5V, $f_{SMPL} = 1$Mps, DF = 256, Filtered Output, unless otherwise noted.
TYPICAL PERFORMANCE CHARACTERISTICS

REF = 5V, f_SMPL = 1Msp, DF = 256, No Latency Output, unless otherwise noted.

T_A = 25°C, V_DD = 2.5V, OV_DD = 2.5V, V_CM = 2.5V,

INL vs Input Voltage

DNL vs Input Voltage

128k Point FFT

No Latency Differential Output

SNR = 86dB

FREQUENCY (kHz)

0
125
250
375
500

AMPLITUDE (dBFS)

–160
–140
–120
–100
–80
–60
–40
–20
0
20
40
60
80
100
120
140
160

INL ERROR (LSB)

–0.5
–0.4
–0.3
–0.2
–0.1
0
1
2
3
4
5

INPUT VOLAGE (V)

No Latency Common Mode Output

SNR = 48dB

FREQUENCY (kHz)

0
125
250
375
500

AMPLITUDE (dBFS)

–120
–100
–80
–60
–40
–20
0
20
40
60
80
100
120
140
160

PIN FUNCTIONS

**RDLA (Pin 1):** Read Low Input A (Filtered Output). When RDLA is low, the serial data output A (SDOA) pin is enabled. When RDLA is high, SDOA pin is in a high-impedance state. Logic levels are determined by $OV_{DD}$.

**RDLB (Pin 2):** Read Low Input B (No Latency Output). When RDLB is low, the serial data output B (SDOB) pin is enabled. When RDLB is high, SDOB pin is in a high-impedance state. Logic levels are determined by $OV_{DD}$.

**$V_{DD}$ (Pin 3):** 2.5V Power Supply. The range of $V_{DD}$ is 2.375V to 2.625V. Bypass $V_{DD}$ to GND with a 10µF ceramic capacitor.

**GND (Pins 4, 7, 16, 23, 24):** Ground.

**IN+ (Pin 5):** Positive Analog Input.

**IN- (Pin 6):** Negative Analog Input.

**REF (Pins 8, 9, 10):** Reference Input. The range of REF is 2.5V to 5.1V. This pin is referred to the GND pin and should be decoupled closely to the pin with a 47µF ceramic capacitor (X7R, 1210 size, 10V rating).

**SEL0, SEL1 (Pins 11, 12):** Down-Sampling Factor Select Input 0, Down-Sampling Factor Select Input 1. Selects the down-sampling factor for the digital filter. Down-sampling factors of 256, 1024, 4096 and 16384 are selected for [SEL0 SEL1] combinations of 00, 01, 10 and 11 respectively. Logic levels are determined by $OV_{DD}$.

**MCLK (Pin 13):** Master Clock Input. A rising edge on this input powers up the part and initiates a new conversion. Logic levels are determined by $OV_{DD}$.

**SYNC (Pin 14):** Synchronization Input. A pulse on this input is used to synchronize the phase of the digital filter. Logic levels are determined by $OV_{DD}$.

**DRL (Pin 15):** Data Ready Low Output. A falling edge on this pin indicates that a new filtered output code is available in the output register of SDOA. Logic levels are determined by $OV_{DD}$.

**SDOA (Pin 17):** Serial Data Output A (Filtered Output). The filtered output code appears on this pin (MSB first) on each rising edge of SCKA. The output data is in 2’s complement format. Logic levels are determined by $OV_{DD}$.

**SDOB (Pin 20):** Serial Data Output B (No Latency Output). The 22-bit no latency composite output code appears on this pin (MSB first) on each rising edge of SCKB. The output data is in 2’s complement format. Logic levels are determined by $OV_{DD}$.

**BUSY (Pin 21):** BUSY Indicator. Goes high at the start of a new conversion and returns low when the conversion has finished. Logic levels are determined by $OV_{DD}$.

**OV_{DD} (Pin 22):** I/O Interface Digital Power. The range of $OV_{DD}$ is 1.71V to 5.25V. This supply is nominally set to the same supply as the host interface (1.8V, 2.5V, 3.3V, or 5V). Bypass $OV_{DD}$ to GND (Pin 23) close to the pin with a 0.1µF capacitor.

**GND (Exposed Pad Pin 25):** Ground. Exposed pad must be soldered directly to the ground plane.
FUNCTIONAL BLOCK DIAGRAM

IN+

REF = 5V

32-BIT SAR ADC

IN–

VDD = 2.5V

GND

LTC2508-32

32

DIGITAL FILTER

SPI PORT

POWER DOWN AND ACQUIRE

CONVERT

RDLA = RDLB = 0

MCLK

DRL

SCKA

SDOA

DA31 DA29 DA27 DA25 DA23 DA21 DA19 DA17 DA15 DA13 DA11 DA9 DA7 DA5 DA3 DA1

DA31 DA29 DA27 DA25 DA23 DA21 DA19 DA17 DA15 DA13 DA11 DA9 DA7 DA5 DA3 DA1

WA7 WA5 WA3 WA1

WA7 WA5 WA3 WA1

DB13 DB11 DB9 DB7 DB5 DB3 DB1

DB12 DB10 DB8 DB6 DB4 DB2 DB0

CB7 CB5 CB3 CB1 CB0

Conversion Timing Using the Serial Interface

TIMING DIAGRAM

For more information www.linear.com/LTC2508-32
APPLICATIONS INFORMATION

OVERVIEW

The LTC2508-32 is a low noise, low power, high-performance 32-bit ADC with an integrated configurable digital filter. Operating from a single 2.5V supply, the LTC2508-32 features a fully differential input range up to ±V_REF, with V_REF ranging from 2.5V to 5.1V. The LTC2508-32 supports a wide common mode range from 0V to V_REF, simplifying analog signal conditioning requirements.

