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Reference Designs

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Devices Connected/Referenced	
<a href="#">AD5755-1</a>	Quad Channel, 16-Bit, Serial Input, 4 mA to 20 mA and Voltage Output DAC, Dynamic Power Control, HART Connectivity
<a href="#">AD5700-1</a>	Low Power HART Modem with Precision Internal Oscillator
<a href="#">ADG759</a>	CMOS Low Voltage, 3 Ω, 4-Channel Multiplexer
<a href="#">ADP2441</a>	36 V, 1 A, Synchronous, Step-Down DC-to-DC Regulator
<a href="#">LT8301</a>	42V <sub>IN</sub> Micropower No-Opto Isolated Flyback Converter with 65 V/3.6 A Switch
<a href="#">ADR02</a>	Ultracompact, Precision 5.0 V Voltage Reference
<a href="#">ADuM3151</a>	3.75 kV, 7-Channel, SPIsulator Digital Isolators for SPI (with 2/1 Auxiliary Channel Directionality)
<a href="#">ADuM3482</a>	Small, 3.75 kV RMS Quad Digital Isolators (2/2 Channel Directionality)

## Completely Isolated 4-Channel Analog Output Circuit for PLC/DCS Systems with HART

### EVALUATION AND DESIGN SUPPORT

#### Circuit Evaluation Boards

- [CN0418 Reference Design Board \(EVAL-CN0418-ARDZ\)](#)
- [Ultra Low Power Arduino Form Factor Development Board \(EVAL-ADICUP3029\)](#)

#### Design and Integration Files

- [Schematics, Layout Files, Bill of Materials, Software](#)

### CIRCUIT FUNCTION AND BENEFITS

The circuit shown in Figure 1 provides a complete, fully isolated, and highly flexible, 4-channel analog output system suitable for industrial grade programmable logic controllers (PLCs), distributed control system (DCS), and other industrial process control applications that require  $\pm 5$  V or  $\pm 10$  V voltage and 4 mA to 20 mA current outputs with HART connectivity.

All 4-channel outputs and power input are protected from transient overvoltage and overcurrent events, suitable for the harshest industrial environments.

The CN0418 power entry circuitry includes on-board filtering and protection, and is compatible with supply voltages from 12 V dc to 36 V dc, including standard 24 V supplies common in many PLC and DCS applications.

The HART compatibility of this module provides a complete field communication solution that is simple to use, low cost, low power, and extremely reliable.

On-chip dynamic power control minimizes package power dissipation in current output mode, easing thermal management concerns in high channel count and high density applications where multiple circuits are used together.

Address selection logic allows up to four circuits to be stacked, providing up to 16 channels in a single node, maintaining isolation between banks of four outputs. An on-board electronically erasable programmable read only memory (EEPROM) can store calibration and identification data.

#### Rev. 0

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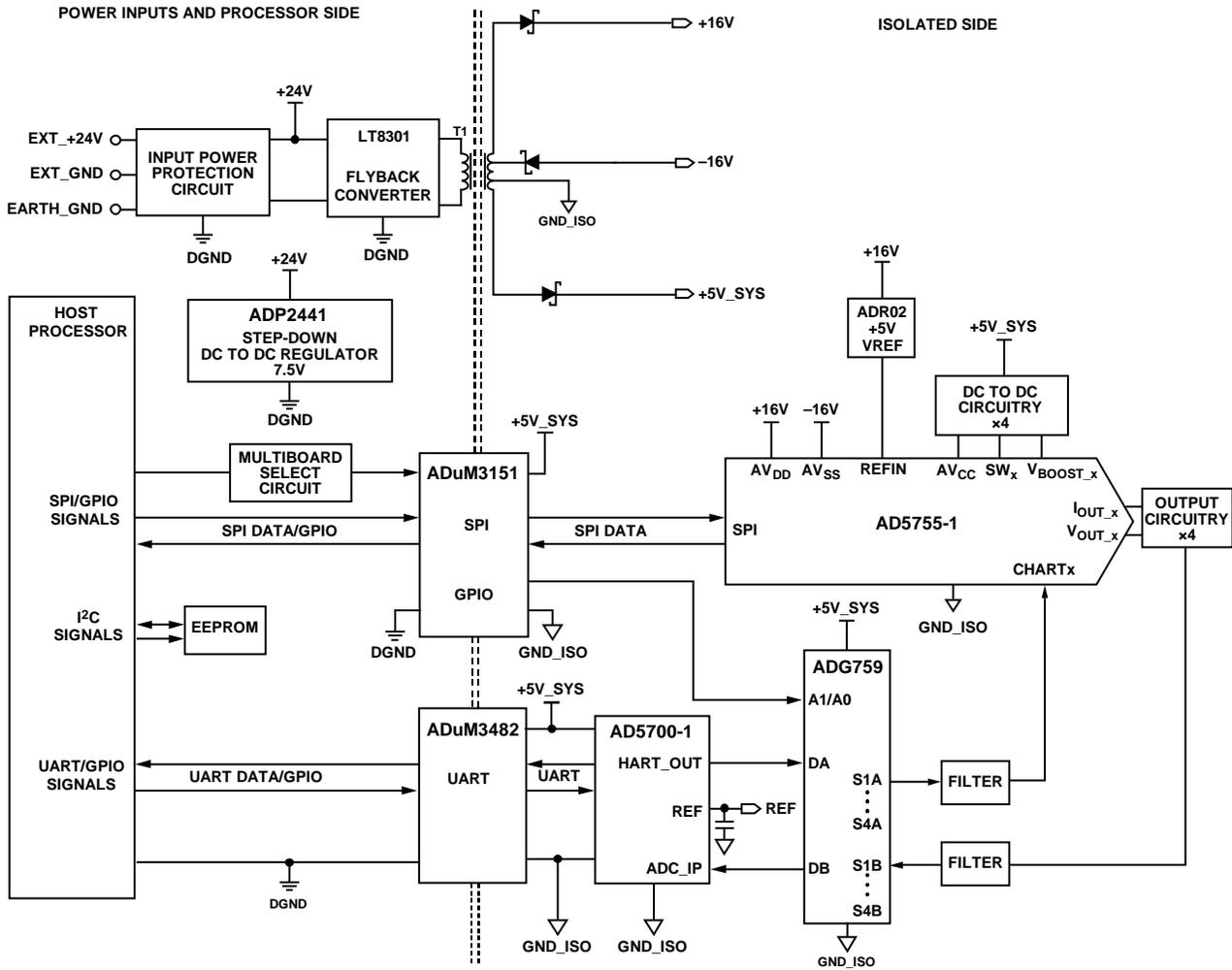


