

## 18V, 1A Step-Down Silent Switcher 3 with Ultra-Low Noise Reference

### FEATURES

- ▶ **Silent Switcher® 3 Architecture**
  - ▶ **Ultra-Low RMS Noise (10Hz to 100kHz):  $4\mu\text{V}_{\text{RMS}}$**
  - ▶ **Ultra-Low Spot Noise:  $4\text{nV}/\sqrt{\text{Hz}}$  at 10kHz**
  - ▶ **Ultra-Low EMI Emissions**
- ▶ **Ultra-Fast Transient Response**
  - ▶ **<1 $\mu\text{s}$  Transient Recovery Time**
- ▶ **High Efficiency at High Frequency**
  - ▶ **Up to 94% Efficiency at 2MHz, 12V<sub>IN</sub> to 5V<sub>OUT</sub>**
  - ▶ **Up to 92% Efficiency at 4MHz, 12V<sub>IN</sub> to 5V<sub>OUT</sub>**
- ▶ **Input Voltage Range: 2.8V to 18V**
- ▶ **Output Voltage Range: 0V to (V<sub>IN</sub> – 0.5V)**
  - ▶ **Unity Gain Configuration up to 13V Output**
- ▶ **Maximum Continuous Output Current: 1A**
- ▶ **Fast Minimum Switch On-Time: 13ns**
- ▶ **Adjustable and Synchronizable: 300kHz to 6MHz**
- ▶ **Precision Reference:  $\pm 0.6\%$  Over Temperature with Remote Sense**
- ▶ **Pin Selectable Forced Continuous Mode (FCM) or Discontinuous Conduction Mode (DCM) During Operation**
- ▶ **Full Frequency Discontinuous Conduction at Light Loads in DCM for Higher Efficiency and Predictable Noise**
- ▶ **Supports *Dynamic Output Voltage Control***
- ▶ **Programmable Power Good**
- ▶ ***Tiny 15-Lead 3mm × 2mm LFCSP* Package**
- ▶ **Pin-to-Pin Compatible Family: LT83201 (1A), LT83203 (3A), LT83205 (5A)**

### TYPICAL APPLICATION

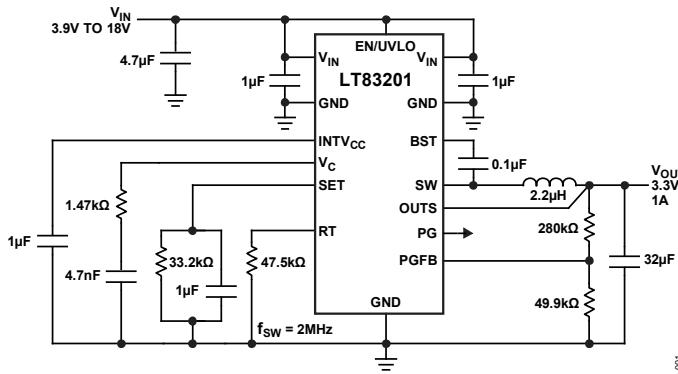


Figure 1. LT83201 Application Diagram

### GENERAL DESCRIPTION

The **LT®83201** synchronous step-down regulator is uniquely designed to combine an ultra-low noise reference with Silent Switcher architecture to achieve both high efficiency and excellent wideband noise performance.

The innovative ultra-low noise architecture allows exceptional low-frequency (0.1Hz to 100kHz) output noise performance in a switching regulator. The output voltage can be programmed with a single resistor, resulting in virtually constant output noise independent of output voltage.

Silent Switcher architecture minimizes EMI emissions while delivering high efficiency at high switching frequencies.

The LT83201 is ideal for noise-sensitive applications which benefit from the high efficiency of a synchronous switching regulator.

### APPLICATIONS

- ▶ RF Power Supplies: PLLs, VCOs, Mixers, LNAs, PAs
- ▶ Low Noise Instrumentation
- ▶ High Speed/High Precision ADCs/DACs
- ▶ General Purpose Power Supply

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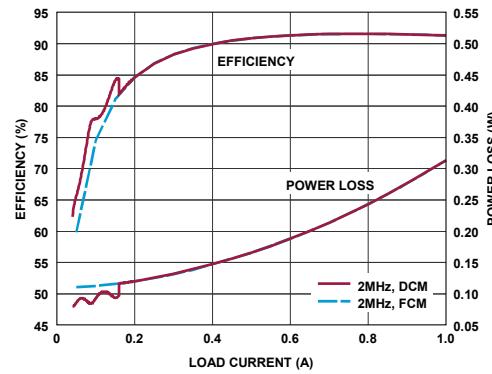


Figure 2. 12V to 3.3V Efficiency

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## REVISION HISTORY

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGE NUMBER
0	4/25	Initial release	—
A	6/25	Updated the Electrical Characteristics table Updated the Related Parts table	4, 5 43

## SPECIFICATIONS

Table 1. Electrical Characteristics

( $T_J = -40^\circ\text{C}$  to  $+125^\circ\text{C}$ , unless otherwise noted. Typical values are at  $T_A = +25^\circ\text{C}$ . All voltages are referenced to GND, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS/COMMENTS	MIN	TYP	MAX	UNITS
Minimum $V_{IN}$	$V_{IN}$	$V_{SET} = 1\text{V}$		2.5	2.8	V
SET Pin Current ( $I_{SET}$ )	$I_{SET}$	$V_{SET} = V_{OUTS} = 1\text{V}$ , $T_A = +25^\circ\text{C}$	99.85	100	100.15	$\mu\text{A}$
		$V_{SET} = V_{OUTS} = 1\text{V}$	99.4	100	100.6	
Fast Start-Up Set Pin Current	$I_{FAST\_STARTUP}$	$V_{IN} = 12\text{V}$ , $V_{SET} = 1\text{V}$ , $T_A = +25^\circ\text{C}$	2.0	2.7	3.2	mA
Start-Up Time Without Fast Start-Up <sup>1,2</sup>	$t_{STARTUP}$	$V_{OUT} = 1\text{V}$ , $C_{SET} = 1\mu\text{F}$ , $V_{IN} = 12\text{V}$ , $V_{PGFB} = 0.5\text{V}$		25		ms
		$V_{OUT} = 1\text{V}$ , $C_{SET} = 4.7\mu\text{F}$ , $V_{IN} = 12\text{V}$ , $V_{PGFB} = 0.5\text{V}$		120		
Start-Up Time With Fast Start-Up <sup>1,2</sup>	$t_{STARTUP}$	$V_{OUT} = 1\text{V}$ , $C_{SET} = 1\mu\text{F}$ , $V_{IN} = 12\text{V}$ , $R_{PGFB(TOP)} = 49.9\text{k}\Omega$ , $R_{PGFB(BOT)} = 49.9\text{k}\Omega$		1		ms
		$V_{OUT} = 1\text{V}$ , $C_{SET} = 4.7\mu\text{F}$ , $V_{IN} = 12\text{V}$ , $R_{PGFB(TOP)} = 49.9\text{k}\Omega$ , $R_{PGFB(BOT)} = 49.9\text{k}\Omega$		2.5		
Output Noise Spectral Density (10kHz) <sup>1,3,4</sup>	$V_{O,NSD(10\text{kHz})}$	$V_{IN} = 12\text{V}$ , $V_{OUT} = 3.3\text{V}$ , $C_{OUT} = 46.4\ \mu\text{F}$ , $L = 0.82\mu\text{H}$ , $R_{SET} = 33.2\text{k}\Omega$ , $C_{SET} = 1.1\mu\text{F}$ , $f_{SW} = 6\text{MHz}$ , $R_C = 1.74\text{k}\Omega$ , $C_C = 3.3\text{nF}$		4		nV/ $\sqrt{\text{Hz}}$
Output RMS Noise (10Hz to 100kHz) <sup>1,3,4</sup>	$V_{O,RMS}$	$V_{IN} = 12\text{V}$ , $V_{OUT} = 3.3\text{V}$ , $C_{OUT} = 46.4\ \mu\text{F}$ , $L = 0.82\mu\text{H}$ , $R_{SET} = 33.2\text{k}\Omega$ , $C_{SET} = 1.1\mu\text{F}$ , $f_{SW} = 6\text{MHz}$ , $R_C = 1.74\text{k}\Omega$ , $C_C = 3.3\text{nF}$		2.08		$\mu\text{V}_{\text{RMS}}$
$V_{IN}$ Quiescent Current	$I_Q$	$V_{EN/UVLO} = 2\text{V}$ , Not Switching, $T_A = +25^\circ\text{C}$		2.7	3.6	mA
		$V_{EN/UVLO} = 0.2\text{V}$ , Shutdown, $T_A = +25^\circ\text{C}$		40	60	$\mu\text{A}$
Oscillator Frequency	$f_{SW}$	$R_T = 392\text{k}\Omega$	270	300	330	kHz
		$R_T = 47.5\text{k}\Omega$	1.93	2	2.07	MHz
		$R_T = 9.76\text{k}\Omega$	5.4	6	6.6	
PGFB Upper Threshold	$V_{PGH}$	$V_{PGFB}$ Rising	529	537.5	546	mV
PGFB Upper Threshold Hysteresis	$V_{PGH\_HYS}$			10		mV
PGFB Lower Threshold	$V_{PGL}$	$V_{PGFB}$ Falling	455	462.5	470	mV
PGFB Lower Threshold Hysteresis	$V_{PGL\_HYS}$			10		mV
PGFB Lower Threshold (Start-Up only)	$V_{PGL\_STARTUP}$	$V_{PGFB}$ Rising	479	486.5	495	mV
PGFB Pin Current	$I_{PGFB}$	$V_{EN/UVLO} = 3\text{V}$ , $V_{PGFB} = 0.5\text{V}$		12		nA
PG Leakage	$I_{PG\_LKG}$	$V_{PG} = 3.3\text{V}$ , $T_A = +25^\circ\text{C}$	-40	40		nA
PG Pull-Down Resistance	$R_{PG}$	$V_{PG} = 0.5\text{V}$	380	1200		$\Omega$

( $T_J = -40^\circ\text{C}$  to  $+125^\circ\text{C}$ , unless otherwise noted. Typical values are at  $T_A = +25^\circ\text{C}$ . All voltages are referenced to GND, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS/COMMENTS	MIN	TYP	MAX	UNITS
SET Pull-Down Resistance	$R_{\text{SET-PULLDOWN}}$	$V_{\text{SET}} = 0.5\text{V}$		520	850	$\Omega$
SYNC/MODE Threshold	$V_{\text{IL}}$	SYNC/MODE DC and Clock Low Level Voltage	0.7			V
	$V_{\text{IH}}$	SYNC/MODE DC and Clock High Level Voltage			1.5	
OUTS Pin Output Current	$I_{\text{OUTS}}$	$V_{\text{SET}} = V_{\text{OUTS}} = 1\text{V}$ , $T_A = +25^\circ\text{C}$	80	160	240	nA
Output Voltage Line Regulation <sup>5</sup>	$\Delta V_{\text{OUT(LINE)}}$	$V_{\text{IN}} = 4\text{V}$ to $18\text{V}$ , $T_A = +25^\circ\text{C}$		0.001	0.01	%/V
Error Amp Offset <sup>5,6</sup>	$V_{\text{EA, OFFSET}}$	$V_C = 1.2\text{V}$ , $V_{\text{SET}} = 3\text{V}$ , $V_{\text{IN}} = 12\text{V}$ , PNP-Based Input Pair	-2	2		mV
		$V_C = 1.2\text{V}$ , $V_{\text{SET}} = 5\text{V}$ , $V_{\text{IN}} = 5.7\text{V}$ , NPN-Based Input Pair	-2	2		
Error Amp Transconductance <sup>6</sup>	$g_{\text{m(EA)}}$	$V_C = 1.2\text{V}$ , $V_{\text{SET}} = 1\text{V}$ , $V_{\text{IN}} = 12\text{V}$ , PNP-Based Input Pair, $T_A = +25^\circ\text{C}$	9.5	12	14.5	mS
		$V_C = 1.2\text{V}$ , $V_{\text{SET}} = 5\text{V}$ , $V_{\text{IN}} = 5.7\text{V}$ , NPN-Based Input Pair, $T_A = +25^\circ\text{C}$	8.3	10.5	12.7	
Error Amp Gain	$A_V$	$V_C = 1.2\text{V}$ , $V_{\text{SET}} = 1\text{V}$ , $V_{\text{IN}} = 6\text{V}$		2800		V/V
$V_C$ Source Current <sup>6</sup>	$I_{\text{VC-SRC}}$	$V_C = 1.2\text{V}$ , $V_{\text{SET}} = 1\text{V}$ , $V_{\text{IN}} = 12\text{V}$ , PNP-Based Input Pair		330		$\mu\text{A}$
		$V_C = 1.2\text{V}$ , $V_{\text{SET}} = 5\text{V}$ , $V_{\text{IN}} = 6\text{V}$ , NPN-Based Input Pair		330		
$V_C$ Sink Current <sup>6</sup>	$I_{\text{VC-SNK}}$	$V_C = 1.2\text{V}$ , $V_{\text{SET}} = 1\text{V}$ , $V_{\text{IN}} = 12\text{V}$ , PNP-Based Input Pair		330		$\mu\text{A}$
		$V_C = 1.2\text{V}$ , $V_{\text{SET}} = 5\text{V}$ , $V_{\text{IN}} = 6\text{V}$ , NPN-Based Input Pair		330		
$V_C$ Clamp Voltage	$V_{\text{C-CLAMP}}$			2.2		V
Minimum On-Time	$t_{\text{ON(MIN)}}$	$I_{\text{LOAD}} = 1\text{A}$		13	18	ns
Minimum Off-Time	$t_{\text{OFF(MIN)}}$	$I_{\text{LOAD}} = 1\text{A}$		70	90	ns
$V_C$ Pin to Switch Current Gain	$G_M$			2.3		A/V
Top Power N-Channel MOSFET Current Limit	$I_{\text{PEAK-LIMIT}}$		2.4	2.9	3.2	A
Bottom Power N-Channel MOSFET Current Limit	$I_{\text{VALLEY-LIMIT}}$		1.35	1.7	2.05	A
SW Leakage Current	$I_{\text{SW-LKG}}$	$V_{\text{IN}} = 18\text{V}$ , $V_{\text{SW}} = 0\text{V}$ , $18\text{V}$ , $T_A = +25^\circ\text{C}$	-1	1		$\mu\text{A}$
Power MOSFET On-Resistance Main Switch (Top)	$R_{\text{DS-ONH}}$			150		$\text{m}\Omega$

( $T_J = -40^\circ\text{C}$  to  $+125^\circ\text{C}$ , unless otherwise noted. Typical values are at  $T_A = +25^\circ\text{C}$ . All voltages are referenced to GND, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS/COMMENTS	MIN	TYP	MAX	UNITS
Power MOSFET On-Resistance Synchronous Switch (Bottom)	$R_{DS-ONL}$			154		$\text{m}\Omega$
Hiccup Timer	$t_{HICC}$	$T_A = +25^\circ\text{C}$		1.7		$\text{ms}$
EN/UVLO Threshold	$V_{ENR}$	EN/UVLO Rising	0.7	0.75	0.8	$\text{V}$
EN/UVLO Hysteresis	$V_{EN\_HYS}$			50		$\text{mV}$
EN Delay Timer <sup>1,9</sup>	$t_{EN\_DELAY}$	$V_{IN} = 12\text{V}$ , $C_{VCC} = 1\mu\text{F}$ , $R_C = 1.24\text{k}\Omega$ , $C_C = 4.7\text{nF}$ , $C_{SET} = 1\mu\text{F}$		114		$\mu\text{s}$
EN/UVLO Input Current	$I_{EN}$	$V_{EN/UVLO} = 2\text{V}$ , $T_A = +25^\circ\text{C}$	-40		40	$\text{nA}$

<sup>1</sup> Not subject to production test.

