

## Using Absolute Output $\mu$ MEMS<sup>®</sup> Gyroscopes with Ratiometric ADCs

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$\mu$ MEMS gyroscopes are often used with low cost ratiometric ADCs integral to many microcontrollers. This application note outlines how to interface a gyro's absolute (invariant with supply voltage variations) output with a ratiometric ADC.

### GENERAL CONCEPTS

Ratiometric ADCs return a numeric value that corresponds to the ratio of the input voltage to the supply voltage. For example, an 8-bit ratiometric ADC that has a supply voltage of 5.00 V and 1.99 V at its input would return a value (in bits) of

$$\text{Output} = 2^8 \times (1.99 \text{ V} / 5.00 \text{ V}) = 102$$

If the supply voltage changes by -5% (to 4.75 V) the converter would return a value approximately 5% greater or

$$\text{Output} = 2^8 \times (1.99 \text{ V} / 4.75 \text{ V}) = 107$$

Since supply voltage can rarely be counted on to be very accurate or constant, some provision must be made for conversion errors when interfaced to transducers with absolute outputs.

### USING THE GYRO'S REFERENCE OUTPUT

All Analog Devices gyros have a 2.5 V reference output that can be used to reduce conversion errors. The general idea is that by performing an A/D conversion on a known voltage (the gyro's 2.5 V reference), one can calculate what the ADC's reference voltage is and an appropriate correction factor. Since the supply voltage can vary, one should perform the 2.5 V reference and gyro rate output conversions as close to simultaneously as possible.

The ADC's transfer function when measuring the gyro's 2.5 V output is

$$A/D_{OUT} = (2.5/A/D_{REF}) \times 2^n$$

where:

$n$  is the number of bits of the A/D converter.

$A/D_{REF}$  is the ADC's reference voltage.

Rearranging the equation:

$$A/D_{REF} = (2.5/A/D_{OUT}) \times 2^n$$

So the correction factor is

$$CF = (A/D_{REF} / REF_{IDEAL})$$

where  $REF_{IDEAL}$  is the ideal ADC reference voltage.

For example:

$$CF = A/D_{REF} / 5 \text{ for a 5 V system.}$$

Finally the corrected A/D value is

$$A/D_{CORRECTED} = A/D_{OUT} \times CF$$

### CONCLUSION

Using a ratiometric ADC with an absolute output device like  $\mu$ MEMS gyros can result in significant errors if the supply voltage can vary. The 2.5 V output on Analog Devices  $\mu$ MEMS gyros allows the user to compensate for these errors by simple calculations as presented above.