The LTC2508-32 simultaneously provides two output codes: (1) a 32-bit digitally filtered high precision low noise code, and (2) a 22-bit no latency composite code. The configurable digital filter reduces measurement noise by lowpass filtering and down-sampling the stream of data from the SAR ADC core, giving the 32-bit filtered output code. The 22-bit composite code consists of a 14-bit code representing the differential voltage and an 8-bit code representing the common mode voltage. The 22-bit composite code is available each conversion cycle, with no cycle of latency.

The digital filter can be easily configured for 4 different down-sampling factors by pin strapping. The configurations provide a dynamic range of 131dB at 3.9ksps and 145dB at 61sps. The digital lowpass filter relaxes the requirements for analog anti-aliasing. Multiple LTC2508-32 devices can be easily synchronized using the SYNC pin.

CONVERTER OPERATION

The LTC2508-32 operates in two phases. During the acquisition phase, a 32-bit charge redistribution capacitor D/A converter (CDAC) is connected to the IN+ and IN- pins to sample the analog input voltages. A rising edge on the MCLK pin initiates a conversion. During the conversion phase, the 32-bit CDAC is sequenced through a successive approximation algorithm, effectively comparing the sampled inputs with binary-weighted fractions of the reference voltage (e.g. V_REF/2, V_REF/4 ... V_REF/4294967296). At the end of conversion, the CDAC output approximates the sampled analog input. The ADC control logic then passes the 32-bit digital output code to the digital filter for further processing. A 14-bit code representing the differential voltage and an 8-bit code representing the common mode voltage are combined to form a 22-bit composite code. The 22-bit composite code is available each conversion cycle, without any cycle of latency.

TRANSFER FUNCTION

The LTC2508-32 digitizes the full-scale differential voltage of 2 × V_REF into 2^32 levels, resulting in an LSB size of 2.3nV with a 5V reference. The ideal transfer function is shown in Figure 2. The output data is in 2’s complement format.

ANALOG INPUT

The LTC2508-32 samples the voltage difference (IN+ - IN-), between its analog input pins over a wide common mode input range while attenuating unwanted signals common to both input pins by the common-mode rejection ratio (CMRR) of the ADC. Wide common mode input range coupled with high CMRR allows the IN+/IN- analog inputs to swing with an arbitrary relationship to each other, provided each pin remains between GND and V_REF. This unique feature of the LTC2508-32 enables it to accept a wide variety of signal swings, including traditional classes of analog input signals such as pseudo-differential unipolar, pseudo-differential true bipolar, and fully differential, thereby simplifying signal chain design.

In the acquisition phase, each input sees approximately 45pF (C_IN) from the sampling circuit in series with 40Ω (R_ON) from the on-resistance of the sampling switch.
APPLICATIONS INFORMATION

The inputs draw a current spike while charging the $C_{IN}$ capacitors during acquisition. During conversion, the analog inputs draw only a small leakage current.

INPUT DRIVE CIRCUITS

A low impedance source can directly drive the high impedance inputs of the LTC2508-32 without gain error. A high impedance source should be buffered to minimize settling time during acquisition and to optimize ADC linearity. For best performance, a buffer amplifier should be used to drive the analog inputs of the LTC2508-32. The amplifier provides low output impedance, which produces fast settling of the analog signal during the acquisition phase. It also provides isolation between the signal source and the ADC inputs.

Noise and Distortion

The noise and distortion of an input buffer amplifier and other supporting circuitry must be considered since they add to the ADC noise and distortion. Noisy input signals should be filtered prior to the buffer amplifier with a low bandwidth filter to minimize noise. The simple one-pole RC lowpass filter (LPF1) shown in Figure 4 is sufficient for many applications.

A coupling filter network (LPF2) should be used between the buffer and ADC input to minimize disturbances reflected into the buffer from sampling transients. Long RC time constants at the analog inputs will slow down the settling of the analog inputs. Therefore, LPF2 typically requires wider bandwidth than LPF1. This filter also helps minimize the noise contribution from the buffer. A buffer amplifier with a low noise density must be selected to minimize degradation of SNR.

High quality capacitors and resistors should be used in the RC filters since these components can add distortion. NPO and silver mica type dielectric capacitors have excellent linearity. Carbon surface mount resistors can generate distortion from self-heating and from damage that may occur during soldering. Metal film surface mount resistors are much less susceptible to both problems.

Input Currents

An important consideration when coupling an amplifier to the LTC2508-32 is in dealing with current spikes drawn by the ADC inputs at the start of each acquisition phase. The ADC inputs may be modeled as a switched capacitor load of the drive circuit. A drive circuit may rely partially on attenuating switched-capacitor current spikes with small filter capacitors $C_{FILT}$ placed directly at the ADC inputs, and partially on the driver amplifier having sufficient bandwidth to recover from the residual disturbance. Amplifiers optimized for DC performance may not have sufficient bandwidth to fully recover at the ADC’s maximum conversion rate, which can produce nonlinearity and other errors. Coupling filter circuits may be classified in three broad categories:
APPLICATIONS INFORMATION

**Fully Settled**—This case is characterized by filter time constants and an overall settling time that is considerably shorter than the sample period. When acquisition begins, the coupling filter is disturbed. For a typical first order RC filter, the disturbance will look like an initial step with an exponential decay. The amplifier will have its own response to the disturbance, which may include ringing. If the input settles completely (to within the accuracy of the LTC2508-32), the disturbance will not contribute any error.

