Connecting the AD1836A Evaluation Board to the ADSP-21161N SHARC® EZ-KIT Lite™

Contributed by Mazlum Adas

June 4, 2003

Introduction

The ADSP-21161N SHARC® DSP has four independent synchronous Serial Ports (SPORTs). Every SPORT has two channels, channel A and B. These channels can be programmed both as receiver or both as transmitter. Beside the Time Division Multiplex (TDM) and serial mode, the SPORTs of the ADSP-21161N SHARC DSP also support the Inter IC-Sound (I²S) mode developed by Philips.

The AD1836A is a multi channel codec which supports up to 96 kHz sample rate. This codec provides support for Right-Justified, Left-Justified, I²S, Serial and TDM mode.

The AD1836A provided with the ADSP-21161N EZ-KIT Lite™ supports TDM and serial mode communication over the serial ports 0 and 2. In order to show the functionality of the serial ports in I²S mode an external AD1836A codec can be connected to serial ports 1 and 3. This document shows how to connect the AD1836A evaluation board and the ADSP-21161N EZ-KIT Lite (board revision 2.3 and silicon revision 1.2) to realize this mode of operation.

I²S Mode Signal Chain

Figure 1 shows the block diagram of the signal chain for the connection between the AD1836A Evaluation Board and ADSP-21161N EZ-KIT Lite.

Figure 1: Connection of the AD1836A Evaluation Board and the ADSP-21161N EZ-KIT Lite
The software flow for the data transmission between the ADSP-21161N SHARC DSP and the AD1836A is described in the following figure (Figure 2):

Figure 2: Data transmission flow diagram

The configuration and initialization of the AD1836A codec is done over the Serial Port Interface (SPI). The I²S data from the Analog to Digital Converters (ADCs) are received from SPORT1 channel A. The SPORT3 transmits with both channels A and B the I²S data back to the Digital to Analog Converters (DACs).

Before examining the software flow of the data transmission, let’s have a look at the system hardware configuration.
**SPI connection**

The Figure 3 shows the connection of the AD1836A Eval. Board to the ADSP-21161N EZ-KIT Lite over the SPI port.

Figure 3: SPI connection between the AD1836A evaluation board and the ADSP-21161N EZ-KIT Lite

The SPI Control Port (P4) on the AD1836A Evaluation Board is used for the SPI connection with the ADSP-21161N EZ-KIT Lite SPI connector (P18) to build up the SPI communication system. The ADSP-21161N SHARC DSP acts as the SPI master and the AD1836A as the SPI slave. A FLAG pin of the ADSP-21161N SHARC DSP is used as the chip select for the slave device (JP4 on the ADSP-21161N EZ-KIT Lite).

**SPORT connection**

The Figure 4 shows the SPORT connection between the two boards.

Figure 4: SPORT connection between the AD1836A evaluation board and the ADSP-21161N EZ-KIT Lite
The on board connectors on both evaluation boards facilitate the hardware setup for the serial port connection. As shown in Figure 4, the SPORT connector (P15) of the ADSP-21161N EZ-KIT Lite needs to be connected to the DSP I/O Port (P3) on the AD1836A Evaluation Board.

On the ADSP-21161N EZ-KIT Lite both frame syncs (SFS1 and SFS3) and the serial clocks (SCLK1 and SCLK3) are tied together with Zero-Ohm Resistors.

On the AD1836A Evaluation Board both bit clocks (ADC ABCLK and DAC DBCLK) and also the Left Right clocks (ALRCLK and DLRCLK) should be connected together to get clear signals. The Figure 5 shows this connection.