<sup>2</sup> The start-up time is defined as the time it takes from the EN/UVLO pin rising above the EN/UVLO threshold to when  $V_{OUT}$  has reached 90% of final value.

<sup>3</sup> OUTS ties directly to  $V_{OUT}$ .

<sup>4</sup> Adding a capacitor across the SET pin resistor decreases output voltage noise. Adding this capacitor bypasses the SET pin resistor's thermal noise as well as the reference current's noise. Use of a SET pin bypass capacitor also increases start-up time.

<sup>5</sup> The LT83201 is tested in a feedback loop that servos  $V_C$  to a specified voltage and measures the resultant  $V_{OUTS}$ .

<sup>6</sup> The PNP-based input pair is active for the error amplifier as long as  $V_{IN}$  is at least 1.4V above  $V_{SET}$ . As  $V_{IN}$  drops to less than 1.4V above  $V_{SET}$ , the part gradually transitions to operating with the NPN-based input pair active.

<sup>7</sup> Thermal Resistance ( $\theta$ ) values determined per JEDEC 51-7, 51-12. For information on improving the thermal resistance and for actual temperature measurements of a demo board in typical operating conditions, see the *Applications Information* section.

<sup>8</sup> This IC includes overtemperature protection that is intended to protect the device during overload conditions. Junction temperature exceeds  $150^\circ\text{C}$  temperature when overtemperature protection is active. Continuous operation above the specified maximum operating junction temperature reduces lifetime.

<sup>9</sup> EN Delay Timer is the time from EN/UVLO high to first switching cycle.

## ABSOLUTE MAXIMUM RATINGS

$T_A = 25^\circ\text{C}$ , unless otherwise specified.

**Table 2. Absolute Maximum Ratings**

PARAMETER	RATING
$V_{IN}$ , EN/UVLO, PG	-0.3V to 18V
OUTS, SET	-0.3V to 13V
SYNC, PGFB	-0.3V to 6V
Operating Junction Temperature	-40°C to 125°C
Storage Temperature Range	-65°C to 150°C
Peak Package Body Temperature	260°C

Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

## PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS

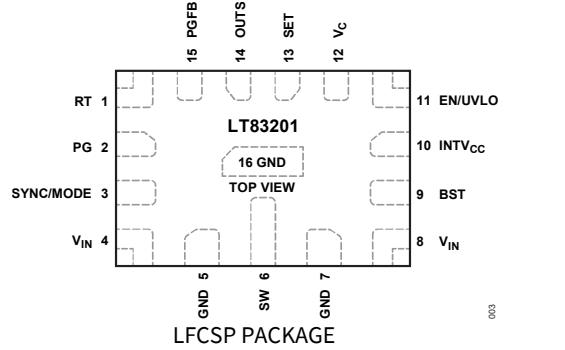


Figure 3. Pin Configurations

Table 3. Pin Descriptions

PIN	NAME	DESCRIPTION
1	RT	A resistor is connected between the RT pin and ground to set the switching frequency.
2	PG	The PG pin is the open-drain output of an internal comparator. PG pulls low until the PGFB pin is within $\pm 7.5\%$ of 0.5V, and there are no fault conditions. PG is also pulled low when EN/UVLO is below 0.75V, INTV <sub>cc</sub> has fallen too low or during thermal shutdown. PG is valid when V <sub>IN</sub> is above 2.8V.
3	SYNC/MODE	For the LT83201, this pin programs three different operating modes: 1) Discontinuous Conduction Mode: Connect this pin to GND for Discontinuous Conduction Mode (DCM) to allow the part to operate in discontinuous mode at light loads for improved efficiency. In this mode, the part may skip pulses at very light loads or very high duty cycles to maintain regulation. 2) Forced Continuous Mode (FCM): This mode offers fast transient response and full frequency operation over a wide load range. Connect this pin high to INTV <sub>cc</sub> (~3.4V) or an external supply >1.5V for FCM. The part also operates in this mode by default if this pin is left floating. 3) Synchronization Mode: Drive this pin with a clock source to synchronize to an external frequency. During synchronization, the part operates in forced continuous mode. Contact the factory for versions of this part that replaces the SYNC/MODE pin with a CLKOUT pin. The CLKOUT pin would provide a 50% duty-cycle square wave of the switching frequency, 180° out-of-phase with the internal clock of the part, with a peak-to-peak amplitude of INTV <sub>cc</sub> to GND.
4, 8	V <sub>IN</sub>	The V <sub>IN</sub> pins supply current to the LT83201 internal circuitry and to the internal top-side power switch. Two 0402 capacitors of 0.1 $\mu$ F or more should be placed to bypass both V <sub>IN</sub> pins with positive terminal of input capacitor as close as possible to the V <sub>IN</sub> pins, and the negative capacitor terminal as close as possible to the GND pins. V <sub>IN</sub> pins must also be connected with an additional local bypass capacitor of 4.7 $\mu$ F or more. To provide sufficient headroom for the current reference, V <sub>IN</sub> must be at least 700mV higher than the required regulation setpoint that is programmed via the SET pin. For example, for the required regulation setpoint of 3.3V, V <sub>IN</sub> must be at least 3.3V + 700mV = 4V, or higher.

5, 7, Exposed Pad	GND	Ground. Place the negative terminal of the input capacitor as close to the GND pins as possible. The exposed pads should be soldered to the PCB for good thermal performance. If necessary due to manufacturing limitations, the exposed pad may be left disconnected; however, the performance degrades.
6	SW	The SW pin is the output of the internal power switches. Connect this pin to the inductor. This node must be kept small on the PCB for good performance and low EMI.
9	BST	This pin is used to provide a drive voltage higher than the input voltage to the topside power switch. Place a 0.1 $\mu$ F boost capacitor as close as possible to the IC.
10	INTV <sub>CC</sub>	Internal 3.4V Regulator Bypass Pin. The internal power drivers and control circuits are powered by this voltage. Do not load the INTV <sub>CC</sub> pin with external circuitry. INTV <sub>CC</sub> current is supplied by V <sub>IN</sub> . Decouple this pin to ground with at least 1 $\mu$ F low equivalent series resistance (ESR) ceramic capacitor placed close to the IC.
11	EN/UVLO	A voltage at this pin greater than 0.75V enables switching, and a voltage less than 200mV is guaranteed to shut down the internal current bias and sub-regulators. The hysteretic threshold voltage is 0.75V going up and 0.7V going down. Connect to V <sub>IN</sub> if the shutdown feature is not used. An external resistor divider from V <sub>IN</sub> is used to program a V <sub>IN</sub> threshold below which the LT83201 shuts down.
12	V <sub>C</sub>	The V <sub>C</sub> pin is the output of the internal error amplifier. The voltage on this pin controls the peak switch current. Connect an RC network from this pin to ground to compensate the control loop.
13	SET	This pin is the non-inverting input of the error amplifier and the regulation setpoint for the LT83201. SET sources a precision 100 $\mu$ A current that flows through an external resistor connected between the SET and GND. The LT83201's output voltage is determined by $V_{SET} = I_{SET} \times R_{SET}$ when used in the default unity-gain configuration. The SET pin voltage range is from 0V to 13V. For applications with output voltages above 13V, see the <i>Output Voltages Above 13V</i> section. A capacitor should be added from SET to GND for the best noise performance. Increasing this capacitance further improves noise at the expense of increased start-up time. See the <i>Set Pin Capacitor: Noise and Soft-Start</i> section for important information on how to select this capacitor. For optimum load regulation, Kelvin connect the ground side of the SET pin resistor directly to the load. This pin is pulled to ground with a 520 $\Omega$ MOSFET ( $R_{SET-PULLDOWN}$ ) during shutdown and fault conditions.
14	OUTS	Output Sense. This pin is the inverting input to the error amplifier. For optimal transient performance and load regulation, Kelvin connect OUTS directly to the output capacitor and the load.
15	PGFB	Power Good Feedback. The PG pin pulls low if PGFB increases above 537.5mV or decreases below 462.5mV. Connecting an external resistor divider between V <sub>OUT</sub> , PGFB, and GND sets the programmable power good threshold with the following transfer function: $0.5V (\pm 7.5\%) \times (1 + R_{PGFB(TOP)}/R_{PGFB(BOT)})$ . As discussed in the <i>Applications Information</i> section, PGFB also activates the fast start-up circuitry. The PGFB pin must be connected to INTV <sub>CC</sub> or 0.5V if power good and fast start-up functionalities are not needed.

## TYPICAL PERFORMANCE CHARACTERISTICS

$T_A = 25^\circ\text{C}$ , unless otherwise noted.

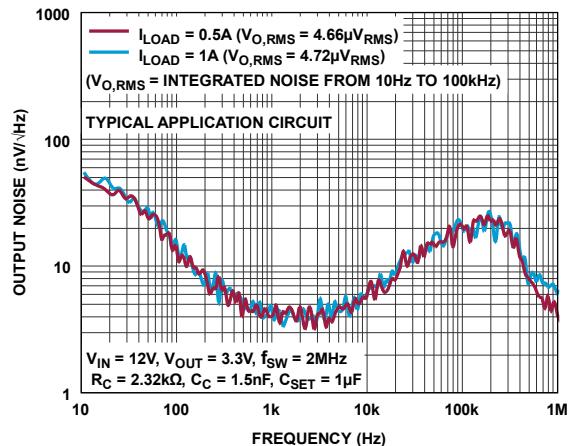


Figure 4. Noise Spectral Density vs. Load

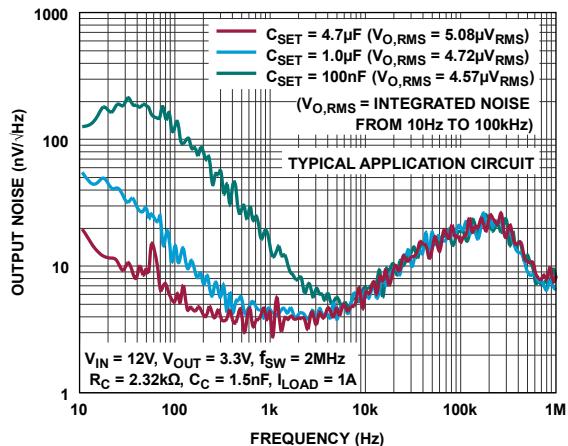


Figure 5. Noise Spectral Density vs.  $C_{\text{SET}}$

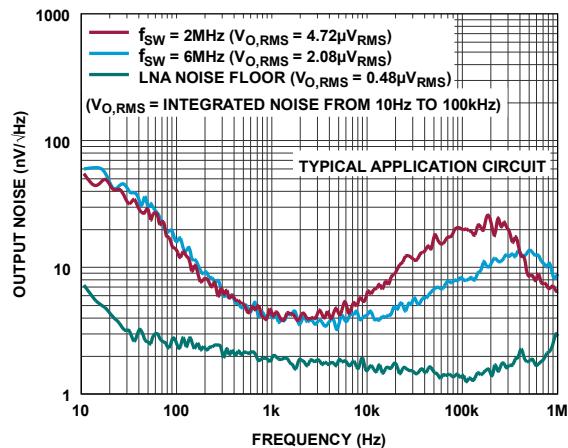


Figure 6. Noise Spectral Density vs. Switching Frequency

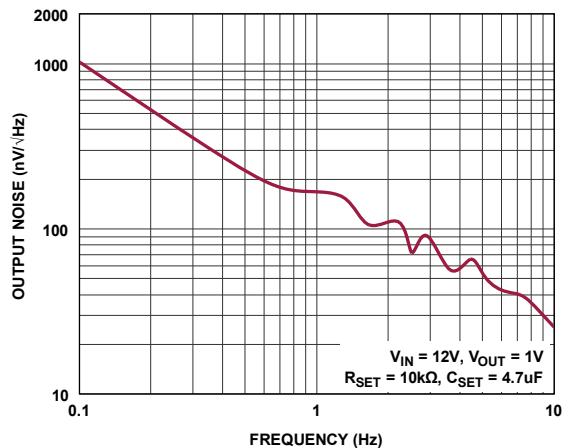


Figure 7. Noise Spectral Density (0.1Hz to 10Hz)