Figure 1. 4-Channel Multiplexed HART Analog Output Circuit Incorporating a Transformer Isolated Power Solution  
(Simplified Schematic: All Connections and Decoupling Not Shown)

17344-001

## CIRCUIT DESCRIPTION

Several standard voltage and current ranges are typically used in industrial control modules, including  $\pm 5$  V,  $\pm 10$  V, 0 V to 5 V, 0 V to 10 V, 4 mA to 20 mA, and 0 mA to 20 mA. The [AD5755-1](#) provides all of these ranges at 16-bit resolution in a fully integrated, low cost, single-chip solution. A 20% overrange feature is also available for the voltage output ranges. Each DAC channel has a gain and offset register, which allow trimming of the gain and offset errors of the entire signal chain.

The current and voltage outputs are available on separate pins, but only one output type is active at a given time, thus allowing both output pins to be tied together and connected to a single terminal. When the current output is enabled, the voltage output is in tristate mode, and when the voltage output is enabled, the current output is in tristate mode. Analog outputs are short-circuit and open-circuit protected.

The [AD5755-1](#) allows an internal or external precision, current setting resistor for the voltage to current conversion circuitry, as shown in Figure 2. The stability of the output current value over temperature is dependent on the stability of the value of the current setting resistor,  $R_{SET}$ . As a method of improving the stability of the output current over temperature, an external 15 k $\Omega$  low drift resistor can be connected to the  $R_{SET\_x}$  pin of the [AD5755-1](#) instead of the internal resistor. The external resistor is selected via the DAC control register. Accuracy measurements were evaluated using both options, as described in the Circuit Evaluation and Test section.

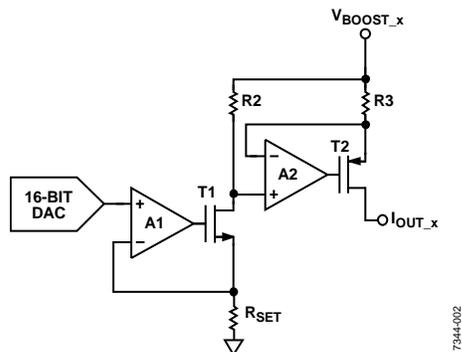


Figure 2. Voltage to Current Conversion Circuitry

### Precision Voltage Reference Selection

The [AD5755-1](#) has an on-chip 10 ppm/ $^{\circ}$ C (maximum) reference. For higher performance over temperature, this design uses an [ADR02](#) reference with a 3 ppm/ $^{\circ}$ C maximum drift (B grade, SOIC package). The voltage applied to the reference input provides a buffered reference for the DAC core. Therefore, any error in the voltage reference is reflected in the outputs.

The [ADR02](#) is a 5 V precision reference that allows for an input voltage of up to 36 V. The [ADR02](#) has a 0.06% maximum accuracy error and a 3 ppm/ $^{\circ}$ C maximum temperature drift (B grade, SOIC package). This drift contributes approximately 0.02% error across the industrial temperature range of  $-40^{\circ}$ C to  $+100^{\circ}$ C.

The [ADR02](#) has a long-term drift of 50 ppm (typical) and a 0.1 Hz to 10 Hz noise specification of 10  $\mu$ V p-p (typical).

### Dynamic Power Control

The [AD5755-1](#) contains integrated dynamic power control using a dc-to-dc boost converter circuit, allowing reduced power consumption in the current output mode. Most PLC current output circuits use a fixed voltage source to meet the output voltage compliance requirements across the full range of load resistor values. For example, a 4 mA to 20 mA loop with 750  $\Omega$  load, when driving 20 mA, requires a compliance voltage of at least 15 V. However, when driving 20 mA into a 50  $\Omega$  load, only 1 V compliance is required. If the 15 V compliance is kept when driving the 50  $\Omega$  load,  $20 \text{ mA} \times 14 \text{ V} = 280 \text{ mW}$  of power is dissipated as loss.