**Partially Settled**—In this case, the beginning of acquisition causes a disturbance of the coupling filter, which then begins to settle out towards the nominal input voltage. However, acquisition ends (and the conversion begins) before the input settles to its final value. This generally produces a gain error, but as long as the settling is linear, no distortion is produced. The coupling filter’s response is affected by the amplifier’s output impedance and other parameters. A linear settling response to fast switched-capacitor current spikes can NOT always be assumed for precision, low bandwidth amplifiers. The coupling filter serves to attenuate the current spikes’ high-frequency energy before it reaches the amplifier.

**Fully Averaged**—If the coupling filter capacitors ($C_{\text{FILT}}$) at the ADC inputs are much larger than the ADC’s sample capacitors (45pF), then the sampling glitch is greatly attenuated. The driving amplifier effectively only sees the average sampling current, which is quite small. At 1Msps, the equivalent input resistance is approximately 22kΩ (as shown in Figure 5), a benign resistive load for most precision amplifiers. However, resistive voltage division will occur between the coupling filter’s DC resistance and the ADC’s equivalent (switched-capacitor) input resistance, thus producing a gain error.

The input leakage currents of the LTC2508-32 should also be considered when designing the input drive circuit, because source impedances will convert input leakage currents to an added input voltage error. The input leakage currents, both common mode and differential, are typically extremely small over the entire operating temperature range. Figure 6 shows the input leakage currents over temperature for a typical part.

Let $R_S1$ and $R_S2$ be the source impedances of the differential input drive circuit shown in Figure 7, and let $I_{L1}$ and $I_{L2}$ be the leakage currents flowing out of the ADC’s analog inputs. The differential voltage error, $V_E$, due to the leakage currents can be expressed as:

$$V_E = \frac{R_{S1}+R_{S2}}{2} \cdot (I_{L1}-I_{L2}) + (R_{S1}-R_{S2}) \cdot \frac{I_{L1}+I_{L2}}{2}$$

The common mode input leakage current, $(I_{L1} + I_{L2})/2$, is typically extremely small (Figure 6) over the entire operating temperature range and common mode input voltage range. Thus, any reasonable mismatch (below 5%) of the source impedances $R_{S1}$ and $R_{S2}$ will cause only a negligible error. The differential leakage current is also typically very small, and its nonlinear component is even smaller. Only the nonlinear component will impact the ADC’s linearity.
APPLICATIONS INFORMATION

For optimal performance, it is recommended that the source impedances, $R_{S1}$ and $R_{S2}$, be between 5Ω and 50Ω and with 1% tolerance. For source impedances in this range, the voltage and temperature coefficients of $R_{S1}$ and $R_{S2}$ are usually not critical. The guaranteed AC and DC specifications are tested with 5Ω source impedances, and the specifications will gradually degrade with increased source impedances due to incomplete settling.

DC Accuracy

The LTC2508-32 has excellent INL specifications. This makes the LTC2508-32 ideal for applications which require high DC accuracy, including parameters such as offset and offset drift. To maintain high accuracy over the entire DC signal chain, amplifiers have to be selected very carefully. A large-signal open-loop gain of at least 126dB may be required to ensure 1ppm linearity for amplifiers configured as unity gain buffers. For example, 1ppm linearity may require that the offset is known to vary less than 5μV for a 5V swing. However, greater offset variations may be acceptable if the relationship is known to be (mostly) linear. Unity-gain buffer amplifiers typically require substantial headroom to the power supply rails for best performance. Inverting amplifier circuits configured to minimize swing at the amplifier input terminals may perform better with less headroom than unity-gain buffer amplifiers. The linearity and thermal properties of an inverting amplifier’s feedback network should be considered carefully to ensure DC accuracy.

Buffering Input Signals

The wide common mode input range and high CMRR of the LTC2508-32 allow analog inputs $IN^+$ and $IN^-$ pins to swing with an arbitrary relationship to each other, provided that each pin remains between $V_{REF}$ and GND. This unique feature of the LTC2508-32 enables it to accept a wide variety of signal swings, simplifying signal chain design.

Buffering DC Accurate Input Signals

Figure 8 shows a typical application where two analog input voltages are buffered using the LTC2057. The LTC2057 is a high precision zero drift amplifier which complements the low offset and offset drift of the LTC2508-32. The LTC2057 is shown in a non-inverting amplifier configura-
APPLICATIONS INFORMATION

The LTC2508-32 has a guaranteed maximum offset error of 130µV (typical drift ±0.014ppm/°C), and a guaranteed maximum full-scale error of 150ppm (typical drift ±0.05ppm/°C). Low drift is important to maintain accuracy over a wide temperature range in a calibrated system.

Buffering DC Accurate Single-Ended Input Signals

While the circuit shown in Figure 8 is capable of buffering single-ended input signals, the circuit shown in Figure 9 is preferable when the single-ended signal reference level is inherently low impedance and doesn’t require buffering. This circuit eliminates one driver and one lowpass filter, reducing part count, power dissipation, and SNR degradation due to driver noise.

The LTC2057 has excellent DC characteristics, but limited output current drive, leading to a degradation in THD as the input frequency increases. Limit the input frequency to 10Hz to maintain full data sheet specified THD.

Buffering AC Input Signals

Many driver circuits presented in this data sheet emphasize performance for low bandwidth input signals, and the amplifiers are chosen accordingly. While the LTC2057 is characterized by excellent DC specifications, its output current drive is limited. This limits the range of input frequencies that the LTC2057 can drive to the full data sheet specifications of the LTC2508-32. The –3dB bandwidth of the filtered output of the LTC2508-32, while operating with a DF of 256, is equal to 480Hz. Therefore, an alternative driver solution is required while driving input signals with bandwidth greater than 10Hz.

The LTC6363 is a low power, low noise, fully differential op amp, and can be used to drive input signals with bandwidth greater than 10Hz. The LTC6363 may be configured to convert a single-ended input signal to a differential output signal or may be driven differentially.