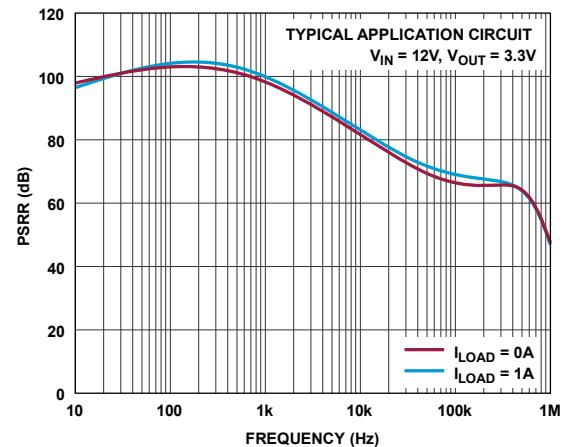


Figure 8. Power-Supply Ripple Rejection

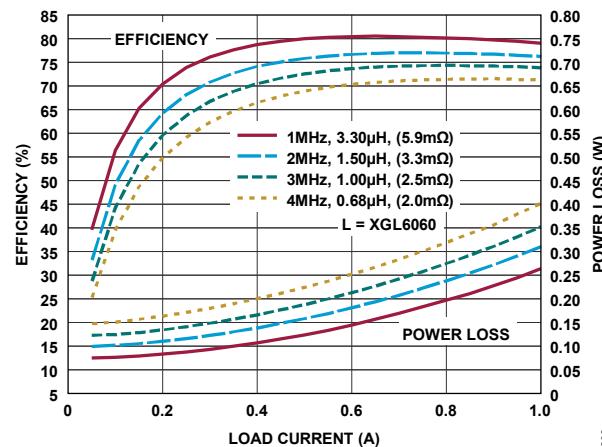
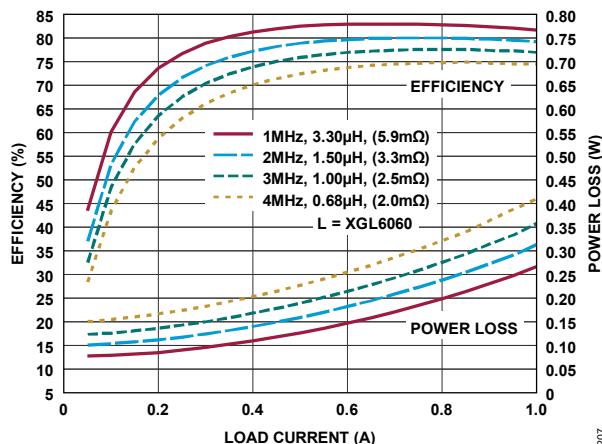
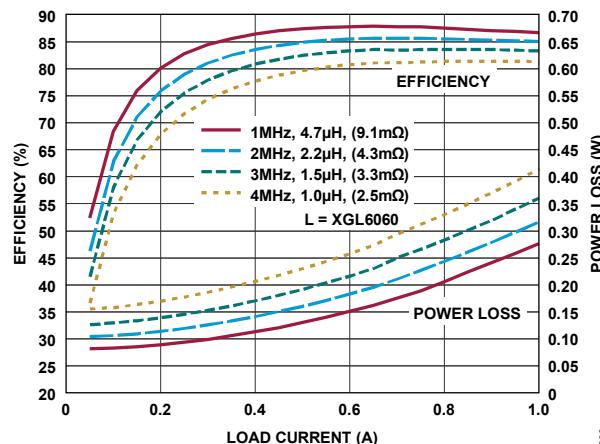
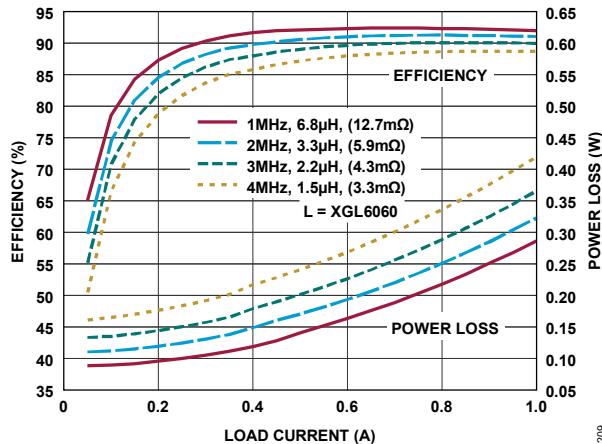
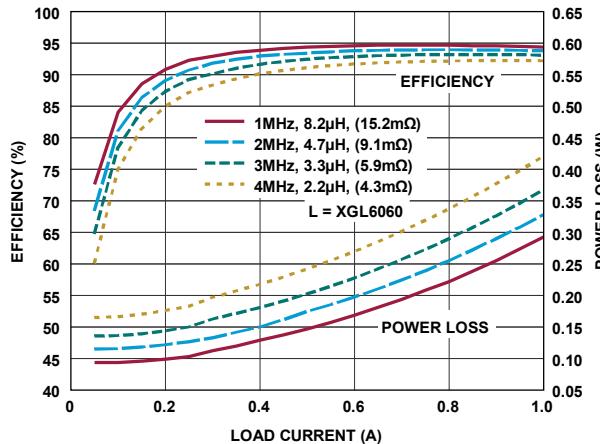
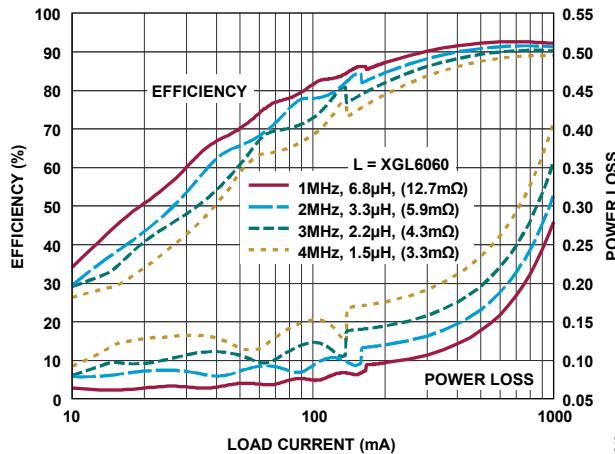
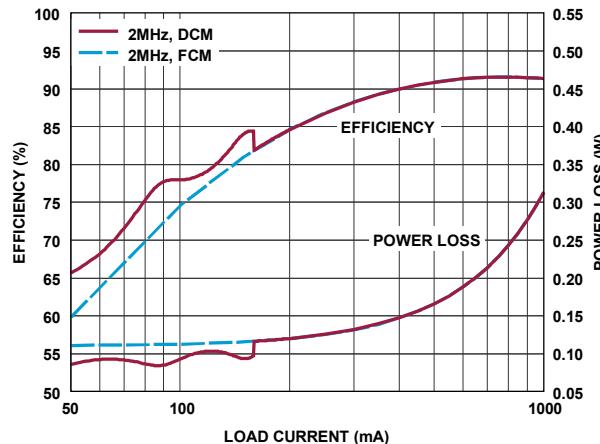


Figure 9. 12V<sub>IN</sub> to 1V<sub>OUT</sub> Efficiency (FCM)

Figure 10.  $12V_{IN}$  to  $1.2V_{OUT}$  Efficiency (FCM)Figure 11.  $12V_{IN}$  to  $1.8V_{OUT}$  Efficiency (FCM)Figure 12.  $12V_{IN}$  to  $3.3V_{OUT}$  Efficiency (FCM)Figure 13.  $12V_{IN}$  to  $5V_{OUT}$  Efficiency (FCM)Figure 14.  $12V_{IN}$  to  $3.3V_{OUT}$  Efficiency (DCM)Figure 15.  $12V_{IN}$  to  $3.3V_{OUT}$  Efficiency

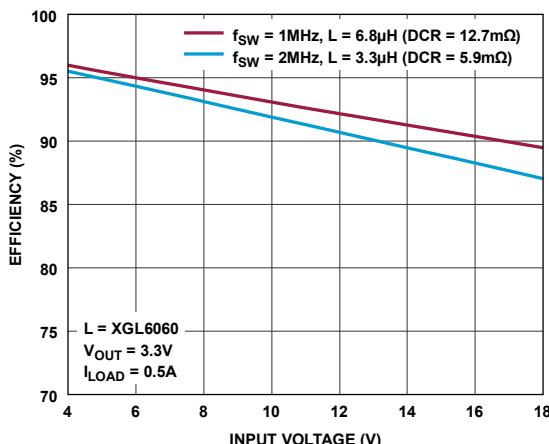
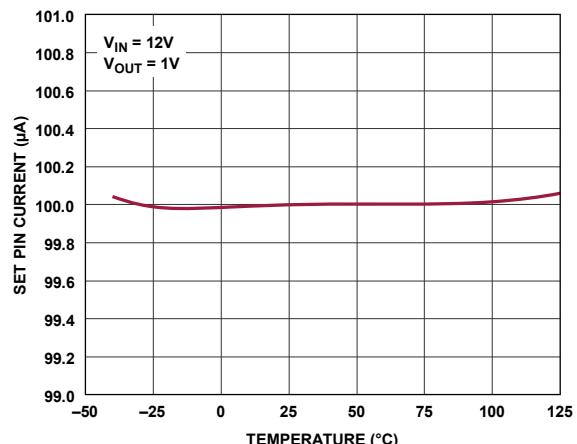
Figure 16. Efficiency vs.  $V_{IN}$ 

Figure 17. SET Pin Current vs. Temperature

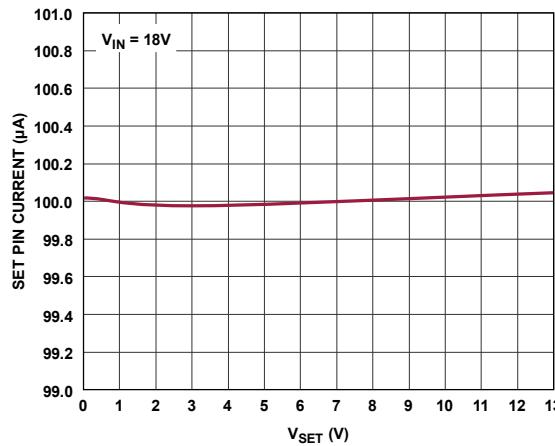
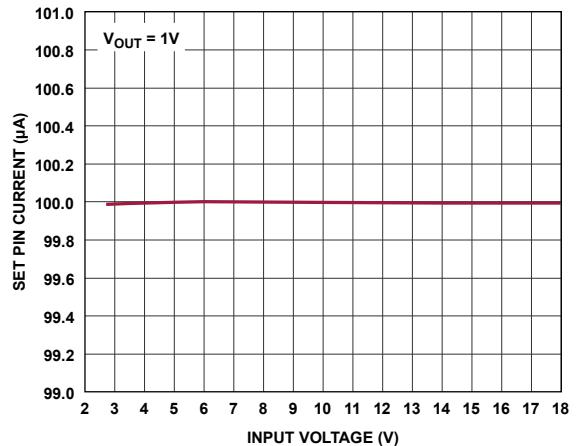
Figure 18. SET PIN Current vs.  $V_{SET}$ 

Figure 19. SET PIN Current vs. Input Voltage

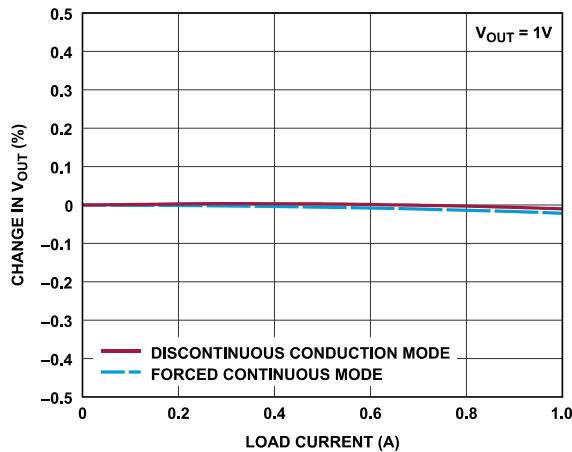


Figure 20. Load Regulation

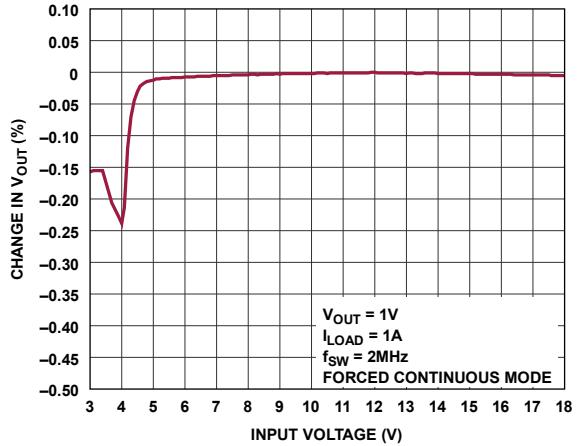


Figure 21. Line Regulation

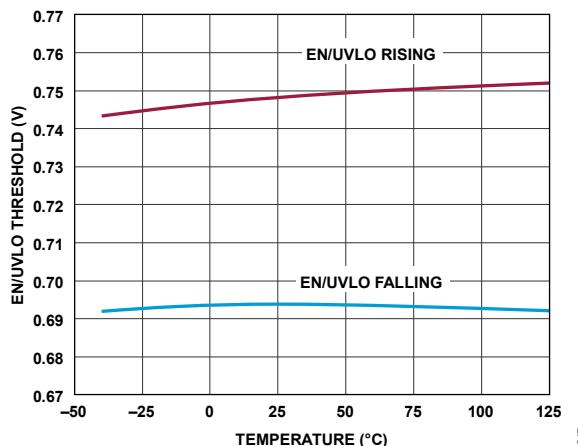


Figure 22. EN/UVLO Pin Thresholds

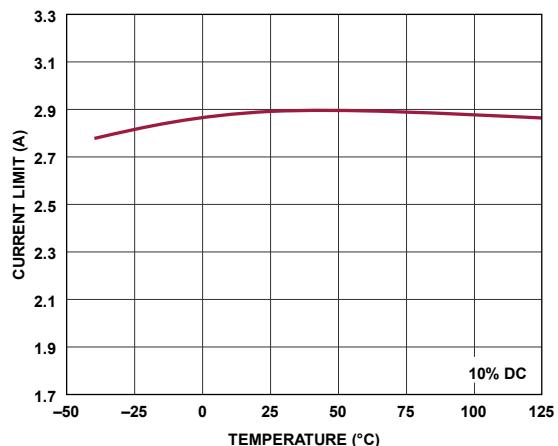


Figure 23. Top MOSFET Current Limit



Figure 24. Top MOSFET Current Limit vs. Duty Cycle

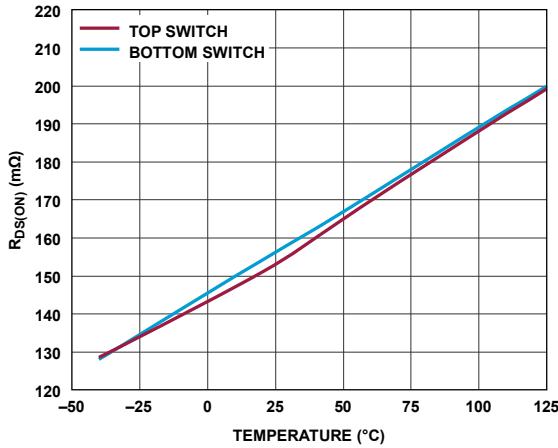
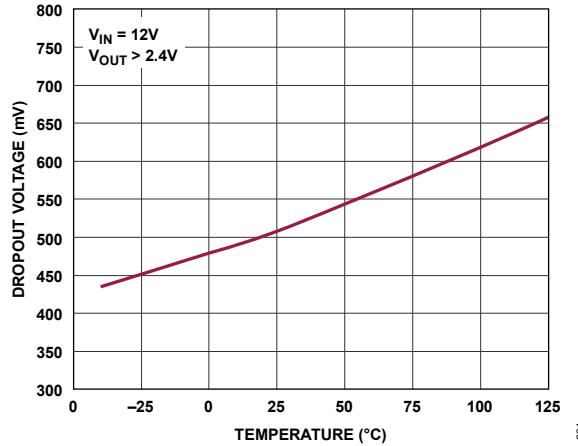
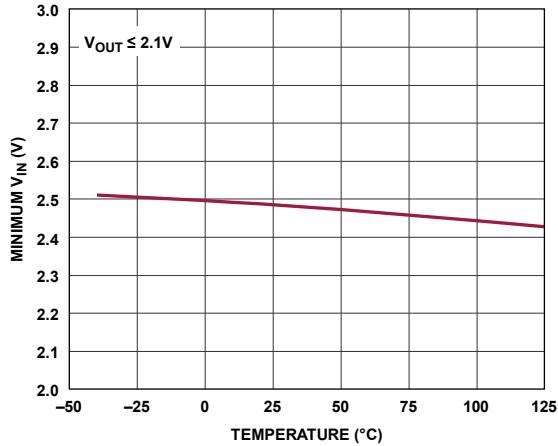
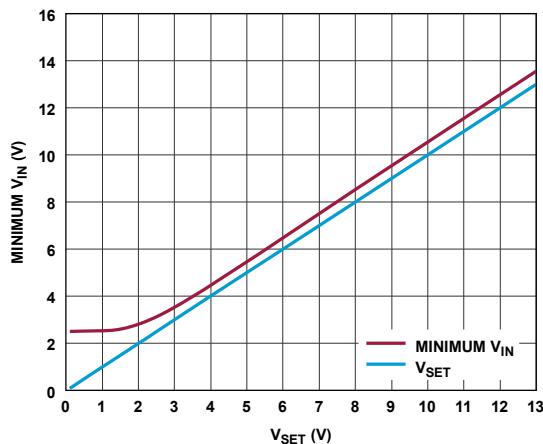
Figure 25. Switch  $R_{DS(ON)}$  vs. Temperature