![Connection of the clocks on the AD1836 Evaluation Board](image)

*Figure 5: Connecting the ADC and DAC1 clocks*

**Jumper Settings on the ADSP-21161N EZ-KIT Lite**

For the connection of the ADSP-21161N EZ-KIT Lite to the AD1836A Evaluation Board the jumpers should be set as follows (Table 1):

<table>
<thead>
<tr>
<th>Jumper</th>
<th>Description</th>
<th>State</th>
</tr>
</thead>
<tbody>
<tr>
<td>JP4</td>
<td>FLAG 0 enable</td>
<td>OFF</td>
</tr>
<tr>
<td>JP5</td>
<td>FLAG 1 enable</td>
<td>OFF</td>
</tr>
<tr>
<td>JP23</td>
<td>SPORT/SPI clock enable</td>
<td>ON</td>
</tr>
<tr>
<td>JP26</td>
<td>Push-button enable FLAG 0</td>
<td>OFF</td>
</tr>
<tr>
<td>JP27</td>
<td>Push-button enable FLAG 1</td>
<td>OFF</td>
</tr>
</tbody>
</table>

*Table 1: ADSP-21161N EZ-KIT Lite jumper’s settings*
Jumpers Settings on the AD1836A Evaluation Board

There are two jumpers and two switches on the AD1836A evaluation board.

The ADCs of the AD1836A on the evaluation board have different operation input modes (see AD1836A Datasheet for more details). For these particular examples, the direct differential mode is selected for best performance. This mode is configured as follows (Table 2):

<table>
<thead>
<tr>
<th>Jumper/Switch</th>
<th>Description</th>
<th>State</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1(1&amp;3, 2&amp;4)</td>
<td>ADC1 input mode</td>
<td>ON</td>
</tr>
<tr>
<td>P2(1&amp;3, 2&amp;4)</td>
<td>ADC2 input mode</td>
<td>ON</td>
</tr>
<tr>
<td>SW1(1&amp;4, 2&amp;5)</td>
<td>Input select</td>
<td>ON</td>
</tr>
</tbody>
</table>

Table 2: AD1836A Evaluation Board jumpers/switch settings

In addition to this, switch 3 (SW3) is used to configure the PLD on the AD1836A evaluation board. For proper data transmission, this switch must be set to one of the following values: C, D, E or F (for more details refer to the AD1836A Evaluation Board schematics).

Initialization of the ADSP-21161N EZ KIT Lite

Listing 1 shows the code section init_DSP (contained in Init_21161_EZKit.asm); all relevant registers of the ADSP-21161N SHARC DSP are initialized here.

```
Init_DSP:
bit set MODE1 CBUFEN; // Enable circular buffering for rev < 1.0
/* Setup hardware interrupts, FLAG LEDs and pushbutton */
ustat2=0x00000000;

/* flags 4-9 are outputs for LEDs, turn on all LEDs*/
bit set ustat2 FLG9O|FLG8O|FLG7O|FLG6O|FLG5O|FLG4O;
bit set ustat2 FLG9|FLG8|FLG7|FLG6|FLG5|FLG4;
dm(IOFLAG)=ustat2;

bit clr MODE2 FLG0O | FLG1O | FLG2O | FLG3O; // flag 0-3 are inputs from pushbutton switches
IMASK = 0x0;
LIRPTL = 0x0;
IRPTL = 0x00000000; /* clear pending interrupts */
L0 = 0; L1 = 0; L2 = 0;
L3 = 0; L4 = 0; L5 = 0;
L6 = 0; L7 = 0; L8 = 0;
L9 = 0; L10 = 0; L11 = 0;
L12 = 0; L13 = 0; L14 = 0;
L15 = 0;
r15 = 0;
IRPTL = 0x00000000; /* clear pending interrupts */
bit set mode1 IRPTEN; /* enable global interrupts, nesting */
bit set imask SP1I|SP3I; /* start audio processing, enable SPORT1 tx & rx int */
```

Listing 1: Init_DSP
Note that, upon reset, circular buffers are enabled. However, this is only the case for silicon revisions 1.0 and greater. Therefore, and in case an older silicon revision is being used, circular buffers would need to be enabled within this routine.

Additionally, this section sets the global interrupt enable bit, which needs to be done before the audio routines start. Also, the related interrupts for the audio processing (SPORT1 and SPORT3) are enabled here.