Figure 10a shows the LTC6363 being used to buffer a 10V differential input signal. In this case, the amplifier is configured as a unity gain buffer using the LT5400-4 precision resistors. As shown in the FFT of Figure 10b, the LTC6363 drives the LTC2508-32 to near full data sheet performance.
ADC REFERENCE

An external reference defines the input range of the LTC2508-32. A low noise, low temperature drift reference is critical to achieving the full data sheet performance of the ADC. Linear Technology offers a portfolio of high performance references designed to meet the needs of many applications. With its small size, low power and high accuracy, the LTC6655-5 is particularly well suited for use with the LTC2508-32. The LTC6655-5 offers 0.025\% (max) initial accuracy and 2ppm/°C (max) temperature coefficient for high precision applications.

When choosing a bypass capacitor for the LTC6655-5, the capacitor’s voltage rating, temperature rating, and package size should be carefully considered. Physically larger capacitors with higher voltage and temperature ratings tend to provide a larger effective capacitance, better filtering the noise of the LTC6655-5, and consequently facilitating a higher SNR. Therefore, we recommend bypassing the LTC6655-5 with a 47μF ceramic capacitor (X7R, 1210 size, 10V rating) close to the REF pin.

The REF pin of the LTC2508-32 draws charge \( Q_{\text{CONV}} \) from the 47μF bypass capacitor during each conversion cycle. The reference replenishes this charge with an average current, \( I_{\text{REF}} = \frac{Q_{\text{CONV}}}{t_{\text{CYC}}} \). The current drawn from the REF pin, \( I_{\text{REF}} \), depends on the sampling rate and output code. If the LTC2508-32 continuously samples a signal at a constant rate, the LTC6655-5 will keep the deviation of the reference voltage over the entire code span to less than 0.5ppm.

When idling, the REF pin on the LTC2508-32 draws only a small leakage current (< 1μA). In applications where a burst of samples is taken after idling for long periods as shown in Figure 11, \( I_{\text{REF}} \) quickly goes from approximately 0μA to a maximum of 1mA at 1Msps. This step in average current drawn causes a transient response in the reference that must be considered, since any deviation in the reference output voltage will affect the accuracy of the output code. In applications where the transient response of the reference is important, the fast settling LTC6655-5 reference is also recommended.

Reference Noise

The dynamic range of the ADC will increase approximately 6dB for every \( 4 \times \) increase in the down-sampling factor (DF). The SNR should also improve as a function of DF in the same manner. For large input signals near full-scale, however, any reference noise will limit the improvement of the SNR as DF increases, because any noise on the REF pin will modulate around the fundamental frequency of the input signal. Therefore, it is critical to use a low-noise reference, especially if the input signal amplitude approaches full-scale. For small input signals, the dynamic range will improve as described earlier in this section.

DYNAMIC PERFORMANCE

Fast Fourier Transform (FFT) techniques are used to test the ADC’s frequency response, distortion and noise at the rated throughput. By applying a low distortion sine wave and analyzing the digital output using an FFT algorithm,
APPLICATIONS INFORMATION

The ADC’s spectral content can be examined for frequencies outside the fundamental. The LTC2508-32 provides guaranteed tested limits for both AC distortion and noise measurements.

Dynamic Range

The dynamic range is the ratio of the RMS value of a full scale input to the total RMS noise measured with the inputs shorted to VREF/2. The dynamic range of the LTC2508-32 with DF = 256 is 131dB which improves with increase in the down-sampling factor.

Signal-to-Noise and Distortion Ratio (SINAD)

The signal-to-noise and distortion ratio (SINAD) is the ratio between the RMS amplitude of the fundamental input frequency and the RMS amplitude of all other frequency components at the ADC output. The output is band-limited to frequencies from above DC and below half the sampling frequency. Figure 12 shows that the LTC2508-32 achieves a typical SINAD of 120dB at a 1MHz sampling rate with a 200Hz input, and DF = 256.

Total Harmonic Distortion (THD)

Total Harmonic Distortion (THD) is the ratio of the RMS sum of all harmonics of the input signal to the fundamental itself. The out-of-band harmonics alias into the frequency band between DC and half the sampling frequency (fSMPL/2). THD is expressed as:

\[ THD = 20 \log \frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + \ldots + V_N^2}}{V_1} \]

where V1 is the RMS amplitude of the fundamental frequency and V2 through VN are the amplitudes of the second through Nth harmonics.

POWER CONSIDERATIONS

The LTC2508-32 has two power supply pins: the 2.5V power supply (VDD), and the digital input/output interface power supply (OVDD). The flexible OVDD supply allows the LTC2508-32 to communicate with any digital logic operating between 1.8V and 5V, including 2.5V and 3.3V systems.

Power Supply Sequencing

The LTC2508-32 does not have any specific power supply sequencing requirements. Care should be taken to adhere to the maximum voltage relationships described in the Absolute Maximum Ratings section. The LTC2508-32 has a power-on-reset (POR) circuit that will reset the LTC2508-32 at initial power-up or whenever the power supply voltage drops below 1V. Once the supply voltage re-enters the nominal supply voltage range, the POR will reinitialize the ADC. No conversions should be initiated until 200μs after a POR event to ensure the reinitialization period has ended. Any conversions initiated before this time will produce invalid results.

TIMING AND CONTROL

MCLK Timing

A rising edge on MCLK will power up the LTC2508-32 and start a conversion. Once a conversion has been started, further transitions on MCLK are ignored until the conversion is complete. For best results, the falling edge
of MCLK should occur within 40ns from the start of the conversion, or after the conversion has been completed. For optimum performance, MCLK should be driven by a clean low jitter signal. Converter status is indicated by the BUSY output which remains high while the conversion is in progress. Once the conversion has completed, the LTC2508-32 powers down and begins acquiring the input signal for the next conversion.

