Low Power, Temperature Compensated Bridge Signal Conditioner and Driver

EVALUATION AND DESIGN SUPPORT

Circuit Evaluation Boards
- CN-0355 Evaluation Board (EVAL-CN0355-PMDZ)
- System Demonstration Platform (EVAL-SDP-CB1Z)
- SDP to PMOD Interposer Board (SDP-PMD-IB1Z)

Design and Integration Files
- Schematics, Layout Files, Bill of Materials

CIRCUIT FUNCTION AND BENEFITS

The circuit in Figure 1 is a complete, low power signal conditioner for a bridge type sensor and includes a temperature compensation channel. This circuit is ideal for a variety of industrial pressure sensors and load cells that operate with drive voltages of between 5 V and 15 V.

The circuit can process full-scale signals from approximately 10 mV to 1 V, using the internal programmable gain amplifier (PGA) of the 24-bit, sigma-delta (Σ-Δ) ADC, making it suitable for a wide variety of pressure sensors.

The entire circuit uses only three ICs and requires only 1 mA (excluding the bridge current). A ratiometric technique ensures that the accuracy and stability of the system does not depend on a voltage reference.

Figure 1. Differential Bridge Type Transducer Monitor with Temperature Compensation (Simplified Schematic: all Connections and Decoupling not Shown)
CIRCUIT DESCRIPTION

The circuit shown in Figure 1 is based on the AD7793, 24-bit, Σ-Δ. It has three differential analog inputs and has an on-chip, low noise PGA with gain that ranges from unity gain to 128, making it ideal for multiple sensor interfaces. The AD7793 consumes a maximum of only 500 μA and is therefore suitable for low power applications. It has a low noise, low drift internal band gap reference and can accept an external differential reference. The output data rate is software programmable from 4.17 Hz to 470 Hz.

The AD8420 low power in-amp with a supply current of 80 μA maximum, can operate up to 36 V single-supply and is used to remove the common voltage at the bridge transducer. It can also provide gain, if needed, to the small differential signal output of the transducer.

The ADA4096-2, dual channel op amp, with a typical supply current of 60 μA per amp and a wide operating input voltage range of up to 30 V, drives the sensor bridge. The other half of the ADA4096-2 is used as a buffer for the reference voltage.

There are a wide variety of pressure sensors requiring a voltage drive between 5 V and 15 V. The circuit shown in Figure 1 provides a complete solution for bridge type transducers and has four critical sections; the transducer voltage drive, the in-amp, the reference buffer, and the ADC.

Bridge Type Transducer Voltage Drive

The ADA4096-2 is configured as a noninverting amplifier with configurable gain set by the feedback resistor, as shown in Figure 2.

![Figure 2. Transducer Voltage Drive](image)

The gain is set by configuring the jumpers indicated in Table 1.

<table>
<thead>
<tr>
<th>Gain</th>
<th>R19/R20/R21/Rf Feedback</th>
<th>P5</th>
<th>P6</th>
<th>P7</th>
</tr>
</thead>
<tbody>
<tr>
<td>5.02</td>
<td>40.2 kΩ</td>
<td>Short</td>
<td>Open</td>
<td>Open</td>
</tr>
<tr>
<td>10.1</td>
<td>91 kΩ</td>
<td>Open</td>
<td>Short</td>
<td>Open</td>
</tr>
<tr>
<td>15</td>
<td>140 kΩ</td>
<td>Open</td>
<td>Open</td>
<td>Short</td>
</tr>
</tbody>
</table>

The transfer function can be computed as follows:

\[
V_{\text{drive}} = V_{\text{ref}} \left( 1 + \frac{R_f}{R_8} \right)
\]

where \( R_f \) can be 40.2 kΩ, 91 kΩ, or 140 kΩ, and \( R_8 = 10 \) kΩ.

An NPN transistor is used to boost the current needed to drive the bridge sensor. Feedback to the inverting input of the ADA4096-2 makes the inverting input voltage equal to the noninverting input voltage, thereby ensuring a constant voltage of the voltage drive across the bridge circuit.

Transistor Q1 is a BJT that has maximum breakdown voltage of 80 V, capable of dissipating 0.35 W at 25°C. The maximum collector current is 500 mA.

Instrumentation Amplifier

The AD8420 rejects the common-mode voltage generated at the bridge and only amplifies the differential bridge voltage, as shown in Figure 3. The AD8420 has rail-to-rail output voltage swing that is completely independent of the input common-mode voltage. This feature exempts the AD8420 from the restrictions caused by the interaction between the common-mode input and output voltages associated with most conventional instrumentation amplifier architectures. The gain of the in-amp is set at unity.