The [AD5755-1](#) circuitry greatly reduces this power loss by sensing the output voltage and regulating the compliance voltage to allow only a small headroom voltage regardless of the load resistance. The [AD5755-1](#) can drive up to 24 mA into a 1 k $\Omega$  load.

### DC-to-DC Converter Operation

The [AD5755-1](#) contains four independent dc-to-dc converters. These converters provide dynamic control of the  $V_{BOOST\_x}$  supply voltage for each channel. Figure 3 shows the discrete components external to the [AD5755-1](#) associated with each channel.

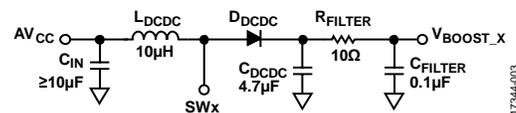


Figure 3. DC-to-DC Circuit

Placing a 10  $\Omega$ , 100 nF low-pass RC filter after  $C_{DCDC}$  is recommended. This filter consumes a small amount of power but reduces the amount of ripple on the  $V_{BOOST\_x}$  supply.

The dc-to-dc converters use a constant frequency, peak current mode control scheme to step up an  $AV_{CC}$  input of 4.5 V to 5.5 V to drive the [AD5755-1](#) output channel. These converters are designed to operate in discontinuous conduction mode (DCM) with a duty cycle of <90% typical.

When a channel is set to a current output range, the converter regulates the  $V_{BOOST\_x}$  supply to 7.4 V ( $\pm 5\%$ ) or ( $I_{OUT\_x} \times R_{LOAD} + \text{headroom}$ ), whichever is greater. In the current output mode with the output disabled, the converter regulates the  $V_{BOOST\_x}$  supply to 7.4 V ( $\pm 5\%$ ). In voltage output mode with the output disabled, the converter regulates the  $V_{BOOST\_x}$  supply to 15 V ( $\pm 5\%$ ). For full details of the dc-to-dc converter operation, see the [AD5755-1](#) data sheet.

### Digital Slew Rate Control

The slew rate control feature of the [AD5755-1](#) allows the user to control the rate at which the output value changes. This feature is available on both the current and voltage outputs and serves two important functions: it reduces the transient current drawn from  $AV_{CC}$  as an output is slewing from a low value to a high value, and it reduces disturbances to HART communication.

With the slew rate control feature disabled, the output value changes at a rate limited by the output drive circuitry and the attached load. With the slew rate feature enabled via the SREN bit of the slew rate control register, the output slews between two levels at a rate defined by the SR\_CLOCK and SR\_STEP parameters accessible via the slew rate control register.

The following equation describes the slew rate as a function of the step size, the update clock frequency, and the LSB size:

$$\text{Slew Time} = \frac{\text{Output Change}}{\text{Step Size} \times \text{Update Clock Frequency} \times \text{LSB Size}}$$

where:

*Slew Time* is expressed in seconds.

*Output Change* is expressed in amps for I<sub>OUT,x</sub> or volts for V<sub>OUT,x</sub>.

See the [AD5755-1](#) data sheet for further details.

### Transient Voltage Protection

The [AD5755-1](#) contains ESD protection diodes that prevent damage from normal handling. However, the industrial control environment can subject input/output (I/O) circuits to much higher transients. To protect the [AD5755-1](#) from excessively high voltage transients, a 24 V transient voltage suppressor (TVS) is placed on the I<sub>OUT,x</sub>/V<sub>OUT,x</sub> connection, as shown in Figure 4.

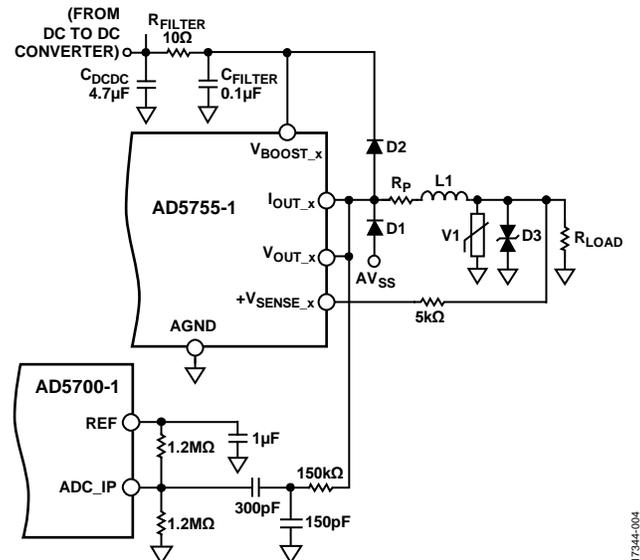


Figure 4. Output Transient Voltage Protection

For added protection, clamping diodes are connected from the I<sub>OUT,x</sub> and V<sub>OUT,x</sub> pins to the V<sub>BOOST,x</sub> and AV<sub>SS</sub> power supply pins. A 5 kΩ current limiting resistor is also placed in series with the +V<sub>SENSE,x</sub> input. This resistor limits the current to an acceptable level during a transient event. The recommended external band-pass filter for the [AD5700](#) HART modem includes a 150 kΩ resistor that limits the current to a sufficiently low level such that additional protection circuitry is not required, even in the most demanding industrial environments.

### Input Power Protection

A regulated industrial standard supply, such as a 12 V dc or 24 V dc supply, is connected to the EVAL-CN0418-ARDZ board through a 2-wire or 3-wire interface. This supply must be protected against faults and electromagnetic interference (EMI) as shown in Figure 5.