**Internal Conversion Clock**

The LTC2508-32 has internal timing circuitry that is trimmed to achieve a maximum conversion time of 652ns. With a maximum sample rate of 1Msps, a minimum acquisition time of 335ns is guaranteed without any external adjustments.

**Auto Power Down**

The LTC2508-32 automatically powers down after a conversion has been completed and powers up once a new conversion is initiated on the rising edge of MCLK. During power-down, data from the last conversion can be clocked out. To minimize power dissipation during power-down, disable SDOA, SDOB and turn off SCKA, SCKB. The auto power-down feature will reduce the power dissipation of the LTC2508-32 as the sampling rate is reduced. Since power is consumed only during a conversion, the LTC2508-32 remains powered down for a larger fraction of the conversion cycle (tCYC) at lower sample rates, thereby reducing the average power dissipation which scales with the sampling rate as shown in Figure 13.

**DECIMATION FILTERS**

Many ADC applications use digital filtering techniques to reduce noise. An FPGA or DSP is typically needed to implement a digital filter. The LTC2508-32 features an integrated decimation filter that provides 4 selectable digital filtering functions without any external hardware, thus simplifying the application solution. Figure 14 shows the LTC2508-32 digitally filtered output signal path, wherein the output DADC(n) of the 32-bit SAR ADC core is passed on to the integrated decimation filter.

### Digital Filtering

The input to the LTC2508-32 is sampled at a rate f_SMPL and digital words DADC(n) are transmitted to the digital filter at that rate. Noise from the 32-bit SAR ADC core is distributed uniformly in frequency from DC to f_SMPL/2. Figure 15 shows the frequency spectrum of DADC(n) at the output of the SAR ADC core. In this example, the bandwidth of interest f_B is a small fraction of f_SMPL/2.

![Figure 13. Power Supply Current of the LTC2508-32 vs Sampling Rate](image1.png)

![Figure 14. LTC2508-32 Digitally Filtered Output Signal Path](image2.png)

![Figure 15. Frequency Spectrum of SAR ADC Core Output](image3.png)
APPLICATIONS INFORMATION

The digital filter integrated in the LTC2508-32 suppresses out-of-band noise power, thereby lowering overall noise and increasing the dynamic range (DR). The lower the filter bandwidth, the lower the noise, and the higher the DR. Figure 16 shows the corresponding frequency spectrum of D1(n) at the output of the digital filter, where noise beyond the cutoff frequency is suppressed by the digital filter.

**Down-Sampling**

The output data rate of the digital filter is reduced by a down-sampler without causing spectral interference in the bandwidth of interest.

The down-sampler reduces the data rate by passing every \( DF^{th} \) sample to the output, while discarding all other samples. The sampling frequency \( f_0 \) at the output of the down sampler is the ratio of \( f_{SMPL} \) and \( DF \), i.e., \( f_0 = \frac{f_{SMPL}}{DF} \).

The LTC2508-32 enables the user to select \( DF \) according to a desired bandwidth of interest. The 4 available configurations can be selected by pin strapping pins SEL0 and SEL1. Table 1 summarizes the different decimation filter configurations and properties. When operating at 1.024Msps, the acquisition time \( (t_{ACQ}) \) of the LTC2508-32 is reduced to 308.5ns and the output data rate correspondingly increases. Note that the dynamic range is unchanged as it is only affected by \( DF \) and not by sampling rate.

### Table 1. Properties of Filters in LTC2508-32

<table>
<thead>
<tr>
<th>SEL1:SEL0</th>
<th>DOWN SAMPLING FACTOR (DF)</th>
<th>( f_{SMPL} = 1\text{Msps} )</th>
<th>( f_{SMPL} = 1.024\text{Msps} )</th>
<th>( f_{SMPL} = 1\text{Msps} )</th>
<th>( f_{SMPL} = 1.024\text{Msps} )</th>
<th>DYNAMIC RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>00</td>
<td>256</td>
<td>480Hz</td>
<td>491.5Hz</td>
<td>3906sps</td>
<td>4000sps</td>
<td>131dB</td>
</tr>
<tr>
<td>01</td>
<td>1024</td>
<td>120Hz</td>
<td>122.8Hz</td>
<td>977sps</td>
<td>1000sps</td>
<td>136dB</td>
</tr>
<tr>
<td>10</td>
<td>4096</td>
<td>30Hz</td>
<td>30.7Hz</td>
<td>244sps</td>
<td>250sps</td>
<td>141dB</td>
</tr>
<tr>
<td>11</td>
<td>16384</td>
<td>7.5Hz</td>
<td>7.7Hz</td>
<td>61sps</td>
<td>62.5sps</td>
<td>145dB</td>
</tr>
</tbody>
</table>

**Aliasing**

The maximum bandwidth that a signal being sampled can have and be accurately represented by its samples is the Nyquist bandwidth. The Nyquist bandwidth ranges from DC to half the sampling frequency (a.k.a. the Nyquist frequency). An input signal whose bandwidth exceeds the Nyquist frequency, when sampled, will experience distortion due to an effect called “Aliasing”.

When aliasing, frequency components greater than the Nyquist frequency undergo a frequency shift and appear within the Nyquist bandwidth. Figure 17 illustrates aliasing in the time domain. The solid line shows a sinusoidal input signal of a frequency greater than the Nyquist frequency \( (f_0/2) \). The circles show the signal sampled at \( f_0 \). Note that the sampled signal is identical to that of sampling another sinusoidal input signal of a lower frequency shown with the dashed line. To avoid aliasing, it is necessary to band-limit an input signal to the Nyquist bandwidth before sampling it. A filter that suppresses spectral components outside the Nyquist bandwidth is called an “Anti-Aliasing Filter” (AAF).