Figure 26. Dropout Voltage vs. Temperature

Figure 27. Minimum  $V_{IN}$  vs. Temperature

Figure 28. Minimum  $V_{IN}$  as a Function of  $V_{SET}$ 

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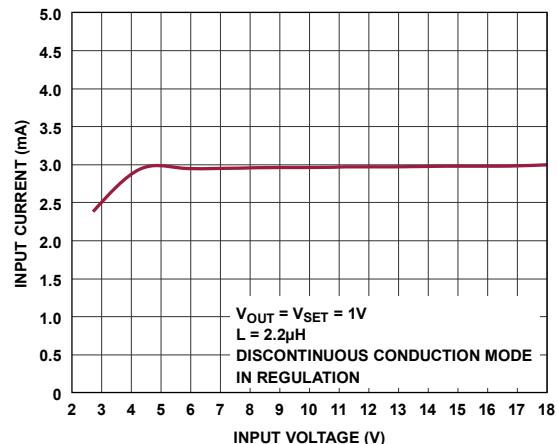


Figure 29. No-Load Supply Current

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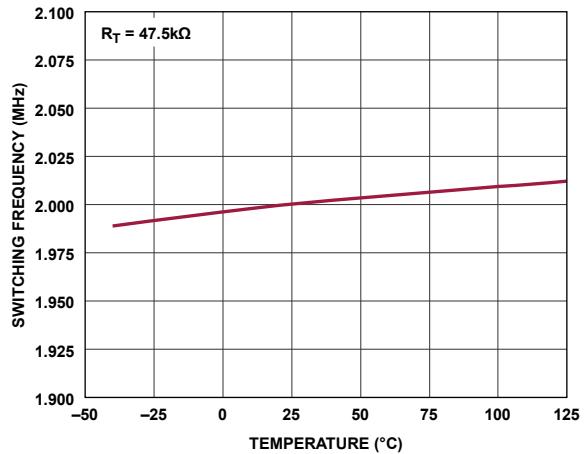


Figure 30. Switching Frequency vs. Temperature

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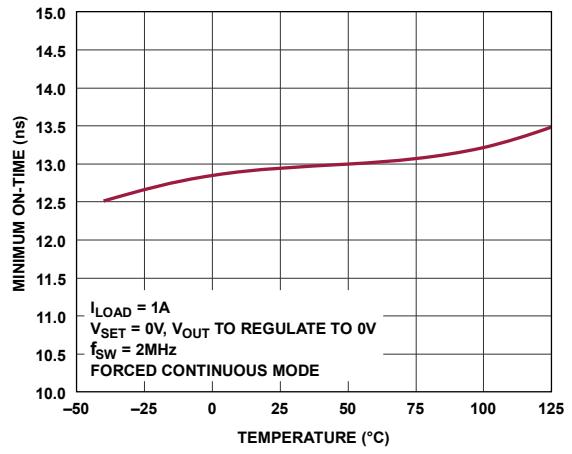


Figure 31. Minimum On-Time vs. Temperature

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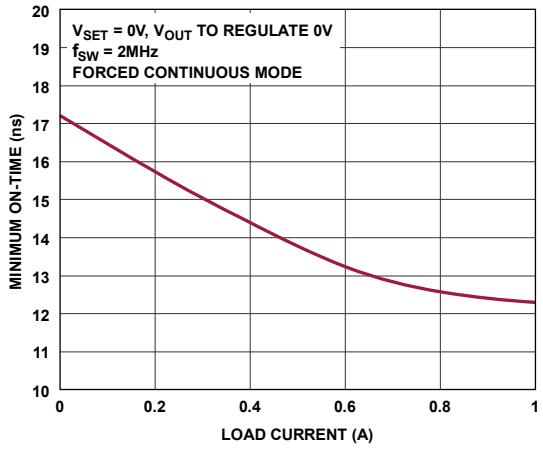
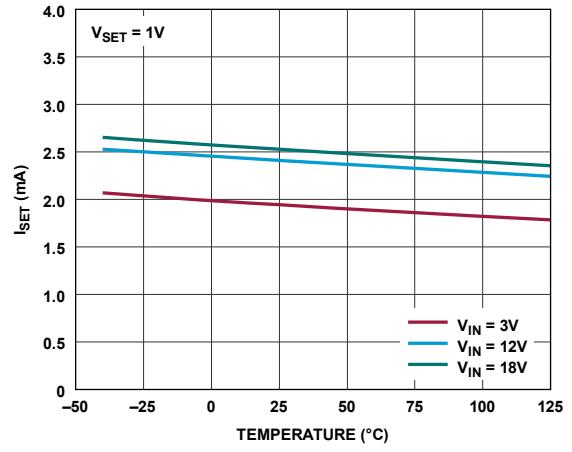
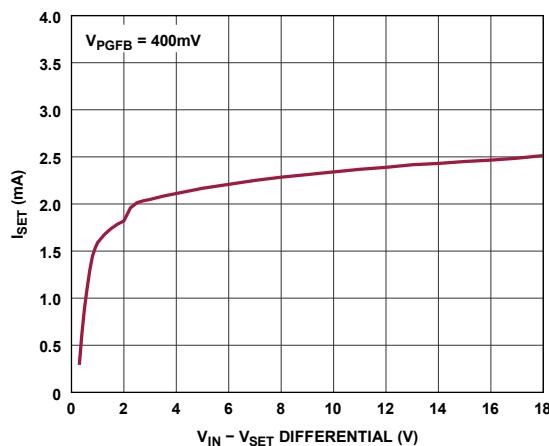


Figure 32. Minimum On-Time vs. Load

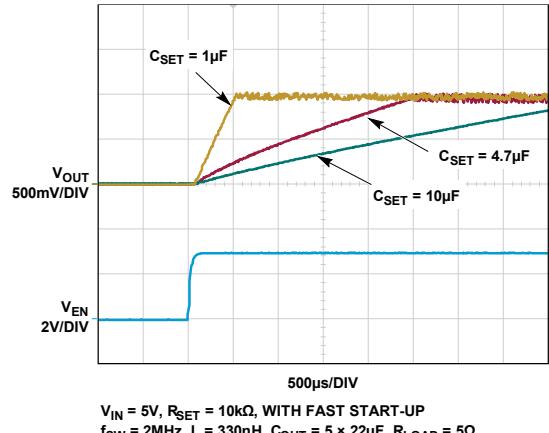
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Figure 33.  $I_{SET}$  During Start-Up with Fast Start-Up Enabled vs. Temperature

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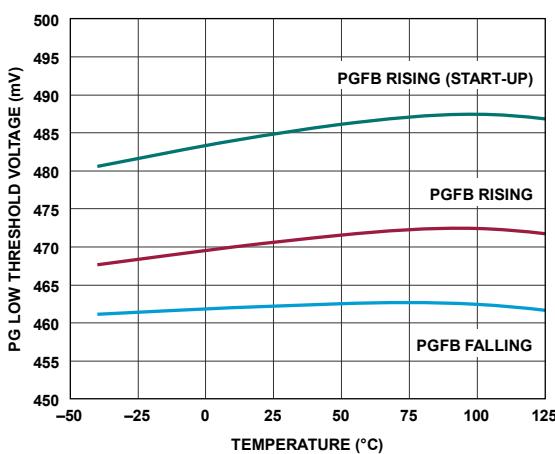


**Figure 34.**  $I_{SET}$  During Start-Up with Fast Start-Up Enabled (vs.  $V_{IN} - V_{SET}$  Differential)



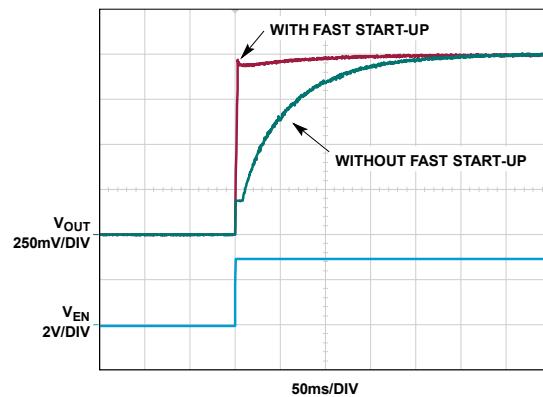
**Figure 36.** Soft-Start Waveforms

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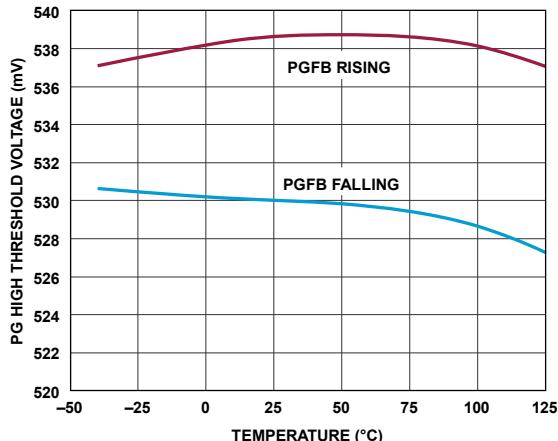
**Figure 38.** Power-Good Low Thresholds

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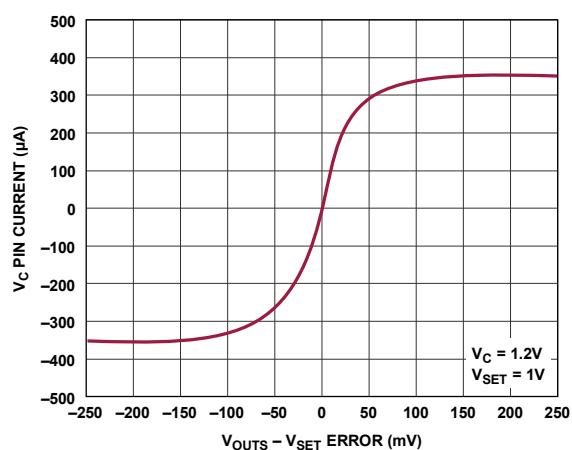
**Figure 35.** Start-Up Time with and without Fast Start-Up Circuitry for Large  $C_{SET}$

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**Figure 37.** Power-Good High Thresholds

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**Figure 39.** Error Amp Output Current

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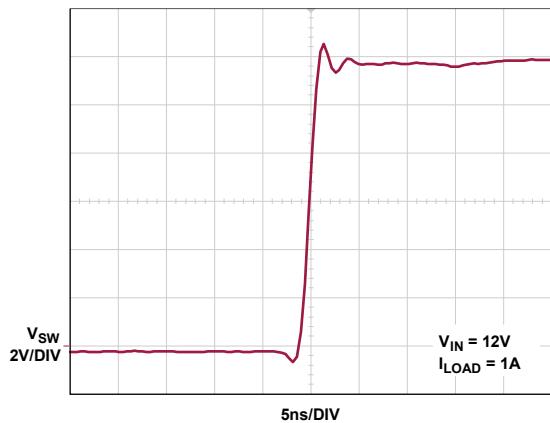


Figure 40. Switch Rising Edge

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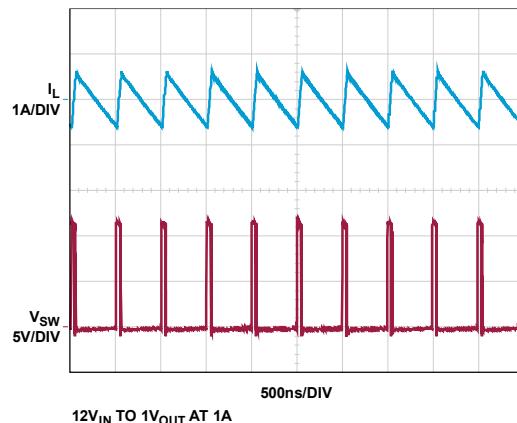


Figure 41. Switching Waveforms, Full Frequency Continuous Operation

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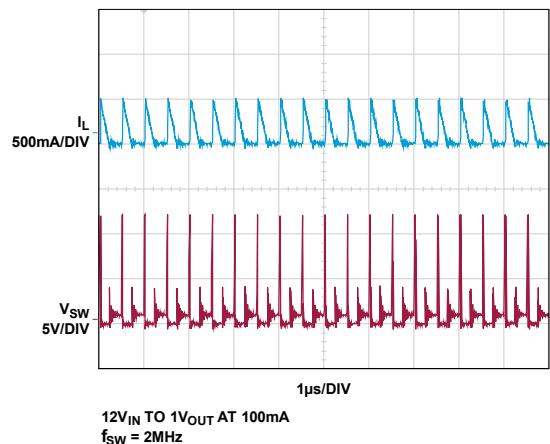


Figure 42. Switching Waveforms, Full Frequency Discontinuous Operation

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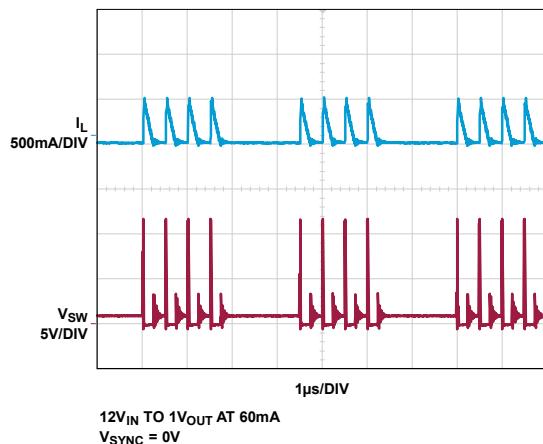


Figure 43. Switching Waveforms, Pulse-Skipping Discontinuous Operation

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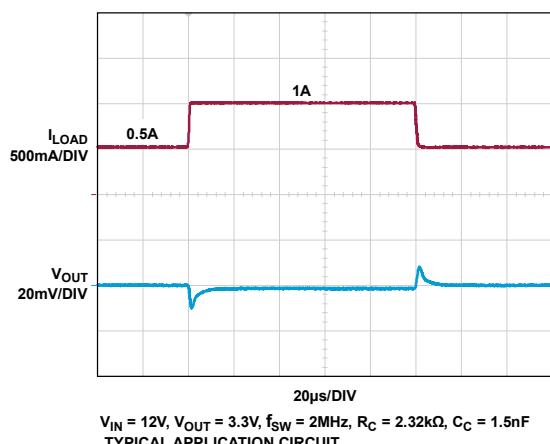