![Figure 3. AD8420 Instrumentation Amplifier](image)

The input to the AD8420 has a differential mode noise filter (20 kΩ/1 μF/100 nF) with a 7.6 Hz bandwidth and a common-mode noise filter (10 kΩ/100 nF) with a 150 Hz bandwidth.

Traditional instrumentation amplifier architectures require the reference pin to be driven with a low impedance source. Any impedance at the reference pin degrades both common-mode rejection ratio (CMRR) and gain accuracy. With the AD8420 architecture, resistance at the reference pin has no effect on CMRR. The transfer function of the AD8420 is

\[
V_{\text{out}} = G (V_{\text{in}+} - V_{\text{in}-}) + V_{\text{ref}}
\]

where:

\[
V_{\text{ref}} = 1.05 \text{ V}
\]

\[
G = 1 + (R_{12}/R_{10})
\]

The AD8420 differential input voltage is internally limited with diodes at ±1 V from −40°C to +85°C. If the input voltage exceeds the limit, the internal diodes start to conduct and draw current. The current is limited internally to a value that is safe for the AD8420.
Reference Buffer

An excitation current of 210 μA, generated by the AD7793, passes through the 5 kΩ resistor, as shown in Figure 4. This generates the 1.05 V reference voltage that is buffered by the ADA4096-2. The output of the buffer drives the reference of the AD7793 and the AD8420. The circuit is ratiometric; therefore, the error due to the variation in the voltage across the 5 kΩ resistor, caused by the 5% tolerance on the 210 μA excitation current from the AD7793, is minimized. The buffered voltage reference also drives the amplifier that sets the voltage drive for the bridge transducer (see Figure 2).

ADC Channel 1 Configuration: Bridge Type Sensor

Channel 1 of the AD7793 measures the bridge sensor output from the AD8420. The external VREF (1.05 V) is used as a reference and therefore, the input range of the AD7793 is ±1.05 V centered on a common-mode voltage of +1.05 V.

ADC Channel 2 Configuration: Temperature Sensor

The second channel of the AD7793 monitors the voltage generated across a resistance temperature detector (RTD), driven by the 210 μA excitation current, as shown in Figure 5. Although 100 Ω platinum RTDs are popular, other resistances (200 Ω, 500 Ω, 1000 Ω, and so on) and materials (nickel, copper, nickel iron) can be specified. For this application, a 100 Ω DIN 43,760 Class A RTD is used.

Table 2. Link Configuration for RTD Connections

<table>
<thead>
<tr>
<th>RTD Connection</th>
<th>P3</th>
<th>P4</th>
</tr>
</thead>
<tbody>
<tr>
<td>2-Wire</td>
<td>Short</td>
<td>Short</td>
</tr>
<tr>
<td>3-Wire</td>
<td>Open</td>
<td>Short</td>
</tr>
<tr>
<td>4-Wire</td>
<td>Open</td>
<td>Open</td>
</tr>
</tbody>
</table>

Link P9 bypasses the RTD if temperature compensation is not required.

Output Coding

The output code for an input voltage on either channel is

\[ \text{Code} = 2^{N-1} \left( \frac{\text{AIN} \times \text{Gain}}{\text{VREF}} + 1 \right) \]

where:

\[ \text{AIN} = \text{AIN}(+) - \text{AIN}(–) = \text{AIN}(+) - \text{VREF} \]

Gain is the PGA gain setting, and \( N = 24 \).

Voltage Supply Requirement

For the circuit to operate properly, the supply voltage, \( V_{CC} \), must be greater than 6 V to provide a minimum 5 V drive for the bridge type transducer.

System Calibration

There are several methods for carrying out pressure sensor temperature calibration. For this application, a four-point calibration procedure was used. A good reference for the calibration procedure is AN13-01, Active Temperature Compensation and Calibration for MEMS Pressure Sensors with Constant Voltage, Silicon Microstructures, Inc., Milpitas, Ca.

Test Data and Results

System Noise

All data capture was taken using the CN-0355 Evaluation Software. Two setup measurements were taken to capture the noise of the board. The first measurement, shown in Figure 6, was taken with the input to the AD8420 shorted, thereby measuring the peak-to-peak noise of the AD8420 and the AD7793. A sample of 1000 was taken; this resulted in a code spread of approximately 100 codes, which translates into a peak-to-peak noise of 12.5 μV, or 17.36 noise free bits for a full-scale span of 2.1 V.
The second measurement was made with a Honeywell NSCSANN600MGUNV gage pressure sensor connected to the evaluation board. This board mounted pressure sensor is unamplified and uncompensated, and the voltage driver was set at 10.1 V. This test effectively shows the noise contributed by the whole system, including the transducer noise, as shown in Figure 7. A sample of 1000 was taken; this resulted in a code spread of approximately 120 codes, which translates into a peak-to-peak noise of 15 μV, or 17.1 noise free bits for a full-scale span of 2.1 V.