**Anti-Aliasing Filters**

Figure 18 shows a typical signal chain including a lowpass AAF and an ADC sampling at a rate of \( f_0 \). The AAF rejects input signal components exceeding \( f_0/2 \), thus avoiding aliasing. If the bandwidth of interest is close to \( f_0/2 \), then...
the AAF must have a very steep roll-off. The complexity of the analog AAF increases with the steepness of the roll-off, and it may be prohibitive if a very steep filter is required.

Alternatively, a simple low-order analog filter in combination with a digital filter can be used to create a mixed-mode equivalent AAF with a very steep roll-off. A mixed-mode filter implementation is shown in Figure 19 where an analog filter with a gradual roll-off is followed by the LTC2508-32 sampling at a rate of \( f_{\text{SMPL}} = D \times f_0 \). The LTC2508-32 has an integrated digital filter at the output of the ADC core. The equivalent AAF \( H_{E\text{Q}}(f) \), is the product of the frequency responses of the analog filter \( H_1(f) \) and digital filter \( H_2(f) \), as shown in Figure 20. The digital filter provides a steep roll-off, allowing the analog filter to have a relatively gradual roll-off.

The digital filter in the LTC2508-32 operates at the ADC sampling rate \( f_{\text{SMPL}} \) and suppresses signals at frequencies exceeding \( f_0/2 \). The frequency response of the digital filter \( H_2(f) \) repeats at multiples of \( f_{\text{SMPL}} \), resulting in unwanted passbands at each multiple of \( f_{\text{SMPL}} \). The analog filter should be designed to provide adequate suppression of the unwanted passbands, such that \( H_{E\text{Q}}(f) \) has only one passband corresponding to the frequency range of interest. Larger \( D \) settings correspond to less bandwidth of the digital filter, allowing for the analog filter to have a more gradual roll-off. A simple first- or second-order analog filter will provide adequate suppression for most systems.
APPLICATIONS INFORMATION

Figure 21 shows the frequency response of the digital filter when the LTC2508-32 is configured to operate with DF = 256 and sampling at f_{SMPL}.

For each configuration of the LTC2508-32, the digital filter is a lowpass finite impulse response (FIR) filter with linear phase response. The bandwidth is inversely proportional to the selected DF value. Each configuration provides a minimum of 80dB attenuation for frequencies in the range of f_0/2 and f_{SMPL} – f_0/2. The filter coefficients and detailed version of the frequency response of the 4 digital filter configurations are available at www.linear.com/docs/52896. Table 2 lists the length and group delay of each digital filter’s impulse response.

Table 2. Length of Digital Filter

<table>
<thead>
<tr>
<th>DOWN-SAMPLING FACTOR (DF)</th>
<th>LENGTH OF DIGITAL FILTER IMPULSE RESPONSE</th>
<th>GROUP DELAY (f_{SMPL} = 1 Msps)</th>
</tr>
</thead>
<tbody>
<tr>
<td>256</td>
<td>2,304</td>
<td>1.2ms</td>
</tr>
<tr>
<td>1,024</td>
<td>9,216</td>
<td>4.6ms</td>
</tr>
<tr>
<td>4,096</td>
<td>36,864</td>
<td>18.4ms</td>
</tr>
<tr>
<td>16,384</td>
<td>147,456</td>
<td>73.7ms</td>
</tr>
</tbody>
</table>

Settling Time and Group Delay

The length of each digital filter’s impulse response determines its settling time. Linear phase filters exhibit constant delay time versus input frequency (that is, constant group delay). Group delay of the digital filter is defined to be the delay to the center of the impulse response.

LTC2508-32 is optimized for low latency, and it provides fast settling. Figure 22 shows the output settling behavior after a step change on the analog inputs of the LTC2508-32. The X axis is given in units of output sample number. The step response is representative for all values of DF. Full settling is achieved in 10 output samples.

Figure 22 shows the output settling behavior after a step change on the analog inputs of the LTC2508-32. The X axis is given in units of output sample number. The step response is representative for all values of DF. Full settling is achieved in 10 output samples.
DIGITAL INTERFACE

The LTC2508-32 features two digital serial interfaces. Serial interface A is used to read the filtered output data. Serial interface B is used to read the no latency output data. Both interfaces support a flexible OVD supply, allowing the LTC2508-32 to communicate with any digital logic operating between 1.8V and 5V, including 2.5V and 3.3V systems.

Filtered Output Data

Figure 23 shows a typical operation for reading the filtered output data. The I/O register contains filtered output codes \( D_{OUT}(k) \) provided by the decimation filter. \( D_{OUT}(k) \) is updated once in every DF number of conversion cycles. A timing signal \( DRL \) indicates when \( D_{OUT}(k) \) is updated. \( DRL \) goes high at the beginning of every \( DF^{th} \) conversion, and it goes low when the conversion completes. The 32-bits of \( D_{OUT}(k) \) can be read out before the beginning of the next A/D conversion.

![Figure 23. Typical Filtered Output Data Operation Timing](image)

![Figure 24. Reading Out Filtered Output Data with Distributed Read](image)
APPLICATIONS INFORMATION

Distributed Read
LTC2508-32 enables the user to read out the contents of the I/O register over multiple conversions. Figure 24 shows a case where one bit of D_{OUT}(k) is read for each of 32 consecutive A/D conversions, enabling the use of a much slower serial clock (SCKA). Transitions on the digital interface should be avoided during A/D conversion operations (when BUSY is high).

Synchronization
The output of the digital filter D_{1}(n) is updated every conversion, whereas the down-sampler output D_{OUT}(k) is updated only once every DF number of conversions. Synchronization is the process of selecting when the output D_{OUT}(k) is updated.