**Configuration of the AD1836A via the SPI**

The ADSP-21161N SHARC DSP configures the AD1836A via its SPI port by sending the appropriate control words. The serial SPI 16-bit word format for the AD1836A codec register commands is as follows:

- D15 to D12 = Codec Register Address
- D11 = Read/Write register (1=rd, 0=wr)
- D10 = Reserved bit, clear to zero
- D9 to D0 = Data Field for codec register

The following registers of the AD1836A are programmed as shown in Table 3:

<table>
<thead>
<tr>
<th>Control Registers</th>
<th>Modes</th>
<th>Setting</th>
</tr>
</thead>
<tbody>
<tr>
<td>DAC control register 1</td>
<td>Serial mode</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Interpolator mode</td>
<td></td>
</tr>
<tr>
<td>ADC control register 1</td>
<td>sample rate</td>
<td>96 kHz</td>
</tr>
<tr>
<td>ADC control register 2¹</td>
<td>SOUT mode</td>
<td></td>
</tr>
<tr>
<td>ADC control register 3</td>
<td>(default)</td>
<td></td>
</tr>
</tbody>
</table>

¹Bit 9 Master/Slave AUX mode in the ADC control register 2 is set to 0, and it can be only set to master in Auxiliary mode.

Table 3: Control Registers Settings

Please refer to the AD1836A Datasheet for more details on the control words and their corresponding settings.

Before sending the control words to the AD1836A it is recommended to reset the codec. Reset will start up the codec and set the control registers to their default settings. This is done in the software routine `powerdown_reset_AD1836A`.

Note that it is not possible to read back the control words sent to the AD1836A from the ADSP-21161N SHARC DSP. Only the Peak Level registers of the ADCs can be read.

In order to be able to program the codec, the ADSP-21161N SHARC DSP SPI port must be configured first. This is done in the SPICTL register as follows (AD1836A_reg_init_viaSpi.asm):

```assembly
dm(SPICTL) = ustat1;
```

The definitions of the relevant bits in the SPICTL registers for this particular example are shown below (Table 4):
<table>
<thead>
<tr>
<th>Bit Name</th>
<th>Bit definition</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SPIEN</td>
<td>SPI Port Enable</td>
<td>This bit enables the SPI system</td>
</tr>
<tr>
<td>MS</td>
<td>Master Select</td>
<td>This bit selects the device as master</td>
</tr>
<tr>
<td>PSSE</td>
<td>Programmable Slave Select Enable</td>
<td>This bit is used to program the controlled automatic generation of slave device select signals during SPI transfer.</td>
</tr>
<tr>
<td>SPTINT</td>
<td>SPITX Interrupt Enable</td>
<td>This bit enables the SPI transmit interrupt. It is necessary to set this bit in SPI data transfer, if the ADSP-21161N SHARC DSP transmits the SPI data words to the slave. The slave selection is subsequently made using the FLS bits.</td>
</tr>
<tr>
<td>FLS</td>
<td>Flag select</td>
<td>These 4 bits select which flag pins are used when multiple slaves are used. The setting FLS0 means that the flag 0 is used to select the slave device.</td>
</tr>
<tr>
<td>BAUDR</td>
<td>Baud Rate</td>
<td>With these four bits it is possible to control the SPI clock frequency. The ADSP-21161N SHARC DSP is set as master, so the master device provides the AD1836A codec (slave) with the clock signal. The equation is ( \text{SPIbaudrate} = \frac{\text{Coreclock}}{2^{(2+RR)}} ) The setting in the code BAUDR8 means: ( \text{SPIbaudrate} = \frac{100\text{MHz}}{2^{(2+8)}} = 97,656kHz )</td>
</tr>
<tr>
<td>WL</td>
<td>Word length</td>
<td>These 2 pins make possible to select different word length. In this application the word length is 16 bit.</td>
</tr>
<tr>
<td>NSMLS</td>
<td>Non-Seamless Operation</td>
<td>This bit indicates that after each word transfer there is a delay before the next word transfer starts.</td>
</tr>
<tr>
<td>DF</td>
<td>Data Format</td>
<td>This bit selects the data format. In this case the MSB sent/received first.</td>
</tr>
<tr>
<td>CPHASE</td>
<td>Clock Phase</td>
<td>This bit selects the clock phase transfer format. ( \text{SPICLK} ) starts toggling at the beginning of the first data transfer bit if the bit is set.</td>
</tr>
<tr>
<td>CP</td>
<td>Clock Polarity</td>
<td>This bit selects the clock polarity. ( \text{SPICLK} ) high is the idle state.</td>
</tr>
<tr>
<td><strong>DCPH0</strong></td>
<td>Deselect SPIDS in CPHASE = 0</td>
<td>This bit deselects when the slave between successive word transfers in CPHASE = 0. The slave is selected in master mode using PSSE functionality. This bit is valid only when NSMLS bit is set.</td>
</tr>
</tbody>
</table>