Figure 44. Transient Response: Load Current Stepped from 0.5A to 1A

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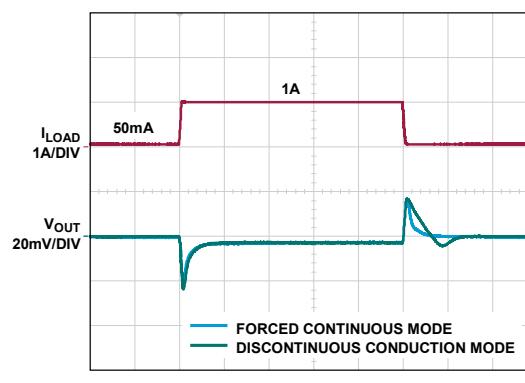


Figure 45. Transient Response: Load Current Stepped from 50mA to 1A

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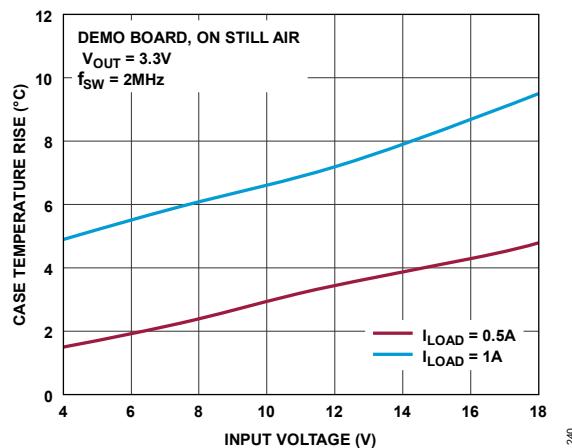


Figure 46. LT83201 Case Temperature Rise

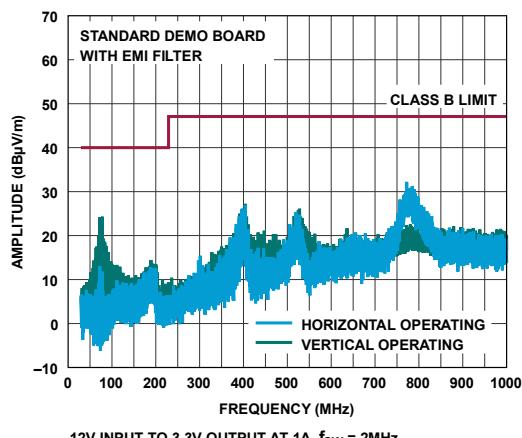


Figure 47. LT83201 Radiated EMI Performance (CISPR32 Radiated Emission Test with Class B Limits)

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## BLOCK DIAGRAM

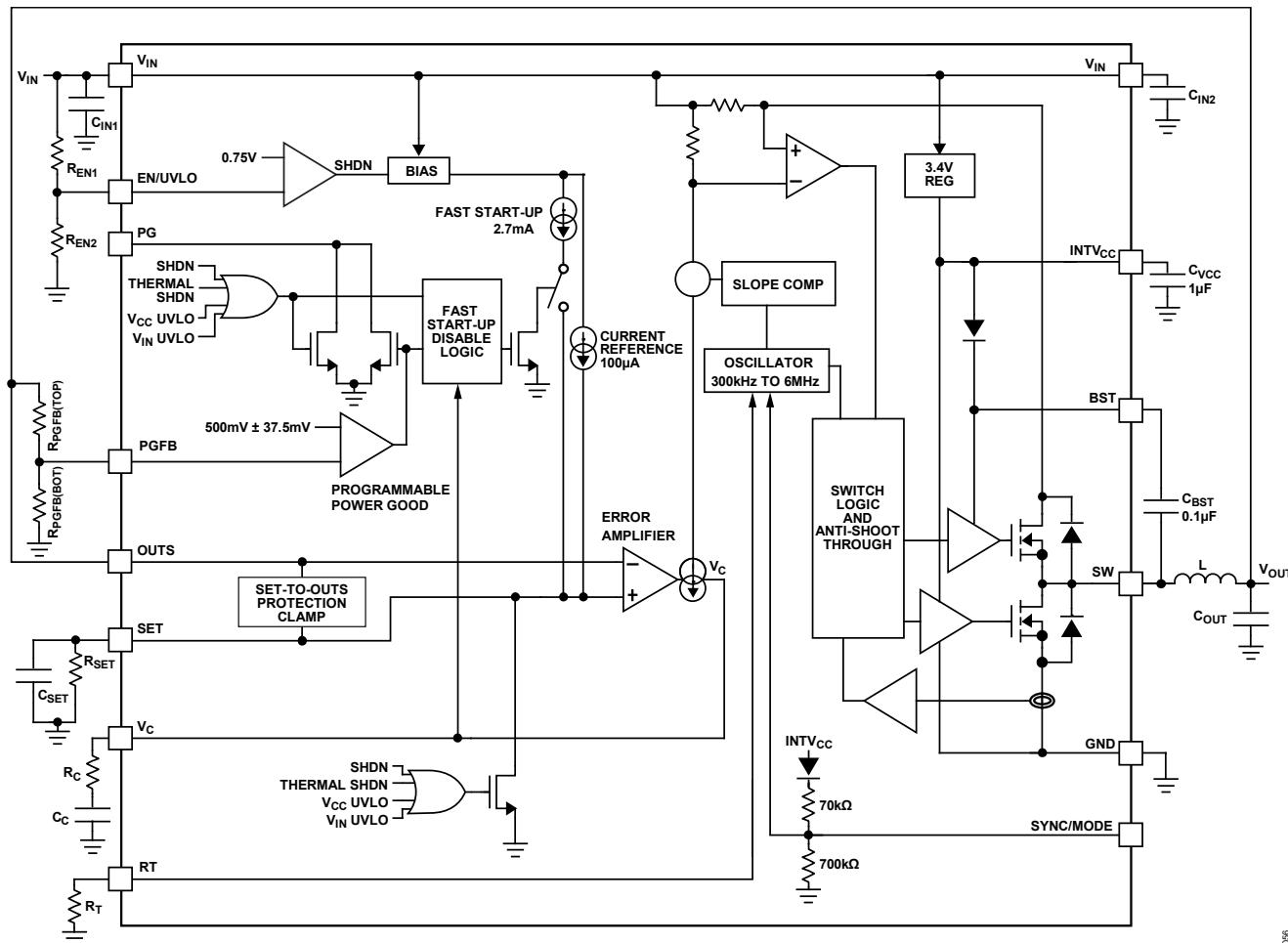


Figure 48. Block Diagram

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## THEORY OF OPERATION

The LT83201 is a constant-frequency, current-mode, monolithic step-down regulator, operating using a current reference-based architecture to allow the employment of unity gain to minimize output noise across all output voltages. An oscillator, with the frequency set using a resistor on the RT pin, turns on the internal top power switch at the beginning of each clock cycle. The current in the inductor increases until the top switch current comparator trips and turns off the top power switch. The peak inductor current at which the top switch turns off is controlled by the voltage on the  $V_C$  pin. The error amplifier servos the  $V_C$  node by comparing the voltage on the OUTS pin to the reference voltage on the SET pin, which is set by the user with a resistor from the SET pin to the ground. When the load current increases, it causes a reduction in the OUTS voltage relative to the reference, leading the error amplifier to raise the  $V_C$  voltage until the average inductor current matches the new load current. When the top power switch turns off, the synchronous power switch turns on until the next clock cycle begins or the inductor current falls to zero (only in the discontinuous conduction mode). If overload conditions result in more than 1.7A flowing through the bottom switch, the next clock cycle is delayed until the switch current returns to a safe level.

The LT83201 features third-generation Silent Switcher technology, which combines an ultra-low noise current reference with previous generation Silent Switcher technology. The output voltage can be programmed with a single resistor, providing unity-gain operation over the output range, resulting in virtually constant ultra-low output noise independent of the output voltage.

If the EN/UVLO pin is below 0.2V, the LT83201 shuts down and draws 40 $\mu$ A from the input. When the EN/UVLO pin rises above 0.75V, the switching regulator becomes active.

To improve efficiency at light loads, connect the LT83201 SYNC/MODE pin to ground for Discontinuous Conduction Mode (DCM), which allows discontinuous conduction at light loads. The LT83201 provides smooth transitions between continuous conduction and discontinuous conduction operation in this mode. In discontinuous mode the LT83201 retains full frequency operation down to light loads for predictable noise.

The SYNC/MODE pin is connected to  $INTV_{CC}$  or to a voltage higher than 1.5V or floated to use Forced Continuous Mode (FCM). If a clock is applied to the SYNC pin, the part synchronizes to an external clock frequency and operates in FCM.

The LT83201 can operate in FCM for fast transient response and full frequency operation over a wide load range. When in FCM, the oscillator operates continuously, and positive SW transitions are aligned to the clock. Negative inductor current is allowed. In this mode, the LT83201 can sink current from the output and return this charge to the input, improving load-step transient response.

The  $V_C$  pin allows the loop compensation of the switching regulator to be optimized based on the programmed switching frequency, allowing for a fast transient response.

## APPLICATIONS INFORMATION

### Low Frequency Output Noise

The LT83201 offers many advantages with respect to noise performance in the low-frequency range (<100kHz). Conventional step-down regulators have several sources of low frequency noise. The most critical noise sources for a conventional regulator are its reference, error amplifier, noise from the resistor divider network used for setting output voltage, and the noise gain created by this resistor divider.

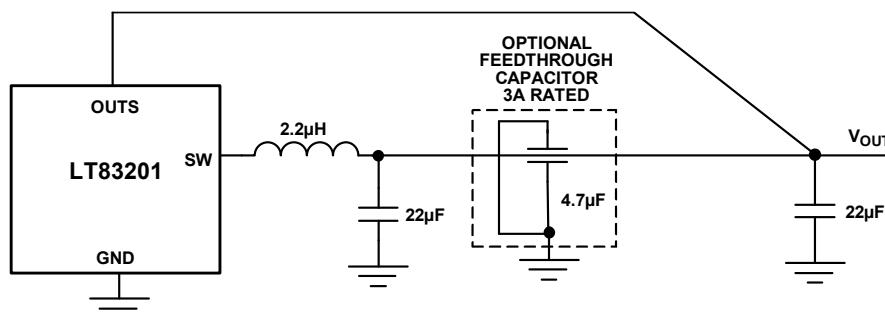
Unlike most step-down regulators, the LT83201 does not use a voltage reference; instead, it uses a 100 $\mu$ A current reference. One problem that conventional step-down regulators face is that the resistor divider setting the output voltage gains up the reference noise. In contrast, the current reference architecture employed by the LT83201 allows unity-gain operation to avoid gaining up the noise from the reference to the output. Therefore, if a capacitor bypasses the SET pin resistor, the output noise is independent of the programmed output voltage. The resultant output noise is typically 4nV/ $\sqrt{\text{Hz}}$  at 10kHz.

With the previously mentioned noise sources operating at such low noise levels, other noise sources become non-negligible contributors to the output noise. Choosing a compensation network that achieves good transient performance with good phase margin ensures optimal noise performance. The Applications Information section on [Frequency Compensation](#) provides guidelines on how to choose appropriate compensation.

### Filtering Switching Ripple and High Frequency Noise

The LT83201 is a switching regulator and also has the typical artifacts of a switching regulator at the output, namely a ripple at the fundamental switching frequency as well as high-frequency spikes associated with the fast switching edges. While the output capacitor absorbs some of these spikes, the capacitor ESL limits its ability to do so at high frequencies. Additional filtering at the output in the form of feedthrough capacitors, ferrite beads, or an additional LC filter stage is recommended to eliminate these high-frequency spikes and significantly reduce switching ripple.

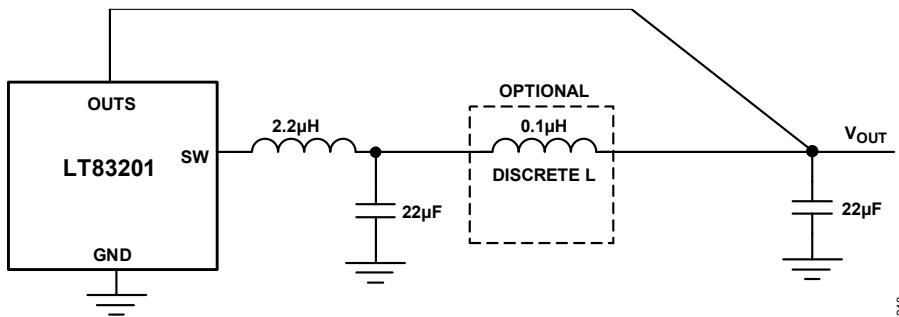
If additional switching ripple reduction is required while retaining fast transient response, ferrite beads, a PCB trace or feedthrough capacitors may be used. For feedthrough capacitors, ensure sufficient feedthrough capacitors are paralleled to carry the required load current. [Figure 49](#) shows an example where two 3A-rated feedthrough capacitors are used for additional switching ripple suppression to deliver up to 6A at the output. In practice, this is limited to 1A for the LT83201.



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**Figure 49. Additional Output Ripple Filtering Using Feedthrough Capacitors**

If transient performance is not critical, other passive filter solutions can be realized using a physical inductor as a larger second L and additional output capacitance for the second C, as shown in [Figure 50](#).



**Figure 50. Additional Output Ripple Filtering Using a Second LC Filter**

When designing an additional filter for further attenuation of the switching ripple, it is highly recommended to design with LTpowerCAD® to ensure that the design is stable with good phase margin and provides sufficient attenuation at the switching frequency of interest.

The Silent Switcher 3 architecture makes it possible to achieve excellent noise performance from low to high frequencies at the output of the LT83201 while utilizing only passive filtering.

## PCB Layout Recommendations

The LT83201 is specifically designed to minimize low-frequency (10Hz to 100kHz) noise and EMI emissions and maximize efficiency when switching at high frequencies. For optimal performance, the LT83201 can use multiple  $V_{IN}$  bypass capacitors.

Two small capacitors are placed as close as possible to the LT83201  $V_{IN}$  pins, and the third capacitor with a larger value, 4.7μF or higher, should be placed near one of these two capacitors. For a recommended PCB layout, see [Figure 51](#).

For more details and PCB design files, refer to the LT83201 demo board manual. Note that large, switched currents flow in the LT83201  $V_{IN}$  and GND pins and the input capacitors. The loops formed by the input capacitors should be as small as possible by placing the capacitors adjacent to the  $V_{IN}$  and GND pins. Capacitors with small case sizes, such as 0402 or 0603, are optimal due to their low parasitic inductance. Special care must be taken with the input capacitors to ensure they have a low-impedance return path to the IC ground. This is achieved by placing several grounds through the GND side of the input capacitors such that the ground plane is utilized to full advantage. This should be an unbroken ground plane with a solid connection to the exposed pad of the IC, as shown in [Figure 51](#).