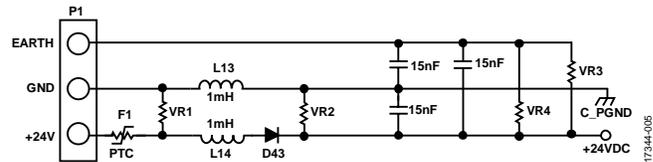


Figure 5. Input Power Transient Voltage Protection

VR1, VR2, VR3, and VR4 are metal-oxide varistor surge suppressors, and F1 is a 1 A, resettable polyfuse. This circuit ensures that the reference design system survives interference and transients that may be present on the power ports. See [PLC Evaluation Board Simplifies Design of Industrial Process Control Systems](#), Analog Dialogue 43-04, April 2009, for more details.

### Power Supply Circuit

The EVAL-CN0418-ARDZ board is powered by a 12 V to 36 V dc supply and uses an on-board switching regulator to provide the 7.5 V supply to the platform board, as shown in Figure 6 and Figure 7. In the test setup, 7.5 V powers the [EVAL-ADICUP3029](#) board. The [EVAL-ADICUP3029](#) board then provides a regulated 3.3 V for the voltage at the IO\_VREF pin (see Figure 7) and 5 V to the remaining circuitry.

The [ADP2441](#) 36 V step down, dc-to-dc regulator accepts an industrial standard 24 V supply, with wide tolerance on the input voltage. The [ADP2441](#) steps the input voltage down to 7.5 V at 1 A for the platform board and 5 V power for the remainder of the EVAL-CN0418-ARDZ, utilizing the 5 V regulator typically present on Arduino-compatible platforms. The circuit also includes filtering and protection on the 24 V supply terminals.

The high switching frequency of the [ADP2441](#) allows minimal output voltage ripple even when small inductors are used. Selecting the size of the inductor involves considering the trade-off between efficiency and transient response. A smaller inductor results in larger inductor current ripple, which provides improved transient response but degrades efficiency. Due to the high switching frequency of the [ADP2441](#), using shielded ferrite core inductors is recommended because of their low core losses and low EMI.

In the Figure 6 circuit, the switching frequency is approximately 550 kHz with the 162 kΩ external resistor. The inductor value of 33 μH is chosen from the [ADP2441](#) data sheet. The circuit is connected to the field supply of 12 V to 36 V using screw terminals. The EARTH terminal can be connected to an external earth connection or to the GND terminal if an external earth connection is not used. Power inductors, varistors, a power diode, and a 1.1 A fuse provide additional input protection against high voltage transient events.

Isolated power is generated by an [LT8301](#) no-opto isolated flyback converter. A transformer with a four-tap secondary winding provides isolation and generates +16 V, -16 V, and +5 V supplies. The output voltage is regulated by sampling the primary side flyback waveform, eliminating the need for opto-isolators, auxiliary sense windings, or other isolated feedback methods.

The [LT8301](#) tends to regulate the most heavily loaded output in a multiple output circuit. The [AD5755-1](#) presents a range of loading conditions to the +16 V supply, -16 V supply, and +5 V supply rails. Table 1 shows the supply voltages under various load conditions that meet the [AD5755-1](#) requirements.

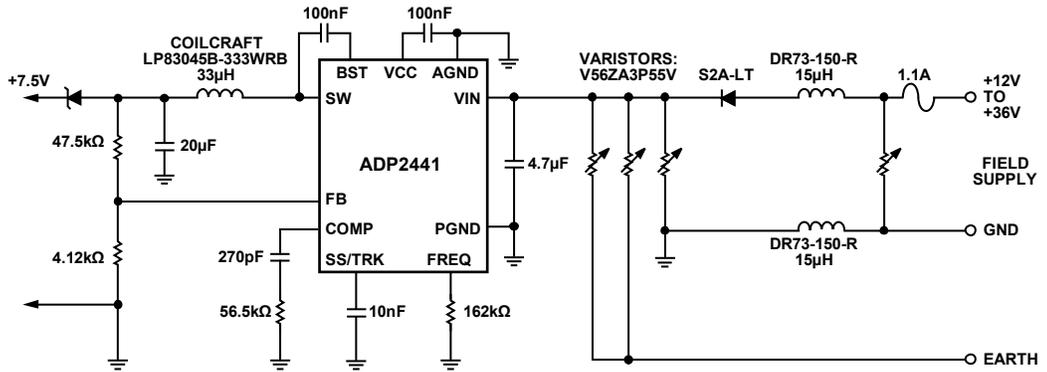


Figure 6. Power Supply Circuit (Simplified Schematic: All Connections Not Shown)

