



Beamforming Technology Advancements for Phased Array Radar Systems

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Agenda

Phased array radar market trends

RF front-end ICs dictate radar performance

Beamforming technology advancements

ADI beamforming IC solutions

Takeaways



**The human spirit must
prevail over technology.**

Albert Einstein

Albert Einstein

Phased Array Radar Market Trends

	Projected 2030 Market Size	CAGR
Conventional Radar	\$8B to 9B*	4% to 5%*
Active Phased Array Radar	\$13B ¹ to 15.94B ²	8.7% ¹ to 9.79% ²



PLATFORMS

Airborne
Naval
Ground
Space Based

FREQUENCY BANDS

S-Band
X-Band
L-Band
C-Band
Others (Ku-, Ka-, E-Bands)

APPLICATIONS

Surveillance
Weather Monitoring
Air Traffic Control
Space Situational Awareness
Automotive & Industrial

TECHNOLOGY DRIVERS

GaN Power Amplifiers
Highly integrated BFICs
Multi-Ch. Data Converters
Integration of AI/ML for Target Recognition & Feature Enhancements

* Copilot summary

¹ Active Phased Array Radar Market Report 2030 by Strategic Market Research (Copilot summary)

² Global Active Phased Array Radar Market Size Study ... Forecasts 2022-2032: GII Research (Copilot summary)

Radar: Radio Detection and Ranging: Maximizing Range

For a phased array radar antenna with N elements:

$$P_r = \frac{P_t N^2 G_e^2 \lambda^2 \sigma}{(4\pi)^3 R^4}$$

$$\text{SNR} = \frac{P_t N^2 G_e^2 \lambda^2 \sigma}{(4\pi)^3 R^4 k T_s B L}$$

$$R_{\max} = \left[\frac{P_t N^2 G_e^2 \lambda^2 \sigma}{(4\pi)^3 k T_s B L \text{SNR}_{\min}} \right]^{1/4}$$

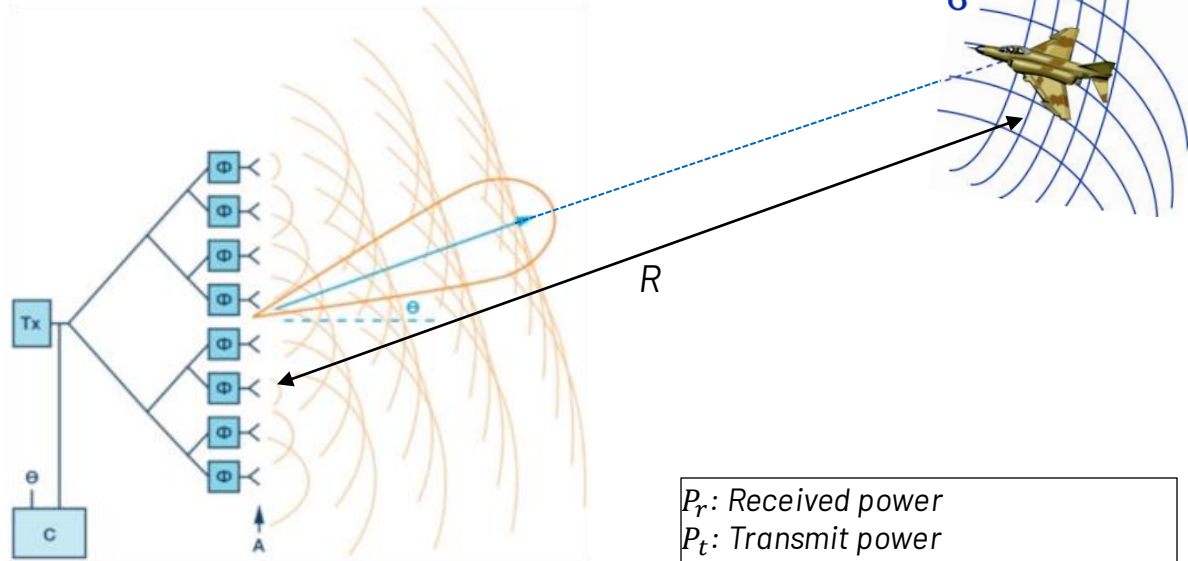
Range scales as $\sqrt{N}$, $1/4$ power of P_t & inverse $1/4$ power of T_s