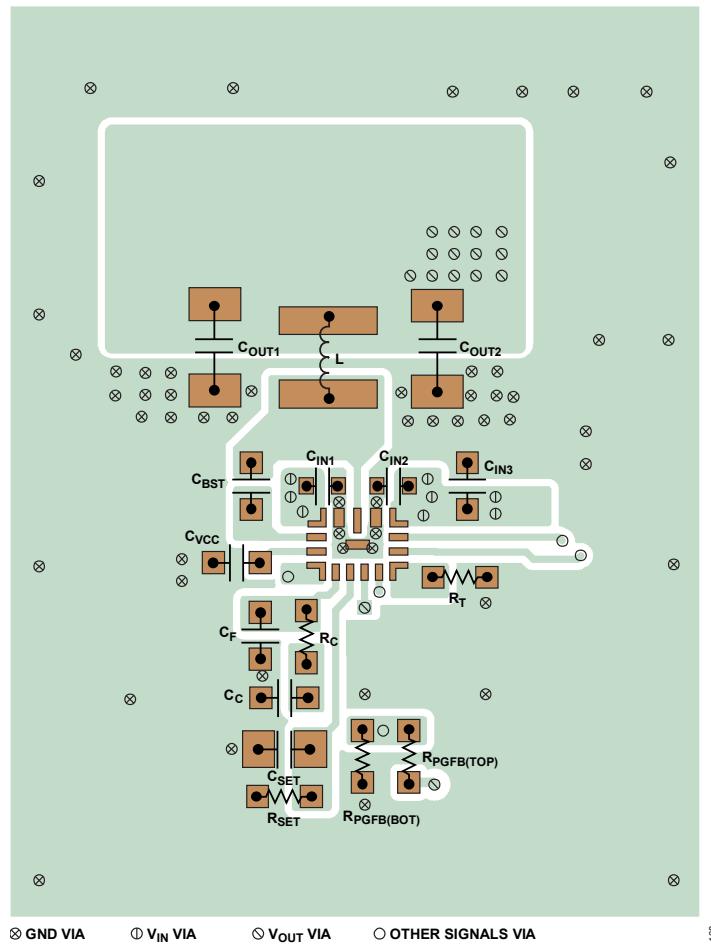


Figure 51. LT83201 Suggested Layout

The main inductor and output capacitors should be placed on the same side of the circuit board as the IC, and their connections should be made on that layer. The impedance of the output bulk capacitor's return path to IC ground should also be minimized through the generous use of ground vias. Care with ground layout prevents switching currents from the input capacitors coupling to the output through the ground, which can introduce unintentional perturbations onto the OUTS pin. A small capacitor may also be placed locally to decouple the OUTS pin if needed.

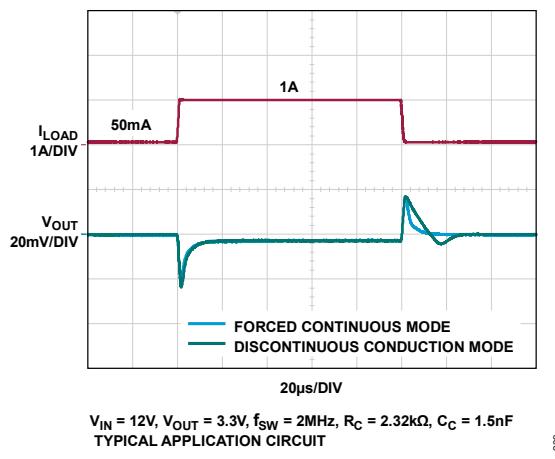
An additional LC filter, if used, can be placed on the other side of the circuit board for optimal EMI performance, though this is not required. Place a local unbroken ground plane under the application circuit on the layer closest to the surface layer. The SW and BST nodes should be as small as possible. Finally, keep the OUTS, PGFB, and RT nodes small so that the ground traces shield them from the SW and BST nodes. The OUTS, PGFB, and RT traces should not pass underneath the main inductor and should also be kept away from the inductor vias.

The exposed pad on the bottom of the package should be soldered to the PCB to reduce thermal resistance to ambient. To keep thermal resistance low, extend the ground plane from the GND as much as possible and add thermal vias to additional ground planes within the circuit board and on the bottom side.

The current reference architecture of the LT83201 allows remote sense of the negative terminals of the load in addition to the positive terminal. Note the via on the ground side of the  $R_{SET}$  and  $C_{SET}$  going to the ground side of the  $C_{OUT}$ , which can be configured for remote sense of the negative terminal of a load placed further away. For more information on implementing remote sense for the LT83201, see the [Output Sensing and Stability](#) section.

## Forced Continuous Mode (FCM)

The LT83201 can operate in FCM for fast transient response and full-frequency operation over a wide load range. When in FCM, the oscillator operates continuously, and positive SW transitions are aligned to the clock. Negative inductor current is allowed at light loads or under large transient conditions. In this mode, the LT83201 can sink current from the output and return this charge to the input, improving load-step transient response (for a comparison of DCM and FCM, see [Figure 52](#)). At light loads, FCM operation is less efficient than DCM operation, but it may be useful in applications where the output is required to sink current. To enable FCM, connect the pin to  $\text{INTV}_{\text{CC}}$  or  $> 1.5\text{V}$ , or float the pin.



**Figure 52. Load Step Transient Response with and without FCM**

FCM is disabled under  $V_{\text{IN}}$  overvoltage conditions ( $V_{\text{IN}}$  pin is held above 18V), if  $V_{\text{OUT}}$  is too high (PGFB pin is held greater than 537.5mV) and during start-up until the voltage on  $V_{\text{OUT}}$  has charged up to  $\sim 97.5\%$  of its final value (as indicated when the PGFB pin rises to above 486.5mV). For the latter two conditions, it is assumed the PGFB pin is connected to the output voltage through an appropriate resistor divider. When FCM is disabled in these ways, negative inductor current is not allowed, and the LT83201 operates in DCM.

## Discontinuous Conduction Mode (DCM)

When not operating in FCM, the LT83201 operates in Discontinuous Conduction Mode (DCM), which allows discontinuous operation at light loads. In this mode, the oscillator operates continuously, all switching cycles are aligned to the clock and negative inductor current is not allowed. This improves efficiency at light loads.

The LT83201 enters discontinuous mode when the inductor valley current drops below 0A and stays in discontinuous mode until the inductor valley current rises slightly above 0A, at which point the part returns to continuous mode operation. This allows a smoother transition between discontinuous and continuous mode operation.

In this mode, the LT83201 may also skip switching cycles at very light loads for improved efficiency or at very high duty cycle to achieve better dropout.

Skipping pulses can result in additional noise at frequencies other than the switching frequency, which could be undesirable for some applications. The LT83201 operates at full frequency down to very light loads due to the excellent minimum on-time. Operating at full frequency at light loads helps achieve higher light load efficiency and predictable noise performance.

## Synchronization

To synchronize the LT83201 oscillator to an external frequency, connect a square wave to the SYNC/MODE pin. The square wave amplitude should have valleys below 0.7V and peaks above 1.5V (up to 6V), with a minimum on-time and off-time of 50ns.

While synchronized to an external clock, the part runs in FCM to maintain regulation. The LT83201 may be synchronized over a 300kHz to 6MHz range. The  $R_T$  resistor should be chosen to set the LT83201 switching frequency to be equal to the synchronization input. The slope compensation is set by the  $R_T$  value, while the minimum slope compensation required to avoid subharmonic oscillations is established by the inductor size, input voltage, and output voltage.

## Setting the Switching Frequency

The LT83201 uses constant-frequency PWM architecture that is programmed to switch from 300kHz to 6MHz by using a resistor connected from the RT pin to GND.

The  $R_T$  resistor required for the desired switching frequency is calculated by Equation 1.

$$R_T = \frac{115.8}{f_{sw}} - 10.4 \quad (1)$$

where  $R_T$  is in  $k\Omega$  and  $f_{sw}$  is the desired switching frequency in MHz. *Table 4* shows the necessary  $R_T$  value for the desired switching frequency.

**Table 4. SW Frequency vs.  $R_T$  Value**

$f_{sw}$ (MHz)	$R_T$ ( $k\Omega$ )
0.3	392
0.4	287
0.5	226
0.6	187
0.7	154
0.8	137
0.9	118
1.0	105
1.2	86.6
1.4	71.5
1.6	61.9
1.8	53.6
2	47.5
2.5	35.7
3	28.7
3.5	23.2
4	18.0
6	9.76

## Operating Frequency Selection and Trade-Offs

Selection of the operating frequency is a trade-off between efficiency, component size, and input voltage range. The advantage of high-frequency operation is that smaller inductor and capacitor values may be used. The

disadvantages are lower efficiency and a smaller input voltage range. The highest switching frequency ( $f_{SW(MAX)}$ ) for a given application can be calculated by Equation 2.

$$f_{SW(MAX)} = \frac{V_{OUT} + V_{SW(BOT)}}{t_{ON(MIN)}(V_{IN} - V_{SW(TOP)} + V_{SW(BOT)})} \quad (2)$$

where  $V_{IN}$  is the typical input voltage,  $V_{OUT}$  is the output voltage,  $V_{SW(TOP)}$  and  $V_{SW(BOT)}$  are the internal switch drops (~0.15V and ~0.15V, respectively, at maximum load), and  $t_{ON(MIN)}$  is the minimum top switch on-time (see the [Electrical Characteristics](#) table). This equation shows that a slower switching frequency is necessary to accommodate a high  $V_{IN}/V_{OUT}$  ratio.

For transient operation,  $V_{IN}$  may go as high as the maximum operating voltage of 18V regardless of the  $R_T$  value; however, LT83201 reduces switching frequency as necessary to maintain control of the inductor current to assure safe operation.

In DCM, the LT83201 is capable of a maximum duty cycle of approximately 99%, and the  $V_{IN}$ -to- $V_{OUT}$  dropout is limited by the  $R_{DS(ON)}$  of the top switch, provided there is sufficient headroom (~0.7V) between  $V_{IN}$  and SET for circuitry to function correctly. In this mode, the LT83201 skips switch cycles, resulting in a lower switching frequency than programmed by  $R_T$ . The LT83201 switches as frequently as necessary to keep the boost capacitor refreshed, with a minimum switching frequency of approximately 80kHz. Note that higher switching frequencies increase the minimum input voltage below which cycles are dropped to achieve a higher duty cycle.

In FCM, the LT83201 does not skip cycles, and so the maximum duty cycle is limited by the minimum off-time and chosen switching frequency. For applications that cannot allow deviation from the programmed switching frequency at low  $V_{IN}/V_{OUT}$  ratios and thus must operate in FCM, use Equation 3 to set the switching frequency.

$$V_{IN(MIN)} = \frac{V_{OUT} + V_{SW(BOT)}}{1 - f_{SW} \times t_{OFF(MIN)}} - V_{SW(BOT)} + V_{SW(TOP)} \quad (3)$$

where  $V_{IN(MIN)}$  is the minimum input voltage without skipped cycles,  $V_{OUT}$  is the output voltage,  $V_{SW(TOP)}$  and  $V_{SW(BOT)}$  are the internal switch drops (~0.15V and ~0.15V, respectively, at maximum load),  $f_{SW}$  is the switching frequency (set by  $R_T$ ), and  $t_{OFF(MIN)}$  is the minimum switch off-time.

## Inductor Selection and Maximum Output Current

The LT83201 is designed to minimize solution size by allowing the inductor to be chosen based on the output load requirements of the application. During overload or short-circuit conditions, the LT83201 safely tolerates operation with a saturated inductor through the use of a high-speed peak-current mode architecture.

A good starting point for the inductor value is given by Equation 4.

$$L = \left( \frac{V_{OUT} + V_{SW(BOT)}}{f_{SW}} \right) \times 0.3 \quad (4)$$

where  $f_{SW}$  is the switching frequency in MHz,  $V_{OUT}$  is the output voltage,  $V_{SW(BOT)}$  is the bottom switch drop (~0.15V), and  $L$  is the inductor value in  $\mu$ H.

To avoid overheating and poor efficiency, choose an inductor with an RMS current rating that is greater than the maximum expected output load of the application.

In addition, the saturation current rating (typically labeled  $I_{SAT}$ ) of the inductor must be higher than the load current plus  $\frac{1}{2}$  of the inductor ripple current. See Equation 5.

$$I_{L(PEAK)} = I_{LOAD(MAX)} + \frac{1}{2} \Delta I_L \quad (5)$$

where  $\Delta I_L$  is the inductor ripple current as calculated in Equation 7 and  $I_{LOAD(MAX)}$  is the maximum output load for a given application.

As a quick example, an application requiring 3A output should use an inductor with an RMS rating of greater than 3A and an  $I_{SAT}$  of greater than 4A. During long-duration overload or short-circuit conditions, the inductor RMS rating requirement is greater to avoid overheating the inductor. To keep the efficiency high, the series resistance (DCR) should be less than  $0.15\Omega$ , and the core material should be intended for high-frequency applications.

The LT83201 limits the peak switch current to protect the switches and the system from overload faults.

The top switch current limit ( $I_{PEAK-LIMIT}$ ) is 2.9A at low duty cycles and decreases linearly to 1.6A at duty cycle = 80%.

The inductor value must be sufficient to supply the desired maximum output current ( $I_{OUT(MAX)}$ ), which is a function of the top switch current limit ( $I_{PEAK-LIMIT}$ ) and the ripple current (see Equation 6).

$$I_{OUT(MAX)} = I_{PEAK-LIMIT} - \frac{\Delta I_L}{2} \quad (6)$$

The peak-to-peak ripple current in the inductor can be calculated using Equation 7.

$$\Delta I_L = \frac{V_{OUT}}{L \times f_{SW}} \times \left(1 - \frac{V_{OUT}}{V_{IN(MAX)}}\right) \quad (7)$$

where  $f_{SW}$  is the switching frequency of the LT83201, and  $L$  is the value of the inductor. Therefore, the maximum output current that the LT83201 deliver depends on the switch current limit, the inductor value, and the input and output voltages. The inductor value may have to be increased if the inductor ripple current does not allow sufficient maximum output current ( $I_{OUT(MAX)}$ ) given the switching frequency and maximum input voltage used in the desired application.

The optimum inductor for a given application may differ from the one indicated by this design guide. A larger-value inductor provides a higher maximum load current and reduces the output voltage ripple. For applications requiring smaller load currents, the value of the inductor may be lower, and the LT83201 may operate with a higher ripple current. This allows the use of a physically smaller inductor or one with a lower DCR, resulting in higher efficiency.

For more information about maximum output current and discontinuous operation, refer to the [Application Note 44: LT1074/LT1076 Design Manual](#).

For duty cycles greater than 50% ( $V_{OUT}/V_{IN} > 0.5$ ), a minimum inductance is required to avoid sub-harmonic oscillation. For more information, refer to the [Application Note 19: LT1070 Design Manual](#). Equation 8 calculates that minimum inductance.

$$L_{MIN} = \frac{V_{IN}(2 \times DC - 1)}{1 \times f_{SW}} \quad (8)$$

where DC is the duty cycle ratio ( $V_{OUT}/V_{IN}$ ), and  $f_{SW}$  is the switching frequency.