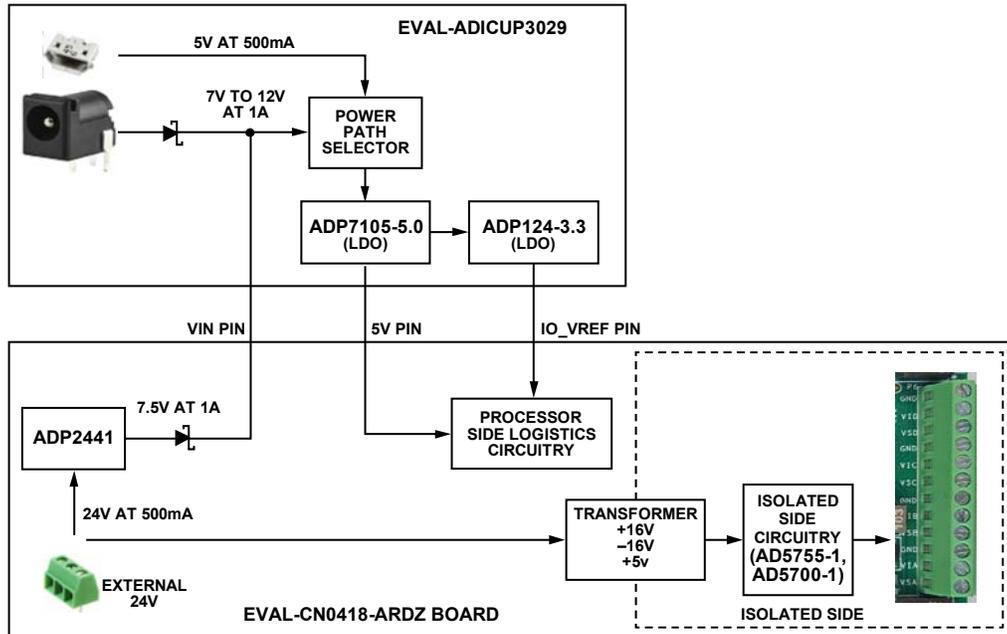


Figure 7. Power Tree and Configurations for EVAL-CN0418-ARDZ Board

Table 1. Transformer Isolated Supply Rail Voltages

Setup	+16 V Supply (V)	-16 V Supply (V)	+5 V Supply (V)
Power Circuit Unloaded, <a href="#">AD5755-1</a> Outputs Disabled	16.15	-16.15	4.8750
<a href="#">AD5755-1</a> in Current Output Mode			
20 mA on Four Channels (1 kΩ Load)	18.55	-20.93	4.8936
24 mA on Four Channels (1 kΩ Load)	19.64	-22.11	4.8622
<a href="#">AD5755-1</a> in Voltage Output Mode, 10 V on Four Channels (500 Ω Load)	17.11	-17.11	4.9476

The [AD5755-1](#) has a wide supply voltage tolerance, but the circuit must be evaluated thoroughly when integrating to customer systems. Verify that the [LT8301](#) maintains regulation of the isolated supplies within the allowable ranges listed in the [AD5755-1](#) data sheet under all normal loading conditions, fault conditions, and over the expected range of input supply voltage.

**HART Coupling**

The [AD5755-1](#) has four CHARTx pins, corresponding to each of the four output channels. A HART signal can be coupled into these pins and appears on the corresponding current output if that output is enabled. Table 2 shows the recommended input voltages for the HART signal at the CHARTx pin. If these voltages are used, the current output meets the HART amplitude specifications. Figure 8 shows the recommended circuit for attenuating and coupling the HART signals to the [AD5755-1](#) HART inputs.

**Table 2. CHARTx Input Voltage to HART Output Current**

R <sub>SET</sub>	CHARTx Input Voltage (mV p-p)	HART Current Output (mA p-p)
Internal R <sub>SET</sub>	150	1
External R <sub>SET</sub>	170	1

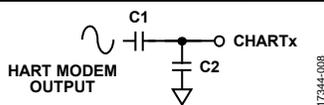


Figure 8. Coupling HART Signal

A minimum capacitance of C1 + C2 is required to ensure that the 1.2 kHz and 2.2 kHz HART frequencies are not significantly attenuated at the output. The recommended values are C1 = 22 nF and C2 = 47 nF. Digitally controlling the slew rate of the output is necessary to meet the analog rate of change requirements for HART.

**Digital Isolation**

The [ADuM3151](#) and [ADuM3482](#) are 3.75 kV quad channel digital isolators in small 20-lead SSOP packages (7.2 mm × 7.8 mm). The isolator core operates between 3.0 V and 5.5 V, whereas the I/O supply can range from 1.8 V to 5.5 V. These devices can be used to interface directly with 1.8 V logic. The [ADuM3151](#) in this design isolates the SPI signals for the [AD5755-1](#) and GPIO controls to control the address lines of the [ADG759](#) quad channel mux, while the [ADUM3482](#) isolates the UART signals for the [AD5700-1](#) HART modem. Stitching capacitance is implemented within the printed circuit board (PCB) itself by overlapping internal planes to reduce EMI radiation and board noise. For more information about EMI mitigation techniques, see the [AN-0971 Application Note, Recommendations for Control of Radiated Emissions with isoPower Devices](#).

**INL and DNL Performance**

The integral nonlinearity (INL) of the [AD5755-1](#) was tested using the transformer isolated switched power supply, as shown in Figure 9. The [AD5755-1](#) data sheet specifies an INL of ±0.006% FSR across the full temperature range for both current output and voltage output, irrespective of whether the internal or an external R<sub>SET</sub> is used. Figure 9 and Figure 10 show that the measured results fall well within this specification.