For large range:

Increase array size

Increase Tx Power

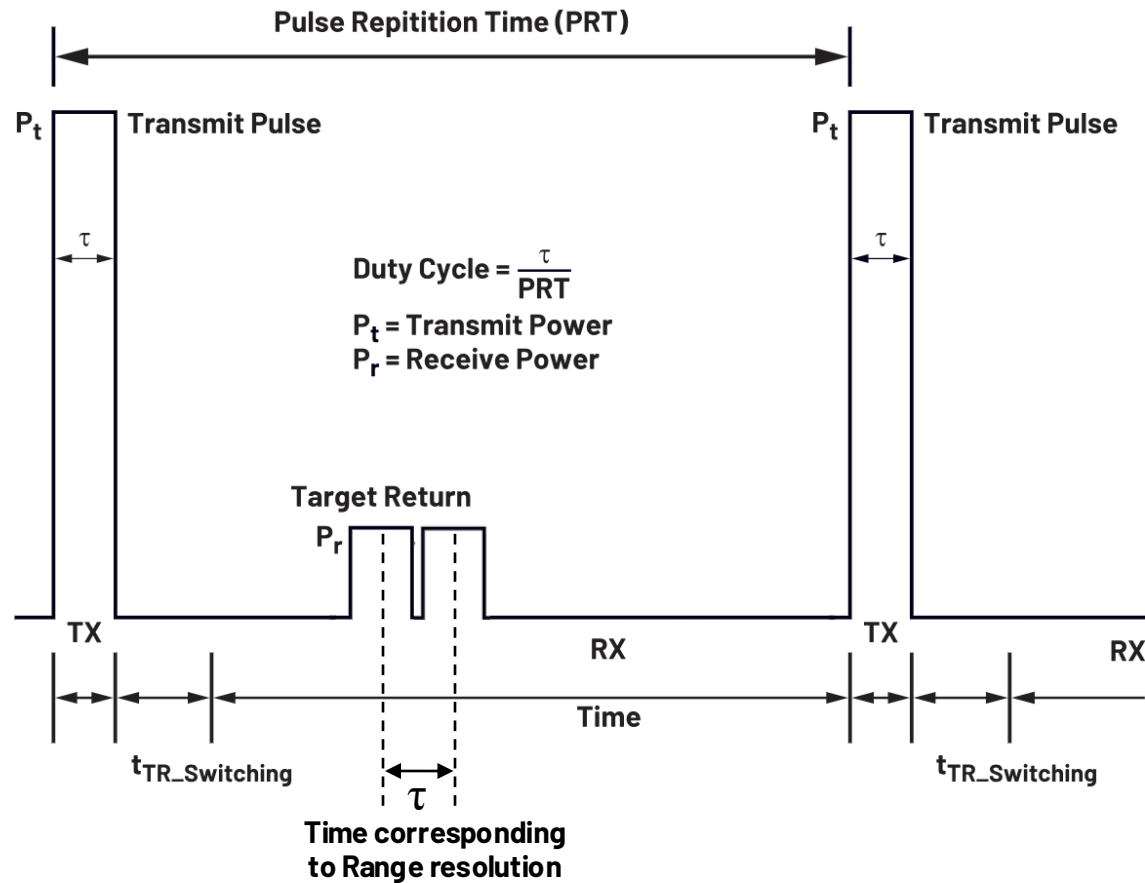
Improve Rx Noise Figure



P_r : Received power
 P_t : Transmit power
 G_e : Antenna element gain
 N : Number of elements
 λ : Wavelength
 σ : Radar cross section (RCS)
 R : Range
 T_s : System noise temperature
 B : Noise bandwidth
 L : System losses

*Beamforming ICs Simplify Phased Array Antenna Design: Keith Benson, ADI (Microwave Journal)