*Table 4: Bit definitions of the SPICTL register*

### Setting up the I/O Processor for chained SPORT DMA

The transmission of the I²S data is done via the SPORTs using chained Direct Memory Access (DMA) operation. DMA chaining is the auto-linkage of DMA transfers. The completion of one DMA sets off another DMA without any core intervention. Transfer Control Blocks (TCB) are data buffers in the internal memory where the DMA parameters are stored. The DMA channel parameters are automatically loaded by the I/O Processor (IOP) from the TCBs when chaining is enabled.

The TCB format for the SPORT looks as follows:

```c
/* TCB format for SPORT:
  GPx ("general purpose"),
  CPx ("Chain Point register"; points to last address (IIx) of next TCB to jump to upon completion of this TCB.),
  Cx (length of source buffer),
  IMx (source buffer step size),
  IIx (source buffer index (initialized to start address)) */
```

For the SPORT1 one TCB for channel A is needed, for the SPORT3 two TCBs for both channels A and B are needed:

```c
.var  sp1a_tcb[5] = 0, sp1a_tcb+4, N, 1, rx1a_buf; /* SPORT1 receive channel a tcb */
.var  sp3a_tcb[5] = 0, sp3a_tcb+4, N, 1, tx3a_buf; /* SPORT3 transmit channel a tcb */
.var  sp3b_tcb[5] = 0, sp3b_tcb+4, N, 1, tx3b_buf; /* SPORT3 transmit channel b tcb */
```

The first DMA in the chain is started by writing the address of the TCB to the Chain Pointer Register of the DMA channel:

```c
r8=sp1a_tcb+4; // Internal Index 1 address
r9=sp3a_tcb+4; // Internal Index 3 address
r10=sp3b_tcb+4; // Internal Index 3 address

dm(CP1A)=r8;   // SPORT1 channel A DMA chain enable
dm(CP3A)=r9;   // SPORT3 channel A DMA chain enable
dm(CP3B)=r10;  // SPORT3 channel B DMA chain enable
```

For more details on the IOP and chained DMA operation refer to ADSP-21161 SHARC DSP Hardware Reference (page 6-28).

Now the AD1836A as well as the DMA Controller have been properly configured, it’s time to configure the SPORTs before starting with the data transmission.
Setting up the SPORTs

The configuration of the serial ports is, that the SPORT1 operates as receiver and the SPORT3 as transmitter.

The settings in the SPORT1 control register are as follows:

```c
// SPORT1 control register set up as a receiver in I2S
R0 = SPEN_A|SLEN32|OPMODE|LFIRST|SDEN_A|SCHEN_A;
dm(SPCTL1) = R0;  /* sport 1 control register SPCTL1 = 0x000D09F1 */
```

Note, that the channel B is not being used, therefore only the parameters of channel A need to be configured (Table 5).

<table>
<thead>
<tr>
<th>Bit Name</th>
<th>Bit Definitions</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SPEN_A</td>
<td>SPORT Enable A</td>
<td>This bit enables the channel A of SPORT1</td>
</tr>
<tr>
<td>SLEN</td>
<td>Serial Word Length</td>
<td>These five bits defines the word length of the data transmission. The transmitted data is 32 bit, but the valuable data is 24 bits.</td>
</tr>
<tr>
<td>MSTR</td>
<td>I2S Serial and L/R clock master</td>
<td>This bit is not set, so the SPORT is provided with external clock and word select and the configuration is in slave mode.</td>
</tr>
<tr>
<td>OPMODE</td>
<td>Operation Mode</td>
<td>This bit must be set, because the operation mode of the SPORT is I2S.</td>
</tr>
<tr>
<td>LFIRST</td>
<td>Left or Right I2S channel RX/TX first</td>
<td>This bit selects the left channel first for receiving data.</td>
</tr>
<tr>
<td>SDEN_A</td>
<td>SPORT transmit dma enable for channel A</td>
<td>The I2S data is received with channel A, so this bit must be enabled.</td>
</tr>
<tr>
<td>SCHEN_A</td>
<td>DMA chaining enable for channel A</td>
<td>This bit enables the DMA chaining for channel A of SPORT1. If one DMA is finished the next one gets started.</td>
</tr>
<tr>
<td>DDIR</td>
<td>Data Direction Control</td>
<td>This bit controls the data direction. If this bit is set, the transmit buffers are active, but the SPORT1 should receive the data, so this bit is not set.</td>
</tr>
</tbody>
</table>