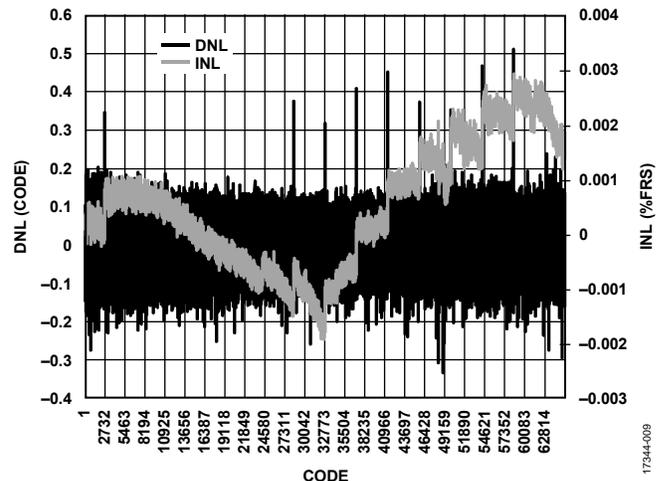


Figure 9. Measured Voltage Output INL/DNL, Channel A

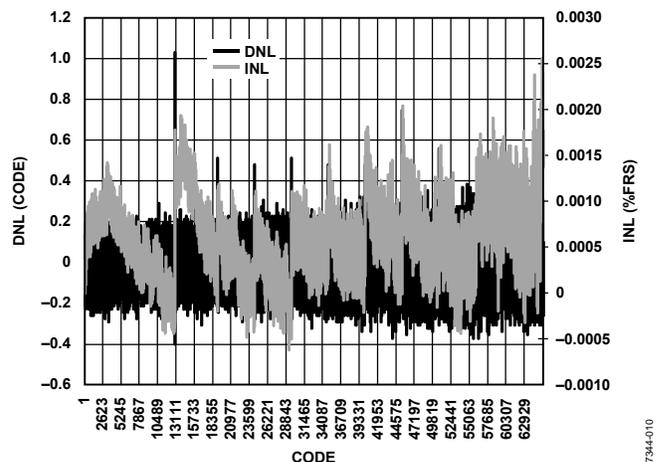


Figure 10. Measured Current Output INL/DNL, Channel A

**Absolute Accuracy Performance**

The specification for the total unadjusted error (TUE) for the [AD5755-1](#) in current output mode using the internal R<sub>SET</sub> is ±0.11% FSR maximum at 25°C. The total error of the [ADRO2](#) reference (B grade) is 0.06% maximum at 25°C.

Table 3 shows the measured current output error of the circuit for Channel A in the 4 mA to 20 mA range with a 500 Ω load using the internal R<sub>SET</sub>. Table 3 summarizes the results for Channel A, using the internal R<sub>SET</sub>, but is indicative of all four channels. All results are within the expected values.

**Table 3. Measured I<sub>OUT\_A</sub> Error (4 mA to 20 mA Range)**

Code	I <sub>OUT</sub> (mA)	Error (% FSR)
0x0000	4.0002	+0.0013
0x4000	7.9994	-0.0038
0x8000	11.9988	-0.0075
0xC000	15.9982	-0.0112
0xFFFF	19.9990	-0.0063

Similar measurements were taken for the voltage output mode, where the AD5755-1 TUE specification is ±0.03% FSR maximum at 25°C. Table 4 shows the results for Channel A. The remaining three channels showed similar results.

**Table 4. Measured V<sub>OUT\_A</sub> Error (±10 V Range)**

Code	V <sub>OUT</sub> (V)	Error (% FSR)
0x0000	-9.996915	-0.000226
0x4000	-8.776362	-0.000179
0x8000	-7.555827	-0.000467
0xC000	5.001719	0.000766
0xFFFF	10.001078	0.001526

**HART Compliance**

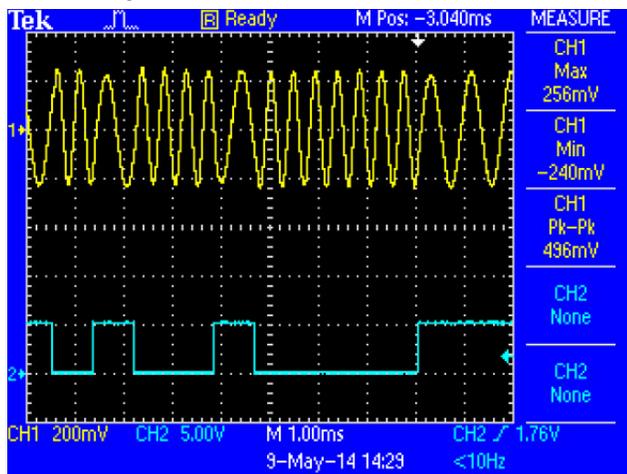


Figure 11. FSK Waveform Measured Across 500 Ω Load

Figure 11 shows the 1200 Hz and 2200 Hz frequency shift keying (FSK) frequencies measured across a 500 Ω load resistor on I<sub>OUT\_A</sub>. Channel 1 shows the modulated HART signal coupled into the AD5755-1 output (set to 4 mA), whereas Channel 2 shows the AD5700-1 TXD signal.

To be HART compliant, the circuit must meet the HART physical layer specifications. Numerous physical layer specifications are included in the HART specification documents. For evaluating the performance of the hardware, the two specifications considered in this circuit note are the output noise during silence and the analog rate of change.

**Output Noise During Silence Test**

When a HART device is not transmitting (silent), it does not couple noise onto the network in the HART extended frequency band. Excessive noise may interfere with reception of HART signals by the device itself or other devices on the network.