This is done by applying a pulse on the SYNC pin of the LTC2508-32. The I/O register for D_{OUT}(k) is updated at each multiple of DF number of conversions after a SYNC pulse is provided, as shown in Figure 25. A timing signal DRL indicates when D_{OUT}(k) is updated.

The SYNC function allows multiple LTC2508 devices, operated from the same master clock that use common SYNC signal, to be synchronized with each other. This allows each LTC2508 device to update its output register at the same time. Note that all devices being synchronized must operate with the same DF.

![Figure 25. Synchronization Using a Single SYNC Pulse](image-url)
APPLICATIONS INFORMATION

Periodic Synchronization

SYNC pulses that reinforce an existing synchronization do not interfere with normal operation. Figure 26 shows a case where a SYNC pulse is applied for each DF number of conversions to continually reinforce a synchronization. Figure 26 indicates synchronization windows when a SYNC pulse may be applied to reinforce the synchronized operation.

Self-Correcting Synchronization

Figure 27 shows a case where an unexpected glitch on MCLK causes an extra A/D conversion to occur. This extra conversion alters the update instants for DOUT(k). The applied periodic SYNC pulse reestablishes the desired synchronization and self corrects within one conversion cycle. Note that the digital filter is reset when the synchronization is changed (reestablished).

Figure 26. Synchronization Using a Periodic SYNC Pulse

Figure 27. Recovering Synchronization from Unexpected Glitch
No Latency Output Data

Figure 28 shows a typical operation for reading the no latency output data. The no latency I/O register holds a 22-bit composite code \( R(n) \) from the most recent sample taken of inputs \( \text{IN}^+ \) and \( \text{IN}^- \) at the rising edge of MCLK. The first 14 bits of \( R(n) \) represent the input voltage difference \( (\text{IN}^+ - \text{IN}^-) \), MSB first. The last 8 bits represent the common-mode input voltage \( (\text{IN}^+ + \text{IN}^-)/2 \) (in two's complement format), MSB first.

50Hz and 60Hz Rejection

Figure 29 shows the frequency response of the digital filter in the LTC2508-32 configured to operate with \( \text{DF} = 16384 \), and \( f_{\text{SMPL}} = 1 \text{Msps} \). As shown, at least 100dB simultaneous suppression of 50Hz and 60Hz is obtained. Note that the frequency axis shown in Figure 29 scales with \( f_{\text{SMPL}} \).

Configuration Word

An 8-bit configuration word, \( \text{WA}[7:0] \), is appended to the 32-bit output code on SDOA to produce a total output word of 40 bits as shown in Figure 30. The configuration word designates which downsampling factor (DF) the digital filter is configured to operate with. Clocking out the configuration word is optional. Table 3 lists the configuration words for each DF value.

Table 3. Configuration WORD for Different DF Values

<table>
<thead>
<tr>
<th>DF</th>
<th>( \text{WA}[7:0] )</th>
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<tbody>
<tr>
<td>256</td>
<td>10000101</td>
</tr>
<tr>
<td>1,024</td>
<td>10100101</td>
</tr>
<tr>
<td>4,096</td>
<td>11000101</td>
</tr>
<tr>
<td>16,384</td>
<td>11100101</td>
</tr>
</tbody>
</table>

For more information [www.linear.com/LTC2508-32](http://www.linear.com/LTC2508-32)
Filtering Output Data, Single Device, DF = 256

Figure 31 shows an LTC2508-32 configured to operate with DF = 256. With RDLA grounded, SDOA is enabled and MSB (DA31) of the output result is available $t_{DSOADRLL}$ after the falling edge of DRL.
APPLICATIONS INFORMATION

Filtered Output Data, Multiple Devices, DF = 256

Figure 32 shows two LTC2508-32 devices configured to operate with DF = 256, while sharing MCLK, SYNC, SCKA and SDOA. By sharing MCLK, SYNC, SCKA and SDOA, the number of required signals to operate multiple ADCs in parallel is reduced. Since SDOA is shared, the RDLA input of each ADC must be used to allow only one LTC2508-32 to drive SDOA at a time in order to avoid bus conflicts. As shown in Figure 32, the RDLA inputs idle high and are individually brought low to read data out of each device between conversions. When RDLA is brought low, the MSB of the selected device is output on SDOA.

Figure 32. Reading Filtered Output with Multiple Devices Sharing MCLK, SCKA and SDOA
APPLICATIONS INFORMATION

No Latency Output Data, Single Device

Figure 33 shows a single LTC2508-32 configured to read the no latency data out. With RDLB grounded, SDOB is enabled and MSB (DB13) of the output result is available \( t_{\text{DSODOBUSYL}} \) after the falling edge of BUSY.

![Diagram of LTC2508-32 configuration](image)

Figure 33. Using a Single LTC2508-32 to Read No Latency Output
APPLICATIONS INFORMATION

No Latency Output Data, Multiple Devices

Figure 34 shows multiple LTC2508-32 devices configured to read no latency data out, while sharing MCLK, SCKB and SDOB. By sharing MCLK, SCKB and SDOB, the number of required signals to operate multiple ADCs in parallel is reduced. Since SDOB is shared, the RDLB input of each ADC must be used to allow only one LTC2508-32 to drive SDOB at a time in order to avoid bus conflicts. As shown in Figure 34, the RDLB inputs idle high and are individually brought low to read data out of each device between conversions. When RDLB is brought low, the MSB of the selected device is output on SDOB.

Figure 34. Reading No Latency Output with Multiple Devices Sharing MCLK, SCKB and SDOB
Filtered Output Data, No Latency Data, Single Device

Figure 35 shows a single LTC2508-32 configured to read both filtered and no latency output data, while sharing SDOA with SDOB and SCKA with SCKB. Sharing signals reduces the total number of required signals to read both the filtered and no latency data from the ADC. Since SDOA and SDOB are shared, the RDLA and RDLB inputs of the ADC must be used to allow only one output to drive the shared SDO bus at a time in order to avoid bus conflicts.