*Table 5: Bit settings of the serial port 1 control register (SPCTL1)*

Similarly SPORT3 control register is configured as follows:

```c
// SPORT3 control register set up as a transmitter in I2S
R0 = SPEN_A|SLEN32|OPMODE|DITFS|LFIRST|SDEN_A|SCHEN_A|SDEN_B|SCHEN_B|FS_BOTH|SPEN_B|DDIR;
dm(SPCTL3) = R0;  /* sport 3 control register, SPCTL3 = 0x273D09F1 */
```

Note that, SPORT3 is transmitting with both channels A and B, so the bits for the B channels must also set. (Table 6)
<table>
<thead>
<tr>
<th>Bit Name</th>
<th>Bit definition</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SPEN_B</td>
<td>SPORT Enable B</td>
<td>This bit enables the channel B of SPORT3.</td>
</tr>
<tr>
<td>SDEN_B</td>
<td>SPORT transmit DMA enable for channel B</td>
<td>This bit enables the DMA for channel B of SPORT3.</td>
</tr>
<tr>
<td>SCHEN_B</td>
<td>DMA chaining enable for channel B</td>
<td>This bit enables the DMA chaining for channel B of SPORT3.</td>
</tr>
<tr>
<td>DDIR</td>
<td>Data Direction Control</td>
<td>This bit must be set now, because the SPORT3 is transmitter.</td>
</tr>
<tr>
<td>DITS</td>
<td>Data Independent TX Frame sync, if DDIR=1</td>
<td>This bit sets the SPORT uses data independent frame sync</td>
</tr>
<tr>
<td>FS_BOTH</td>
<td>Frame Sync both enable</td>
<td>The data transmission occurs, if data is present in both TX buffers</td>
</tr>
</tbody>
</table>

Table 6: Bit settings of the serial port 3 control register (SPCTL3)

**Interrupt service routines of the SPORTs**

When the SPORT1 receives the I²S data from the ADC an interrupt will be generated (remember that the serial port interrupts have been previously enabled). In the `Process_AD1836A_Audio_Samples` routine, the data will be read from the receive buffer. After reading the data from the receive buffer, the data will then be written to the transmit buffers A and B of SPORT3. Note that these data transfers are performed by the core (using the Data Address Generators - DAGs)

Once the data is in the transmit buffers, the I²S data will get transmitted to the DACs.

```
Process_AD1836A_Audio_Samples:
LCNTR=1024, DO (PC,3) UNTIL LCE; // do the next 3 instructions many times
R0=DM(I0,M0);                    // read the data from the receive buffer
DM(I1,M1)=R0;                    // write the data to the transmit buffer a
DM(I2,M2)=R0;                    // write the data to the transmit buffer b
rti;
```
Figure 6 illustrates the data flow when it’s received until it gets transmitted out to the DAC:

Additionally, the data transmission between the ADSP-21161N SHARC DSP SPORTs and the AD1836A codec is shown in Figure 7, where:

Channel 1: Frame sync 96 kHz
Channel 2: I²S data received on the SPORT1 channel A
Channel 3: I²S data transmitted with SPORT3 channel A
Channel 4: I²S data transmitted with SPORT3 channel B

Figure 7: Scope plot of the I²S data transmission
**References**


**Document History**

<table>
<thead>
<tr>
<th>Version</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>June 04, 2003 by Mazlum Adas</td>
<td>Initial Release</td>
</tr>
</tbody>
</table>