**Figure 7. Histogram Showing Output Code Spread of 120 Codes with Pressure Sensor Connected**

### System Current Consumption

Table 3 shows the total current consumption of the system, excluding the current consumed by the pressure transducer.

**Table 3. Maximum Circuit Currents at 25°C**

<table>
<thead>
<tr>
<th>Component</th>
<th>Consumption (mA)</th>
</tr>
</thead>
<tbody>
<tr>
<td>ADA4096-2</td>
<td>0.150</td>
</tr>
<tr>
<td>AD8420</td>
<td>0.080</td>
</tr>
<tr>
<td>AD7793</td>
<td>0.400</td>
</tr>
<tr>
<td>Excitation Current (R6)</td>
<td>0.210</td>
</tr>
<tr>
<td>R19 and R8 Current</td>
<td>0.104</td>
</tr>
<tr>
<td>Total</td>
<td>0.944</td>
</tr>
</tbody>
</table>

The Honeywell NSCSANN600MGUNV pressure sensor has an impedance of about 3 kΩ, which adds approximately 3.36 mA to the total current in Table 3.

The current consumed by the system can be further reduced by driving the RTD with a lower current, such as 10 μA, and at the same time use a higher RTD resistance value, such as 1 kΩ.

### Error Analysis for Active Components

The maximum and root-sum-square (RSS) errors, due to the active components in the system for AD8420 and the ADA4096-2, are shown in Table 4.

**Table 4. System Error Analysis for Full-Scale Range (FSR) = 1.05 V**

<table>
<thead>
<tr>
<th>Error Component</th>
<th>Error Component</th>
<th>Error Value</th>
<th>Error % FSR</th>
</tr>
</thead>
<tbody>
<tr>
<td>AD8420</td>
<td>Offset</td>
<td>250 μV</td>
<td>0.025%</td>
</tr>
<tr>
<td></td>
<td>Gain</td>
<td>0.05%</td>
<td>0.050%</td>
</tr>
<tr>
<td>ADA4096-2 (1/2, G = 10)</td>
<td>Offset</td>
<td>3 mV</td>
<td>0.300%</td>
</tr>
<tr>
<td>ADA4096-2 (1/2, G = 1)</td>
<td>Offset</td>
<td>300 μV</td>
<td>0.030%</td>
</tr>
<tr>
<td>AD7793 (Internal Reference)</td>
<td>Offset</td>
<td>0.01%</td>
<td>0.010%</td>
</tr>
<tr>
<td>RSS Offset</td>
<td></td>
<td></td>
<td>0.060%</td>
</tr>
<tr>
<td>RSS Gain</td>
<td></td>
<td></td>
<td>0.050%</td>
</tr>
<tr>
<td>RSS FSR Error</td>
<td></td>
<td></td>
<td>0.110%</td>
</tr>
<tr>
<td>Maximum Offset</td>
<td></td>
<td></td>
<td>0.365%</td>
</tr>
<tr>
<td>Maximum Gain</td>
<td></td>
<td></td>
<td>0.050%</td>
</tr>
<tr>
<td>Maximum FSR Error</td>
<td></td>
<td></td>
<td>0.415%</td>
</tr>
</tbody>
</table>

### Total Circuit Accuracy

A good approximation of the total error contributed by the resistor tolerances is to assume that each of the critical resistors contributes equally to the total error. The two critical resistors are R8 and any of the R19, R20, or R21 resistors. The worst case resistor tolerance build up of 0.1% yields a total resistor error of 0.2% maximum. If RSS errors are assumed, the total RSS error is 0.1√2 = 0.14%.

Combining the resistor errors with the component errors from Table 4 yields the following results:

- Offset error = 0.365% + 0.1400% = 0.505%
- Gain error = 0.050% + 0.1400% = 0.190%
- Full-scale error = 0.415% + 0.1400% = 0.555%

These errors assume that calculated resistor values are selected, that the only errors are tolerance errors, and that the voltage drive for the transducer is set to a gain of 10.1.

The linearity error was tested over an input range of −500 mV to +500 mV, using the setup shown in Figure 10. The total nonlinearity was approximately 0.45%. The nonlinearity is primarily caused by the input transconductance (gm) stage of the AD8420.
The total output error (%FSR) is calculated by taking the difference between the measured output voltage and the ideal output voltage, dividing by the FSR of the output voltage, and multiplying the result by 100. The results of this calculation are shown in Figure 8.