How Timing Affects Performance: Blind Range and Resolution



Minimum detectable range (blind range) $= (\tau + t_{\text{TR_Switching}}) \times (c/2)$

- Pulse width and T/R switching time of $0.1\mu\text{s}$ each results in a **blind range** of 30m

Range resolution, $\Delta R = \tau \times (c/2)$

- $0.1\mu\text{s}$ pulse width results in range resolution of 15m
- Shorter pulse improves resolution, longer pulse improves SNR

Pulse compression breaks this trade-off

Compression Ratio (CR) $= B \cdot T$; where $B = \text{BW}$, $T = \text{pulse duration}$

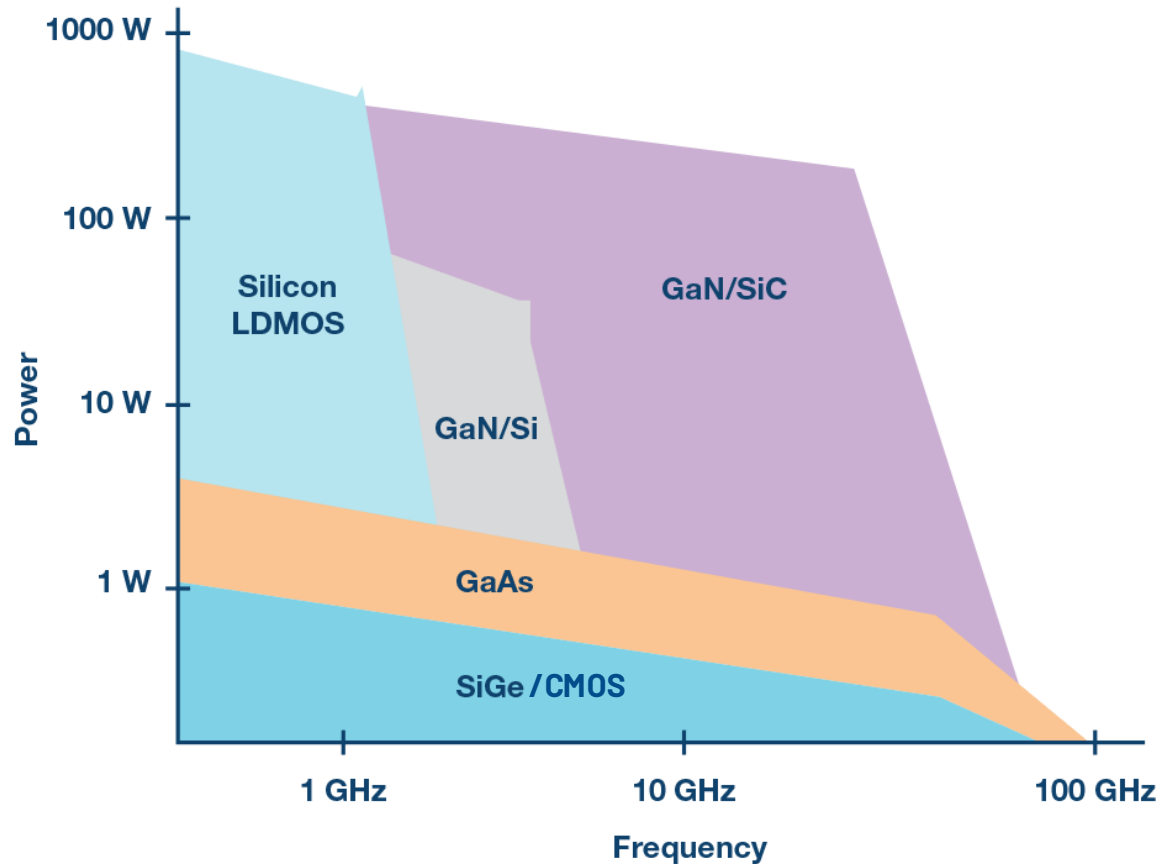
Processing gain, $G = B \cdot T \Rightarrow 10\log_{10}(BT)$ dB