As shown in Figure 35, the RDLA and RDLB inputs idle high and are individually brought low to read data from each serial output when data is available. When RDLA is brought low, the MSB of the filtered output data from SDOA is output on the shared SDO bus. When RDLB is brought low, the MSB of the no latency data output from SDOB is output on the shared SDO bus.
BOARD LAYOUT

To obtain the best performance from the LTC2508-32, a four-layer printed circuit board (PCB) is recommended. Layout for the PCB should ensure the digital and analog signal lines are separated as much as possible. In particular, care should be taken not to run any digital clocks or signals alongside analog signals or underneath the ADC.

Supply bypass capacitors should be placed as close as possible to the supply pins. Low impedance common returns for these bypass capacitors are essential to the low noise operation of the ADC. A single solid ground plane is recommended for this purpose. When possible, screen the analog input traces using ground.

Reference Design

For a detailed look at the reference design for this converter, including schematics and PCB layout, please refer to DC2222, the evaluation kit for the LTC2508-32. DC2222 is designed to achieve the full data sheet performance of the LTC2508-32. Customer board layout should copy DC2222 grounding, and placement of bypass capacitor as closely as possible.
LTC2508-32

PACKAGE DESCRIPTION


DKD Package
24-Lead Plastic DFN (7mm × 4mm)
(Reference LTC DWG # 05-08-1864 Rev 0)

NOTE:
1. DRAWING PROPOSED TO BE MADE VARIATION OF VERSION (WXXX) IN JEDEC PACKAGE OUTLINE MO-229
2. DRAWING NOT TO SCALE
3. ALL DIMENSIONS ARE IN MILLIMETERS
4. DIMENSIONS OF EXPOSED PAD ON BOTTOM OF PACKAGE DO NOT INCLUDE MOLD FLASH, MOLD FLASH, IF PRESENT, SHALL NOT EXCEED 0.15mm ON ANY SIDE
5. EXPOSED PAD SHALL BE SOLDER PLATED
6. SHADED AREA IS ONLY A REFERENCE FOR PIN 1 LOCATION ON THE TOP AND BOTTOM OF PACKAGE

For more information [www.linear.com/LTC2508-32](http://www.linear.com/LTC2508-32)
## REVISION HISTORY

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<th>DATE</th>
<th>DESCRIPTION</th>
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<tr>
<td>A</td>
<td>11/16</td>
<td>Corrected text in SNR and Digital Filtering sections</td>
<td>19, 20</td>
</tr>
<tr>
<td>B</td>
<td>2/17</td>
<td>Corrected output data rate value in Table 1</td>
<td>21</td>
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<td>C</td>
<td>4/17</td>
<td>Add operation for 1.024msps sample rate</td>
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### RELATED PARTS

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<td>24-Bit, 1.5/2Msps, ±0.5ppm INL Serial, Low Power ADC</td>
<td>2.5V Supply, ±5V Fully Differential Input, 100dB SNR, MSOP-16 and 4mm × 3mm DFN-16 Packages</td>
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<td>LTC2368-24</td>
<td>24-Bit, 1Msps, ±0.5ppm INL Serial, Low Power ADC with Unipolar Input Range</td>
<td>2.5V Supply, 0V to 5V Fully Unipolar Input, 98dB SNR, MSOP-16 and 4mm × 3mm DFN-16 Package</td>
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<td>LTC2378-20/</td>
<td>20-Bit, 1Msps/500ksps/250ksps, ±0.5ppm INL Serial, Low Power ADC</td>
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<td>LTC2377-20/</td>
<td>18-Bit, Single Parallel IOUT SoftSpan™ DAC</td>
<td>±1LSB INL/DNL, Software-Selectable Ranges, 7mm × 7mm LQFP-48 Package</td>
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<td>LTC2376-20</td>
<td>16-Bit/14-Bit/12-Bit Single Serial VOUT DAC</td>
<td>±1LSB INL/DNL, MSOP-8 Package, 0V to 5V Output</td>
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<tr>
<td>LTC2630</td>
<td>12-Bit/10-Bit/8-Bit Single VOUT DACs</td>
<td>SC70 6-Pin Package, Internal Reference, ±1LSB INL (12 Bits)</td>
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### REFERENCES

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<td>LTC6655</td>
<td>Precision Low Drift Low Noise Buffered Reference</td>
<td>5V/4.906V/3.3V/3V/2.5V/2.048V/1.25V, 2ppm/°C, 0.25ppm Peak-to-Peak Noise, MSOP-8 Package</td>
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<td>LTC6652</td>
<td>Precision Low Drift Low Noise Buffered Reference</td>
<td>5V/4.906V/3.3V/3V/2.5V/2.048V/1.25V, 5ppm/°C, 2.1ppm Peak-to-Peak Noise, MSOP-8 Package</td>
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### AMPLIFIERS

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<td>Low Noise Zero-Drift Operational Amplifier</td>
<td>4µV Offset Voltage, 0.015µV/°C Offset Voltage Drift</td>
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<td>LTC6363</td>
<td>Low Power, Fully Differential Output Amplifier/Driver</td>
<td>Single 2.8V to 11V Supply, 1.9mA Supply Current, MSOP-8 and 2mm × 3mm DFN-8 Package</td>
</tr>
<tr>
<td>LTC6362</td>
<td>Low Power, Fully Differential Input/Output Amplifier/Driver</td>
<td>Single 2.8V to 5.25V Supply, 1mA Supply Current, MSOP-8 and 3mm × 3mm DFN-8 Package</td>
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