![Figure 8. Bridge Transducer Simulated Output Voltage (with Associated Linearity Error Plot) vs. ADC Reading](image)

Figure 8 shows a photo of the EVAL-CN0355-PMDZ evaluation board. Complete documentation for the system can be found in the CN-0355 Design Support Package.

**COMMON VARIATIONS**

Other suitable ADCs are the AD7792 and the AD7785. Both devices have the same set of features as the AD7793. However, the AD7792 is a 16-bit ADC, and the AD7785 is a 20-bit ADC.

The AD8237, a micropower, zero drift, true rail-to-rail instrumentation amplifier can also be used for low supply voltage versions of this circuit configuration.

The AD8226 in-amp is another option, when better linearity is needed at a higher current consumption (approximately 525 μA).

For a low supply voltage range application that requires a low noise and offset voltage, a dual channel AD8606 is an alternative to the ADA4096-2. The dual channel AD8606 features very low offset voltage, low input voltage and current noise, and wide signal bandwidth. It uses the Analog Devices, Inc. patented DigiTrim® trimming technique, which achieves superior precision without laser trimming.

**CIRCUIT EVALUATION AND TEST**

This circuit uses the EVAL-CN0355-PMDZ circuit board, the EVAL-SDP-CB1Z System Demonstration Platform (SDP) evaluation board, and the SDP-PMD-IB1Z, which is a PMOD board base interposer for the SDP. The SDP and the SDP-PMD-IB1Z boards have 120-pin mating connectors, allowing for the quick setup and evaluation of the performance of the circuit. To evaluate the EVAL-CN0355-PMDZ board using the SDP-PMD-IB1Z and the SDP, the EVAL-CN0355-PMDZ is connected to the SDP-PMD-IB1Z by a standard 100 mil spaced, 25 mil square, right angle, pin header connector.

**Equipment Required**

The following equipment is needed to evaluate and test the CN-0355 circuit:

- A PC with a USB port and Windows® XP and Windows® Vista (32-bit), or Windows® 7 (32-bit)
- The EVAL-CN0355-PMDZ circuit evaluation board
- The EV AL-SDP-CB1Z circuit evaluation board
- The SDP-PMD-IB1Z interposer board
- The CN0355 Evaluation Software
- A 6 V wall wart or alternate power supply
- The Yokogawa GS200 precision voltage source
- The Agilent E3631A voltage source

**Getting Started**

Load the evaluation software by placing the CN-0355 Evaluation Software CD in the PC. Using My Computer, locate the drive that contains the evaluation software CD and open the Readme file. Follow the instructions contained in the Readme file for installing and using the evaluation software.

**Setup**

The CN-0355 evaluation kit includes self installing software on the a CD. This software is compatible with Windows XP (SP2) and Vista (32-bit and 64-bit). If the setup file does not run automatically, run the setup.exe file from the CD.

Install the evaluation software before connecting the evaluation board and SDP board to the USB port of the PC, to ensure that the evaluation system is correctly recognized when connected to the PC.

1. When installation from the CD is complete, power up the SDP-PMD-IB1Z evaluation board. Using the supplied cable, connect the SDP board (via Connector A) to the SDP-PMD-IB1Z evaluation board and then to the USB port of the PC that will be used for evaluation.
2. Connect the 12-pin, right angle, male pin header of the EVAL-CN0355-PMDZ to the 12-pin, right angle, female pin header of the SDP-PMD-IB1Z.
3. Before running the program, connect the pressure sensor terminal and the RTD sensor to the terminal jacks of the EVAL-CN0355-PMDZ.
4. When all the peripherals and power supply are connected and turned on, by clicking the RUN button on the GUI, and when the evaluation system is successfully detected by the PC, the EVAL-CN0355-PMDZ circuit board can then be evaluated using the evaluation software.
The functional block diagram of the test setup is shown in Figure 10. The test setup must be connected as shown.

The Agilent E3631A and the Yokogawa GS200 precision voltage supplies were used to power up the board and to simulate the sensor output. Channel CH1 of the Agilent E3631A was set at 24 V to serve as the Vcc power supply for the board and the other channel, CH2, was set at 5 V to generate the common-mode voltage. CH2 was connected in series with the Yokogawa GS200, as shown in Figure 7. The Yokogawa was connected to the input terminal of the evaluation board with a 1.5 kΩ series resistor that simulates the impedance of the bridge. The Yokogawa simulates the sensor output by generating ±500 mV at a 25°C differential input voltage at the in-amp input.

The CN-0355 Evaluation Software was used to capture the data for linearity error shown in Figure 8 from the EVAL-CN0355-PMDZ evaluation board, using the setup shown in Figure 10.

Details of the software operation can be found in the CN-0355 Software User Guide.