$\tau_{\text{compressed}} \approx \frac{1}{B}$; Range resolution $\Delta R = \frac{c}{2B}$

For shorter blind range & better resolution

- **Reduce T/R switching time**
- **Employ pulse compression**

Process Technologies for Radar Front-End ICs



Combination of high frequency and high power is not achievable on Si technologies

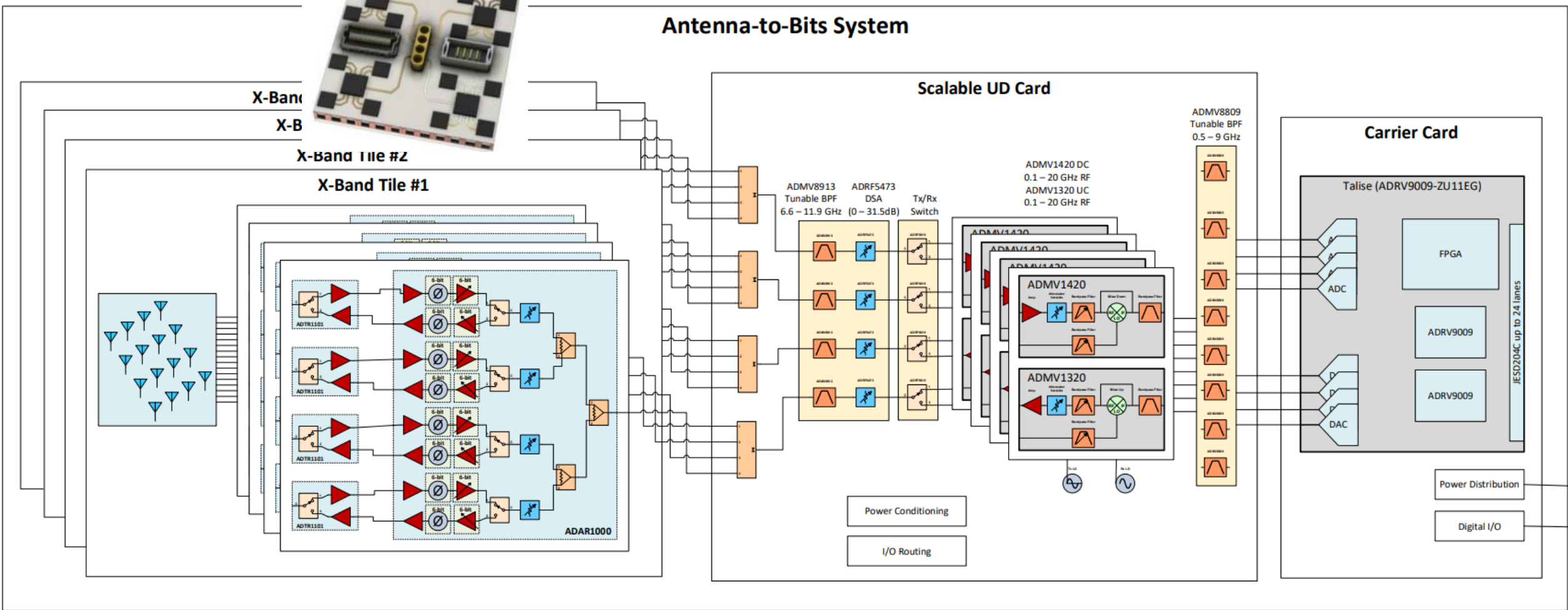
- Fine line, high-speed devices have lower breakdown voltages
- Power combining reduces efficiency
- Si is excellent for beamforming ICs needing high level of integration and moderate transmit output power