The voltage noise measured across a 500 Ω load must contain no more than 2.2 mV rms of combined broadband and correlated noise in the HART extended frequency band. Additionally, the noise must not exceed 138 mV rms outside of this frequency band.

This noise was measured by connecting the HCF\_TOOL-31 filter (available from the HART Communication Foundation) across the 500 Ω load and subsequently connecting the output of the filter to a true rms meter. An oscilloscope was used to examine the output waveform.

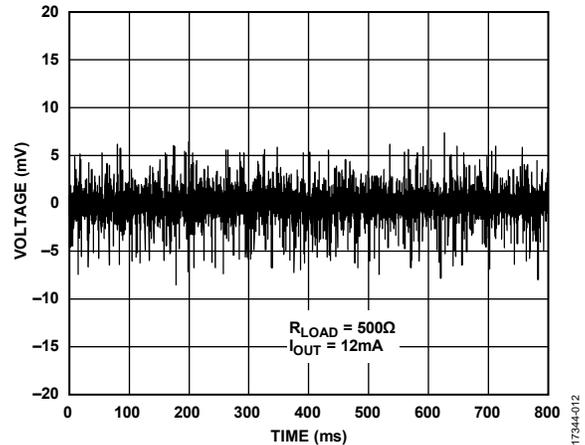


Figure 12. Output Noise During Silence Waveform at Input to HCF\_TOOL-31

**Analog Rate of Change**

This specification ensures that when a device regulates current, the maximum rate of change of analog current does not interfere with HART communications. Step changes in current disrupt HART signaling. The worst case change in the analog output current must not produce a disturbance higher than 15 mV peak, measured across a 500 Ω load in the HART extended frequency band. Meeting this requirement ensures that the maximum bandwidth of the analog signaling is within the specified dc to 25 Hz frequency band.

For this test, the HCF\_TOOL-31 was again connected across the 500 Ω load, as in the noise during silence test, and an oscilloscope was connected to its output. Rather than setting the AD5755-1 output to a fixed output current, however, the AD5755-1 was programmed to output a cyclic waveform, switching from 4 mA to 20 mA. To meet the required system specifications, the output current change was limited by the digital slew rate control feature of the AD5755-1. This feature is described in more detail in the AD5755-1 data sheet. For this test, SR\_CLOCK and SR\_STEP were set to 64 kHz and 16 LSBs, respectively, giving a slew time of 64 ms. The result is shown in Figure 13. Channel 1 shows the AD5755-1 I<sub>OUT\_A</sub> signal stepping between 4 mA and 20 mA, sensed across the 500 Ω load and connected to the input to the band-pass filter. The output of the filter (which has a gain factor of 10) can be seen on Channel 2. The peak value is within the previously mentioned 150 mV peak limits.

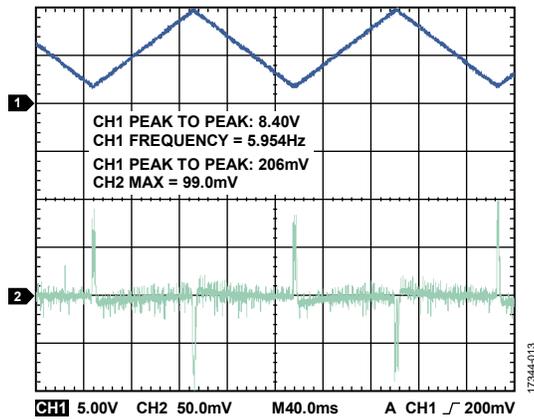


Figure 13. Analog Rate of Change Waveform,  $I_{out\_A}$

## COMMON VARIATIONS

For applications requiring only current outputs, the [AD5757](#) can be used as an alternative to the [AD5755-1](#). If less than 16 bits of resolution is required, the 12-bit [AD5737](#) can be used.

For applications that operate close to or at the maximum current of the [AD5755-1](#), use the power solution shown in [DC2906A](#) demo manual (based on the [LT8302](#)), which provides higher output power.

The [AD5700](#) modem can be used instead of the [AD5700-1](#). However, either an external crystal or a CMOS clock is required because the [AD5700](#) does not have the internal oscillator option provided on the [AD5700-1](#). See the [AD5700](#) data sheet and the [AD5700-1](#) data sheet for further details.

For single channel applications, see [Circuit Note CN0321, Fully Isolated, Single Channel Voltage and 4 mA to 20 mA Output with HART Connectivity](#).

## CIRCUIT EVALUATION AND TEST

The provided software targets the [EVAL-ADICUP3029](#) platform, but it is designed to be easily portable to other microcontroller platforms. When porting to other platforms, be sure to thoroughly review hardware compatibility, including voltage levels and functionality.



Figure 14. EVAL-CN0418-ARDZ board

## Required Equipment

The following equipment is required for operation:

- EVAL-CN0418-ARDZ reference design board
- Serial terminal program such as Tera Term or Putty
- [EVAL-ADICUP3029](#) development board
- PC (Windows® 32-bit or 64-bit)
- 24 V power supply such as Agilent E3631A
- Precision voltage and current meter, such as Agilent 3458A
- Four 500  $\Omega$  precision load resistors
- Oscilloscope (Tektronix TDS2024B or equivalent)
- USB Type A to micro USB Type B
- CN0418 software

## Getting Started

For more information and complete details on setup, reference the [CN0418 user guide](#).