## Overcurrent Protection (OCP) and Hiccup Mode

The LT83201 protects against overload and output short-circuit conditions by cycle-by-cycle current limiting both the current through the top and bottom switches.

Current is sensed in the top switch when it is on. The top switch is immediately turned off when the top switch current limit ( $I_{PEAK-LIMIT}$ ) is detected, and the bottom switch is turned on. Current is also sensed in the bottom switch when it is on, and the top switch is not allowed to turn back on unless the current through the bottom switch has dropped below the bottom switch current limit ( $I_{VALLEY-LIMIT}$ ). This effectively stretches the switching period and lowers the frequency for as long as the protection is required, as the top switch will not be allowed to turn on at the oscillator clock edge until the bottom switch current drops below  $I_{VALLEY-LIMIT}$ . This limits the average current during an output short-circuit condition to the RMS average of  $I_{PEAK-LIMIT}$  and  $I_{VALLEY-LIMIT}$ .

The LT83201 recognizes an overcurrent condition when either  $I_{PEAK-LIMIT}$  or  $I_{VALLEY-LIMIT}$  is triggered, and the  $V_C$  voltage rails at its maximum value of  $V_{C\_CLAMP}$ . Once an overcurrent condition is detected, an internal timer is started. If the overcurrent condition persists for longer than approximately 1.7ms ( $t_{HICC}$ ), then the part enters hiccup mode and suspends switching for  $\sim 12$ ms ( $7 \cdot t_{HICC}$ ) before soft start is attempted again. Hiccup mode ensures low average power dissipation under output short-circuit conditions both within the device and the inductor. During this period of suspended switching in hiccup mode, the  $V_C$  pin, PG pin, and SET pin are pulled low internally to ensure the part soft-starts correctly when it next attempts to switch again.

## Input Capacitors

The  $V_{IN}$  of the LT83201 should be bypassed with at least three ceramic capacitors for the best performance. Two small ceramic capacitors can be placed close to the part ( $C_{OPT1}$ ,  $C_{OPT2}$ ). These capacitors should be 0402 in size.

Note that a larger input capacitance is required when a lower switching frequency is used. If the input power source has a high impedance or there is significant inductance due to long wires or cables, additional bulk capacitance may be necessary. This can be provided with a low-performance electrolytic capacitor.

A ceramic input capacitor combined with trace or cable inductance forms a high quality (underdamped) tank circuit. If the LT83201 is plugged into a live supply, the input voltage can ring to twice its nominal value, possibly exceeding the LT83201's voltage rating. This situation is easily avoided; for more information, refer to the [Application Note 88: Ceramic Input Capacitors Can Cause Overvoltage Transients](#).

## Output Capacitor and Output Ripple

The output capacitor has two essential functions. Along with the inductor, it filters the square wave generated by the LT83201 to produce the DC output. In this role, it determines the output ripple; thus, a low impedance at the switching frequency is important. The second function is to store energy to satisfy transient loads and stabilize LT83201's control loop. Ceramic capacitors have very low ESR and provide the best ripple performance. For good starting values, see the [Typical Applications](#) section.

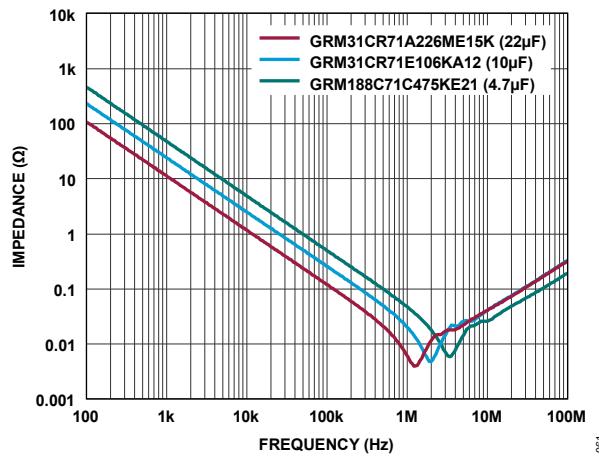
Use X5R or X7R types. This choice provides a low output ripple and good transient response. Transient performance can be improved with a higher-value output capacitor. Increasing output capacitance also decreases the output voltage ripple. A lower value of the output capacitor is used to save space and cost, but transient performance suffers, resulting in loop instability. For the suggested capacitor values, see the [Typical Applications](#) section.

When choosing a capacitor, special attention should be given to the data sheet to calculate the effective capacitance under the relevant operating conditions of voltage bias and temperature. A physically larger capacitor or one with a higher voltage rating may be required.

The LT83201 typically operates at a switching frequency of 2MHz. *Table 5* shows some examples of output capacitors with ideal frequency characteristics when operating at switching frequencies around 2MHz. *Figure 53* shows the frequency characteristics of these capacitors. It can be seen that a combination of these capacitors minimizes the impedance at the switching frequency on the output and keeps the impedance low enough to suppress any higher-frequency harmonics near the switching frequency, thus achieving the lowest output ripple.

**Table 5. Examples of Output Capacitors with Desirable Frequency Characteristics for 2MHz Operation**

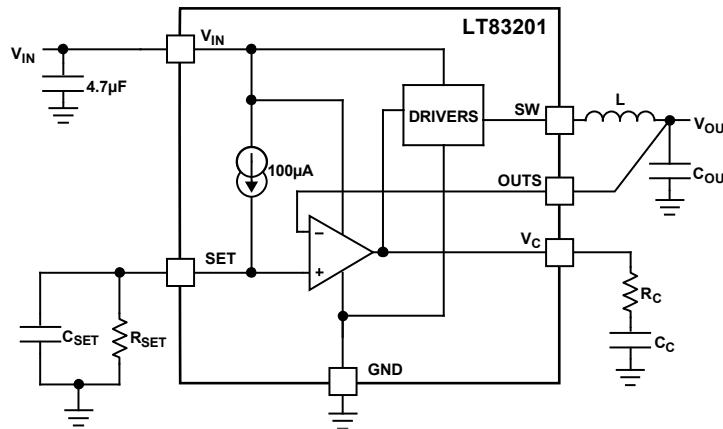
PART DESCRIPTION	MANUFACTURER/PART NUMBER
22 $\mu$ F, X7R, 10V, 20% 1206	MURATA, GRM31CR71A226ME15K
10 $\mu$ F, X7R, 25V, 10% 1206	MURATA, GRM31CR71E106KA12
4.7 $\mu$ F, X7S, 16V, 10% 0603	MURATA, GRM188C71C475KE21



**Figure 53. Frequency Characteristics of Example Output Capacitors for 2MHz Operation**

## Output Voltage

The LT83201 incorporates a precision 100 $\mu$ A current source flowing out of the SET pin, which also connects to the error amplifier's non-inverting input. *Figure 54* shows that connecting a resistor from SET to GND generates a reference voltage for the error amplifier. This reference voltage is simply the product of the SET pin current and the SET pin resistor. The error amplifier's unity-gain configuration produces a low-impedance version of this voltage on its inverting input, the OUTS pin, which is externally connected to the output voltage of the circuit.



**Figure 54. Adjustable Reference for Error Amplifier**

The LT83201's error amplifier and current reference allow for a wide output voltage range from 0V (using a  $0\Omega$  resistor) to 13V. A PNP-based input pair is active from  $V_{OUT}$  equals 0V up to  $V_{IN}$  minus 1.4V, and an NPN-based input pair is active for output voltages where  $V_{IN} - V_{OUT} < 1V$  or less, with a smooth transition between the two input pairs in between these ranges. The PNP-based input pair is designed to offer the best overall performance, as it is active in the vast majority of applications. For more information on offset voltage and SET pin current and output noise, see the *Electrical Characteristics* table. *Table 6* lists many common output voltages and their corresponding 1%  $R_{SET}$  resistors. Where the exact resistor value required for the output voltage is not available, two resistors can be paralleled to achieve the desired value. For example, for a 0.8V output voltage, a resistor value of exactly  $8k\Omega$  is required. The closest value with a single 1% resistor is  $8.06k\Omega$ ; with two resistors,  $8.25k\Omega$  can be paralleled with  $267k\Omega$  to achieve (almost) exactly  $8k\Omega$ . 0.1% resistors may be used to achieve higher accuracy.

**Table 6. 1% Resistor for Common Output Voltages**

$V_{OUT}$ (V)	$R_{SET}$ (k $\Omega$ )
0.8	8.06
1	10
1.8	18
2.5	24.9
3.3	33.2
5	49.9
6	60.4
9	90.9
12	120

The benefit of using a current reference compared with a voltage reference, as used in conventional regulators, is that the regulator always operates in a unity-gain configuration, independent of the programmed output voltage. This allows the LT83201 to have loop gain, frequency response, and bandwidth independent of the output voltage. Moreover, since none of the error amp gain is needed to amplify the SET pin voltage to a higher output voltage, output load regulation is more tightly specified.

Since the zero  $T_c$  current source is highly accurate, the SET pin resistor can become the limiting factor in achieving high accuracy. Hence, it should be a precision resistor. Additionally, any leakage paths to or from the SET pin create errors in the output voltage. If necessary, use high-quality insulation (for example, Teflon, Kel-F); moreover, cleaning of all insulating surfaces to remove fluxes and other residues may be required. High-humidity environments may require a surface coating at the SET pin to provide a moisture barrier.

Since the SET pin is a high-impedance node, unwanted signals may couple into the SET pin and cause erratic behavior. This is most noticeable when operating with a minimum output capacitor at heavy load currents. Bypassing the SET pin with a small capacitance to GND resolves this issue—100nF is sufficient. This is the minimum recommended capacitance. In general, a larger capacitance is typically preferred; for more information, see the *Set Pin Capacitor: Noise and Soft-Start* section.

For applications requiring higher accuracy or an adjustable output voltage, the SET pin may be actively driven by an external voltage source capable of sinking 100 $\mu$ A. Connecting a precision voltage reference to the SET pin eliminates any errors present in the output voltage due to the reference current SET pin resistor tolerances.

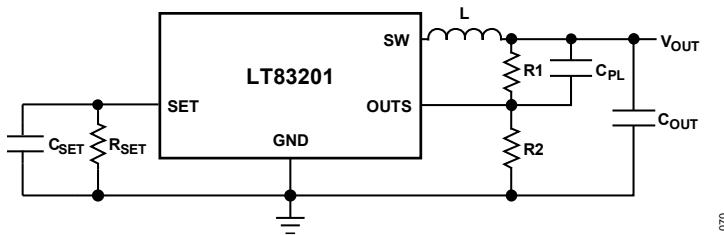
To protect the LT83201's low noise error amplifier, a protection clamp exists between the SET and OUTS pins. This SET-to-OUTS protection clamp limits the maximum voltage between SET and OUTS during transient events, with a maximum DC current of 20mA allowed through the clamp. Therefore, in applications where SET is actively driven by a voltage source, the voltage source must be current limited to 20mA or less.

## Output Voltages Above 13V

The LT83201 can be configured for output voltages above 13V, even though the SET pin voltage is limited to a maximum of 13V, by using a traditional resistor divider from  $V_{OUT}$  to OUTS, as shown in [Figure 55](#). It is recommended to configure the SET pin voltage to be 12V, in which case the resistor values can be chosen according to Equation 9.

$$R1 = R2 \cdot \left( \frac{V_{OUT} - 12V}{12V + R2 \times I_{OUTS}} \right) \quad (9)$$

The OUTS pin current is  $160\text{nA} \pm 80\text{nA}$  per the [Electrical Characteristics](#) table. The divider values R1 and R2 can be chosen such that this OUTS pin current variation introduces  $<0.1\%$  error in output voltage regulation. The thermal noise of the resistors in the resistor divider also adds to the output noise. It is recommended to choose the resistor values such that their impedance as viewed from the SET pin ( $R1||R2$ ) is less than  $5\text{k}\Omega$  to keep their noise contribution low compared to the noise contribution of the part itself.



**Figure 55. Configuring the LT83201 for Output Voltages above 13V**

At output voltages above 13V, the low frequency noise has some dependence on the output voltage, the divider gains up the noise. By configuring the SET voltage to be 12V, this dependency is minimized, for example, the noise gain from a 12V reference to  $15V_{OUT}$  is 24 times lower than the gain from a conventional 0.5V voltage reference to  $15V_{OUT}$ .

## Output Voltages Below 0.5V

Due to the current reference architecture, the LT83201 can be configured for output voltages below 0.5V all the way down to 0V. It should be noted that for output voltages below 0.5V, the Power Good and Fast Start-Up functionalities are not available, and these functionalities must be disabled correctly by tying PGFB to INTV<sub>CC</sub> or to 0.5V.

## Output Sensing and Stability

The LT83201's OUTS pin provides a Kelvin sense connection to the output. The SET pin resistor's GND side provides a Kelvin sense connection to the load's GND side.

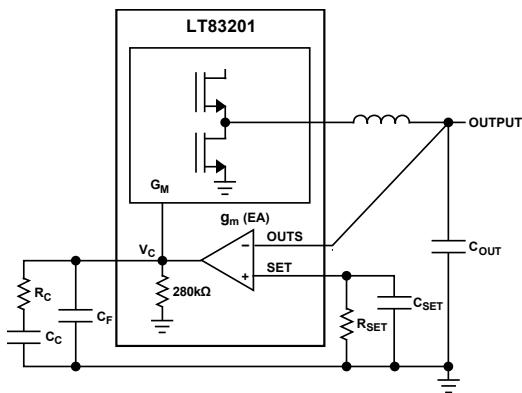
The LT83201's internal error amplifier has a relatively high voltage gain of  $\sim 2800$ . Therefore, it is important to avoid adding extra impedance (ESR and ESL) to the feedback loop and to minimize the noise coupling onto the OUTS pin, as a combination of excessive parasitics and noise injection can cause instability in the system. To that end, minimize the effects of PCB trace and solder inductance by tying the OUTS pin directly to  $C_{OUT}$  and the GND side of  $C_{SET}$  directly to the GND side of  $C_{OUT}$ . If this is not possible, for example, due to a design requiring remote sensing, a small local OUTS capacitor of 150pF or less may be added for noise decoupling at the OUTS pin. For more information on the recommended layout that meets these requirements, refer to the LT83201 demo board manual.

The LT83201 is an externally compensated part, so even if the recommended layout is not followed (sometimes it is not possible due to application-specific limitations), it is possible to choose a more conservative compensation with a lower gain or bandwidth in order to retain stability during operation. However, this is at the expense of a transient response. A superior layout allows a better tradeoff between transient response, phase margin, and output noise performance when selecting compensation values.