GaN is a better technology for high-power applications

GaAs LNAs for better noise figure

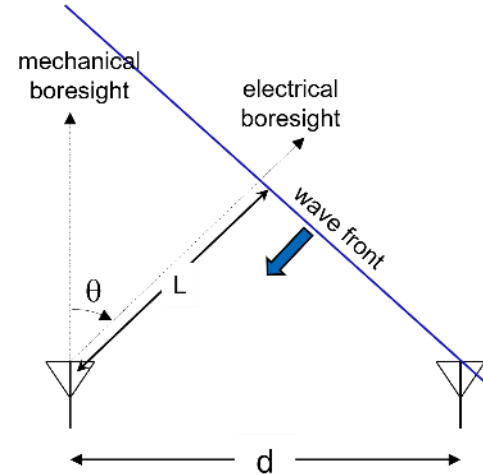
CMOS SOI for high-power T/R switches

Hybrid Beamforming: High-Level Block Diagram



TRM (ADTR1101) BFIC (ADAR1000) ADI tunable filter, Att. & Sw. UDCs (ADMV1320/1420) Multi-ch. ADC/DAC

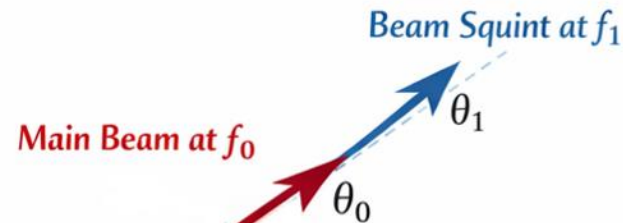
Beamforming: Time Delay vs. Phase Shifter: Beam Squint



Θ : beam steering angle
 Δt : incremental time delay between elements
 $\Delta\phi$: incremental phase shift between elements
 L : incremental propagation distance between elements
 d : distance between elements
 c : speed of light

$$L = d \sin \theta$$

Phase Shifters



Time Delay Units



$$L = d \sin \theta$$

For time delay between elements:
 $\Delta t = L/c$
 $\Delta t = d \sin \theta / c$

Solving for θ :
 $\theta = \arcsin(\Delta t c / d)$

For phase shift between elements:
 $\Delta\phi = 2\pi L / \lambda = 2\pi f L / c$
 $\Delta\phi = 2\pi f d \sin \theta / c$