## Software Installation

Follow these steps to install the software:

1. Attach the EVAL-CN0418-ARDZ onto the [EVAL-ADICUP3029](#) board.
2. Connect the [EVAL-ADICUP3029](#) board via the USB port of the PC using the supplied cable.
3. Power up the EVAL-CN0418-ARDZ by applying 24 V to the terminal block P1 connector.
4. Upload the firmware to the [EVAL-ADICUP3029](#).

## Functional Block Diagram

Figure 15 shows a functional block diagram of the test setup.

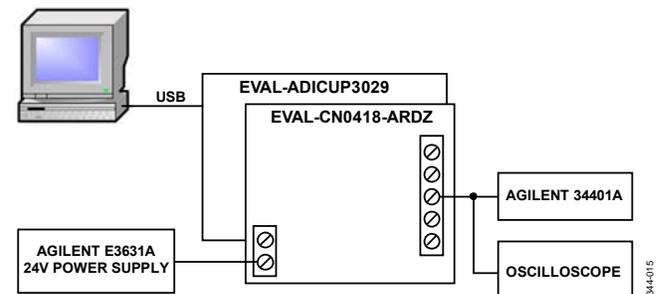


Figure 15. Test Setup Functional Diagram

Follow these basic steps for setup:

1. Connect the EVAL-CN0418-ARDZ to the [EVAL-ADICUP3029](#) as shown in Figure 16.

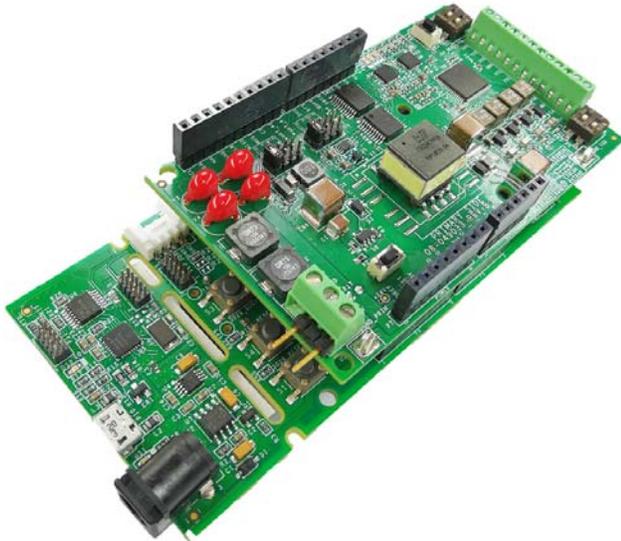


Figure 16. EVAL-CN0418-ARDZ Board Attached to EVAL-ADICUP3029

2. If the jumpers are not already mounted, mount the jumpers provided in the box in the same configuration as shown in Figure 17.

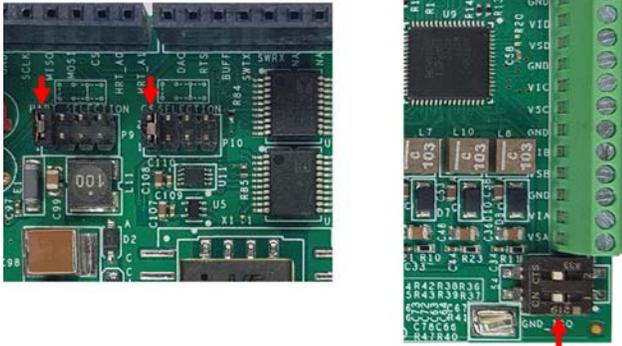


Figure 17. Default Shunt Jumper Position of P9 and P10; Dual Inline Package (DIP) Switch in the On Position

3. Apply 24 V dc to the P17 jumper of the EVAL-CN0418-ARDZ.
4. Connect the micro USB cable from the [EVAL-ADICUP3029](#) to the PC.
5. Open a serial terminal window using a command line interrupter program such as Putty, Telnet, or Tera Term.

For detailed instructions on how to set up the hardware and software to interface with the computer, reference the [CN0418 user guide](#).

## LEARN MORE

[CN-0418 Design Support Package](#).

[CN-0267 Circuit Note, Complete 4 mA to 20 mA Loop Powered Field Instrument with HART Interface, Analog Devices](#).

[CN-0270 Circuit Note, Complete 4 mA to 20 mA HART Solution, Analog Devices](#).

[CN-0278 Circuit Note, Complete 4 mA to 20 mA HART Solution with Additional Voltage Output Capability, Analog Devices](#).

[CN-0321 Circuit Note, Fully Isolated, Single Channel Voltage and 4 mA to 20 mA Output with HART Connectivity, Analog Devices](#).

[CN-0328 Circuit Note, Completely Isolated 4-Channel Multiplexed HART Analog Output Circuit, Analog Devices](#).

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## Data Sheets and Evaluation Boards

[AD5755-1 Data Sheet and Evaluation Board](#).

[AD5700/AD5700-1 Data Sheet and Evaluation Board](#).

[ADG759 Data Sheet](#).

[ADP2441 Data Sheet](#)

[LT8301 Data Sheet](#)

[ADR02 Data Sheet](#)

[ADuM3151 Data Sheet](#)

[ADuM3482 Data Sheet](#)

## REVISION HISTORY

7/2019—Revision 0: Initial Version

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