Solving for θ :
 $\theta = \arcsin(\Delta\phi c / 2\pi f d)$

Beamformer Technology Advancements

Low power consumption

Passive TDU/phase shifters and DSA

Wider RF bandwidth for multifunction arrays

High transmit output power, low noise figure

High-channel count to enable dual polarized antennas

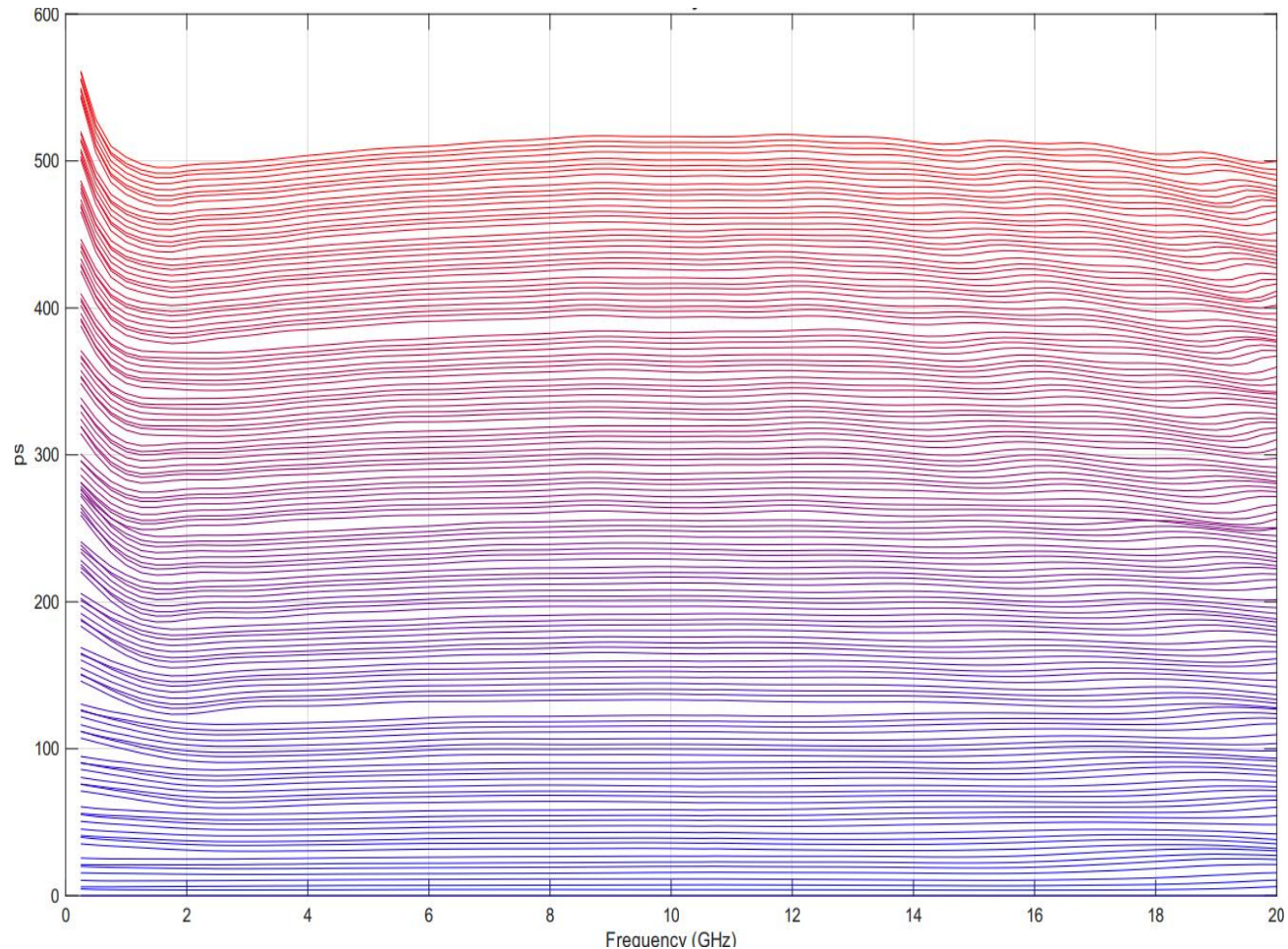
Integrated fast switching gate drivers

Integrated receiver limiters

On-chip beam state memory for faster scanning

Better thermals with WLCS packaging

ADAR4002 (0.5GHz to 19GHz, 508ps TDU) Time Delay Response



Packaging Advancements: Embedded Package

Interconnect evolution

Gold wire → Cu wire → Solder ball interconnect → Cu pillar interconnect → ?

Interconnect without interconnect: embedded package

Embedded package advantages

Functionalizing the substrate

- Vertical connection with reduced length (parasitic resistance and inductance)

Alternative to the flip-chip package

- EM improvement
- Flexible die connection design and placement

Reduced footprint of a package

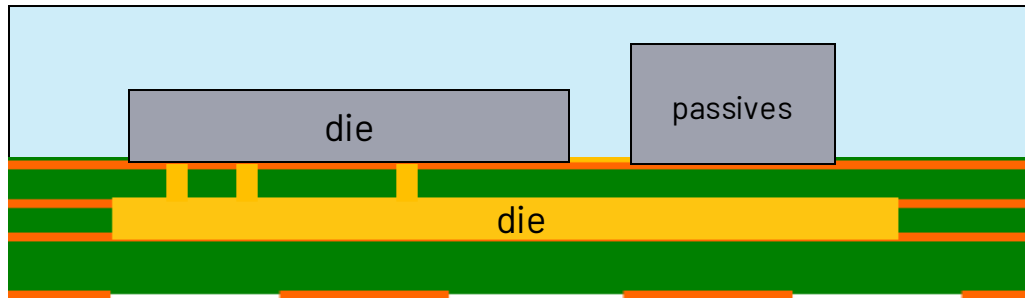
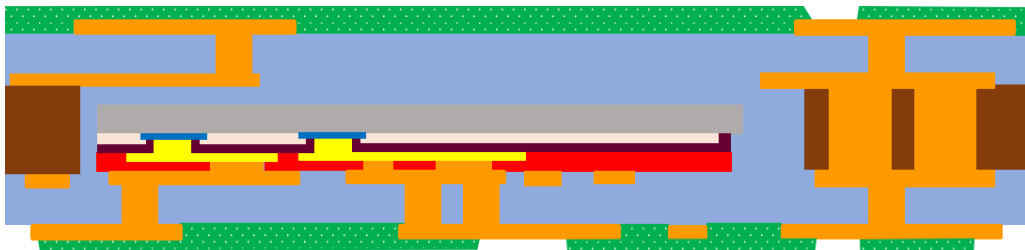


Illustration of an embedded package with die-to-die vertical connection



Details of a typical embedded substrate

ADI Beamforming IC products

Radar/TDD



ADAR1000

Half-Duplex
X- and Ku-Band (8GHz to 16GHz)
1×4 T/R BFIC

Wideband TDU



ADAR4002

0.5GHz to 19GHz,
Bidirectional
508psec TDU



ADAR4000/ADAR4001

2GHz to 18GHz, 508psec
TDU, 1×4 Full Duplex Tx/Rx
BFICs

T/R Modules



ADTR1101

Freq: 8GHz to 12GHz
Tx Pout: 37dBm (5W)
Pkg: 5mm × 5mm LGA



ADTR1104

Freq: 8GHz to 12GHz
Tx Pout: 39.5dBm (9W)
Pkg: 5mm × 5mm LGA



ADTR1107

Freq: 6GHz to 18GHz
Tx Pout: 25dBm
Pkg: 5mm × 5mm LGA

Satcom Payloads



ADAR3006/ADAR3007

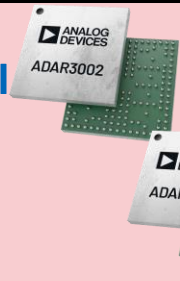
Ku Band Full Duplex
16 Channels, 4×4
ADAR3006: 10.7GHz to
12.75GHz
ADAR3007: 13.75GHz
to 14.6GHz



ADAR3000/ ADAR3001

Ka-Band Full Duplex
16 Channels, 4×4
ADAR3000: 17GHz to
22GHz
ADAR3001: 27GHz
to 31GHz

Satcom Terminal



ADAR3002/ADAR3003

Ka Band Full Duplex
ADAR3002: 17GHz to 21GHz
(RX)
16 Channels, 8×2
ADAR3003: 27GHz to 31GHz
(TX)
8 Channels, 1×8



ADMV4680

Satcom Ku-
Band 1×4
T/R BFIC

Comms. T/R BFICs



ADMV48281

24GHz to
30GHz
2×8 T/R BFIC



ADMV1228

24GHz to 30GHz
2×8 UDC + BFIC



ADMV49281

37GHz to
44GHz 2×8
T/R BFIC

Wilkinson Power Combiner/Splitter



ADAR5000

4 - Way Wilkinson
17GHz to 32GHz



ADAR5001

2 - Way Wilkinson
10GHz to 40GHz

Takeaways and Future Trends

APAR is the backbone of modern airborne, naval, ground-based, weather and spaceborne radars

- Multiple simultaneous beams and modes - search, track, imaging
- Adaptive patterns: interferer nulling, sidelobe shaping

Miniaturized front-end electronics enables scalable flat panel arrays

- GaN amplifiers and high-channel count Beamformer ICs

Digital beamforming and signal processing breakthroughs

- ML/AI assisted target recognition, clutter suppression, and adaptive beam steering

Emerging application and active research areas

- SAR (Synthetic Aperture Radar) for:
 - Defense ISR applications on UAVs and satellites
 - Terrain structural information for mineral exploration, oil spill boundaries on water, sea, and ice hazard maps
- Rapid volume scanning using AESA for fast-evolving storms, tornado genesis, and microbursts

Parting thought:

“Our scientific power has outrun our spiritual power. We have guided missiles and misguided men.” — Dr. Martin Luther King Jr.