## Frequency Compensation

The loop compensation determines the stability and transient performance and is provided by the components connected to the  $V_C$  pin. Generally, a capacitor ( $C_C$ ) and a resistor ( $R_C$ ) in series to ground are used. Designing the compensation network can be complicated, and the best values depend on the application. A practical approach is to start with one of the circuits in this data sheet that is similar to user's application and tune the compensation network to optimize the performance. LTpowerCAD simulation can help in this process. Stability should then be checked across all operating conditions, including load current, input voltage, and temperature. The [LT1375](#) data sheet contains a more thorough discussion of loop compensation and describes how to test the stability using a transient load.

[Figure 56](#) shows an equivalent circuit for the LT83201 control loop. The error amplifier is a transconductance amplifier with transconductance  $g_m = 12\text{mS}$ , with finite output impedance. The power section, consisting of the modulator, power switches, and inductor, is modeled as a transconductance amplifier with transconductance  $G_M = 2.3\text{A/V}$ , generating an output current proportional to the voltage at the  $V_C$  pin. Note that the output capacitor integrates this current and that the capacitor on the  $V_C$  pin ( $C_C$ ) integrates the error amplifier output current, resulting in two poles in the loop. A zero is required and comes from a resistor  $R_C$  in series with  $C_C$ . This simple model works as long as the value of the inductor is not too high and the loop crossover frequency is much lower than the switching frequency. For more information about the compensation of switching mode power supplies, refer to [Application Note 149: Modeling and Loop Compensation Design of Switching Mode Power Supplies](#).



**Figure 56. Model for Loop Response**

## EN/UVLO Pin

The LT83201 is in shutdown when the EN/UVLO pin is low and active when the pin is high. The rising threshold of the EN/UVLO comparator is 0.75V, with 50mV of hysteresis. The EN/UVLO pin can be connected to  $V_{IN}$  if the shutdown feature is not used or tied to a logic level if shutdown control is required. If connecting the EN/UVLO pin to  $V_{IN}$  instead of driving it with a digital signal, it is recommended to connect EN/UVLO to  $V_{IN}$  through a resistor divider to set an appropriate UVLO threshold. This ensures correct startup and shutdown behavior in the event of rapid power cycling.

When the enable pin drops below 0.7V, the part stops switching, but internal circuitry continues drawing current as the  $\text{INTV}_{CC}$  regulator is still awake. A full shutdown is guaranteed when the enable pin drops below 200mV. In full shutdown, the  $\text{INTV}_{CC}$  regulator is disabled, and the part draws less than 60 $\mu\text{A}$ .

Adding a resistor divider from  $V_{IN}$  to EN/UVLO programs the LT83201 to regulate the output only when  $V_{IN}$  is above the required voltage (see the [Block Diagram](#)). This threshold,  $V_{IN(\text{EN})}$ , is typically used when the input supply is either current limited or has a relatively high source resistance. A switching regulator draws constant power from the source, so the source current increases as the source voltage drops. This looks like a negative resistance load to the

source and causes the source to current limit or latch low under low source voltage conditions. The  $V_{IN(EN)}$  threshold prevents the regulator from operating at source voltages where the problems might occur. This threshold can be adjusted by setting the values of  $R_{EN1}$  and  $R_{EN2}$  such that they satisfy Equation 10.

$$V_{IN(EN)} = \left( \frac{R_{EN1}}{R_{EN2}} + 1 \right) \times 0.75V \quad (10)$$

where the LT83201 remains off until  $V_{IN}$  is above  $V_{IN(EN)}$ . Due to the comparator's hysteresis, switching does not stop until the input falls slightly below  $V_{IN(EN)}$ .

## INTV<sub>cc</sub> Regulator

An internal low dropout (LDO) regulator produces the 3.4V supply from  $V_{IN}$  that powers the drivers and the internal bias circuitry. The INTV<sub>cc</sub> supplies enough current for the LT83201's circuitry. The voltage on INTV<sub>cc</sub> varies between 2.6V and 3.4V when  $V_{IN}$  is between 2.7V and 3.5V. Do not connect an external load to the INTV<sub>cc</sub> pin.

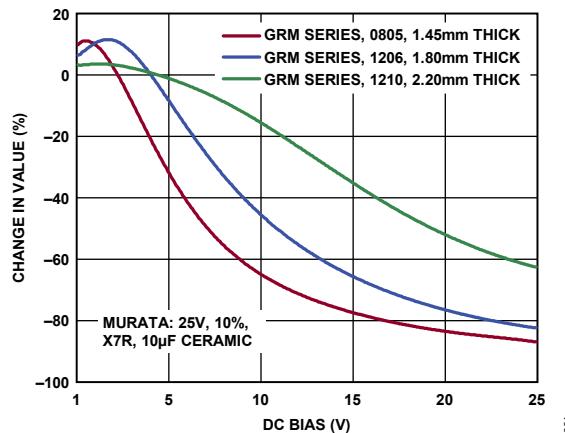
## Set Pin Capacitor: Noise and Soft-Start

In addition to reducing output noise, using a SET pin bypass capacitor reduces the sensitivity to any parasitic coupling of voltage spikes onto the SET pin. Note that any bypass capacitor leakage deteriorates the LT83201's DC regulation. Capacitor leakage of even 100nA is a 0.1% DC error. Therefore, it is recommended to use a good quality, low leakage ceramic capacitor.

Using a SET pin bypass capacitor also soft-starts the output and limits inrush current. Soft-starting the output prevents a current surge on the input supply. The SET pin capacitor and resistor values set the ramp-up time of the reference voltage, and the output voltage tracks this voltage. The SET pin resistor size is determined by the application's required output voltage; however, the capacitor size may be selected to achieve the desired ramp-up time. It is important to consider that the size of the SET pin capacitor also plays a role in noise performance, which is typically the more important factor in determining the size of this capacitor.

Ceramics are manufactured with a variety of dielectrics, each with a different behavior across temperature and applied voltage. Care should be taken when selecting a ceramic capacitor for bypassing the SET pin, as this is a critical component. An X7R (or better) ceramic capacitor is strongly recommended for its superior stability across temperature and DC voltage bias. Additionally, larger case sizes are recommended for better DC bias and AC voltage characteristics.

As shown in *Figure 57*, capacitor DC bias characteristics tend to improve as component case size increases.



**Figure 57. Capacitor Voltage Coefficient for Different Case Sizes**

Larger case sizes are also beneficial for improved AC voltage characteristics. Capacitor values are often rated at  $1V_{RMS}$  of AC voltage, and can drop significantly when operating near  $0V_{RMS}$ , which is the operating condition of a bypass capacitor.

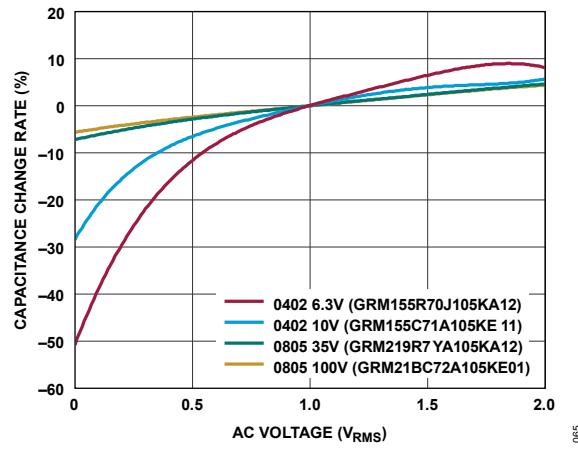
As shown in *Figure 58*, larger case sizes tend to experience a smaller capacitance drop when operating near  $0V_{RMS}$ . Therefore, an 0805 or larger ceramic capacitor should be used for the SET pin bypass capacitor for best performance. A larger required capacitance value may require larger case sizes; for example, a  $4.7\mu F$  value should use 1206 or larger.

*Table 7* shows some recommended SET pin capacitors.

**Table 7. Suggested SET Capacitor Part Numbers**

PART DESCRIPTION	MANUFACTURER/PART NUMBER
1 $\mu F$ , X7R, 35V, 0805	MURATA, GRM219R7YA105KA12
4.7 $\mu F$ , X7R, 50V, 1206	MURATA, GRM31CR71H475MA12
10 $\mu F$ , X7R, 100V, 1210	MURATA, GRM32EC72A106KE05

For high vibration environments, non-piezoelectrically responsive capacitors should be used at the SET pin for optimal performance. A piezoelectric ceramic capacitor generates voltage across its terminals due to mechanical stress upon it, induced by mechanical vibrations or thermal transients. Film capacitors are the preferred option. If a ceramic must be used, soft-termination ceramics are available, which reduce the sensitivity to the piezoelectric effect.



**(a) Rated Capacitance = 1 $\mu F$**

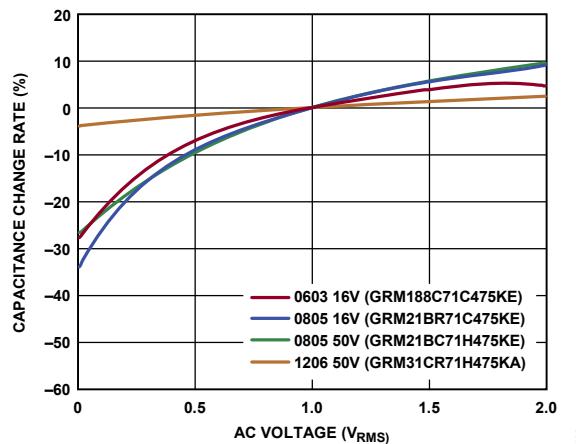
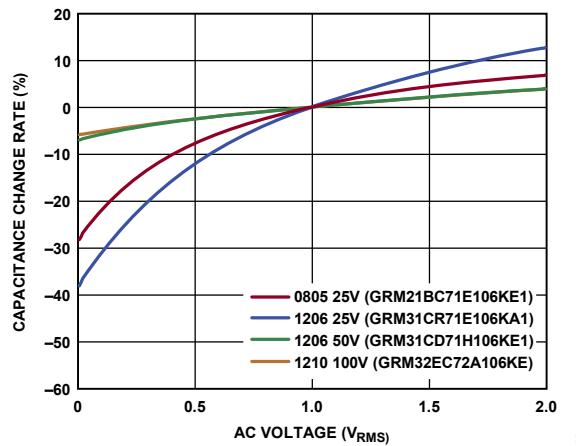
(b) Rated Capacitance =  $4.7\mu\text{F}$ (c) Rated Capacitance =  $10\mu\text{F}$ 

Figure 58. AC Voltage Characteristics for Different Capacitor Case Sizes

Without fast start-up enabled, the  $R_c$  time constant, formed by the SET pin resistor and capacitor, controls soft-start time. Connect the PGFB pin to  $INTV_{CC}$  or to 0.5V to disable fast start-up. The ramp-up rate from 0% to 90% of nominal  $V_{OUT}$  is given by Equation 11.

$$t_{START\_NO\_FAST\_START-UP} = 2.3 \times R_{SET} \times C_{SET} \quad (11)$$

With fast-start-up enabled, the start-up time can be significantly reduced, with the ramp-up time from 0% to 90% of the nominal  $V_{OUT}$  given by Equation 12. For how the 2.7mA fast start-up current varies with temperature and  $V_{IN} - V_{SET}$  differential voltage, see the *Typical Performance Characteristics* section.

$$t_{START\_FAST\_START-UP} = \frac{100\mu A \times R_{SET} \times C_{SET}}{2.7mA} \quad (12)$$

In most applications, fast start-up is enabled, in which case a minimum SET capacitor size of 1 $\mu$ F is recommended for preventing reference voltage overcharge as well as ensuring good noise performance.

The SET pin is pulled to ground with a 520 $\Omega$  MOSFET ( $R_{SET-PULLDOWN}$ ) during shutdown, thermal shutdown,  $V_{CC}$  UVLO or  $V_{IN}$  UVLO. To ensure soft-start when the part exits any of the above conditions, there must have been sufficient time to allow the SET pin to be pulled to close to ground prior to start-up. This time will be a function of the chosen SET pin capacitance and  $R_{SET-PULLDOWN}$ .

## Fast Start-Up

For ultra-low noise applications that require low 1/f noise (that is, at frequencies below 100Hz), a larger value SET pin capacitor is required, up to 22 $\mu$ F. A larger value capacitor can be used, but care should be taken regarding leakage. While normally larger capacitors significantly increase the regulator's start-up time, the LT83201 incorporates fast start-up circuitry that increases the SET pin current to about 2.7mA during start-up.

Upon start-up, the 2.7mA current source remains engaged while PGFB is below the power good start-up threshold ( $V_{PGL\_STARTUP}$ ) of 486.5mV, unless the regulator is in thermal shutdown,  $V_{IN}$  is too low, or  $INTV_{CC}$  has fallen too low.

The fast start-up circuit is permanently disabled once PGFB rises above  $V_{PGL\_STARTUP}$  until either the part is powered down, or the part is placed into shutdown by pulling the EN/UVLO pin below 0.75V.

There is one more condition under which the 2.7mA current source is disabled during start-up. The purpose of this is to prevent overcharging  $V_{SET}$ . Since the part assumes that the PGFB pin is an accurate indication of the voltage on the SET pin, it assumes that  $V_{OUTS}$  follows  $V_{SET}$  closely. However, this may not always be the case; for example, if the output capacitance is very large or if, for some reason, the output is temporarily shorted to the GND. Therefore, fast charge is disabled whenever  $V_{OUTS}$  is lagging  $V_{SET}$  by more than 30mV. This prevents incorrect behavior where the 2.7mA current source stays on even when  $V_{SET}$  has risen above its intended final value.

If programmable power good and fast start-up capabilities are not required, the PGFB pin must be connected to either  $INTV_{CC}$  or to 0.5V.

## Programmable Power Good

As shown in the *Block Diagram*, the power good threshold is user programmable using the ratio of two external resistors,  $R_{PGFB(BOT)}$  and  $R_{PGFB(TOP)}$  (see Equation 13).

$$V_{OUT(PG\_THRESHOLD)} = 0.5V \times \left(1 + \frac{R_{PGFB(TOP)}}{R_{PGFB(BOT)}}\right) + I_{PGFB} \times R_{PGFB(TOP)} \quad (13)$$

If the PGFB pin increases above 537.5mV or decreases below 462.5mV, the open-drain PG pin asserts and becomes low impedance, indicating power is bad. The power good comparator has hysteresis of 10mV. The PGFB pin current

( $I_{PGFB}$ ) from the *Electrical Characteristics* table must be considered when determining the resistor divider network. Note that the programmable power good and fast start-up capabilities are disabled when PGFB is tied to 0.5V or when the device is in shutdown.

The PGFB pin current ( $I_{PGFB}$ ) can be ignored if  $R_{PGFB(BOT)}$  is less than 50k $\Omega$ . *Table 8* suggests some 1% PGFB resistor divider values for common  $V_{OUT}$  configurations.

**Table 8. Suggested PGFB Resistor Divider Values**

$V_{OUT}$ (V)	$R_{PGFB(TOP)}$ (k $\Omega$ )	$R_{PGFB(BOT)}$ (k $\Omega$ )
0.8	29.4	48.7
0.9	39.2	48.7
1	49.9	49.9
1.2	69.8	49.9
1.8	130	49.9
3.3	280	49.9
5	453	49.9

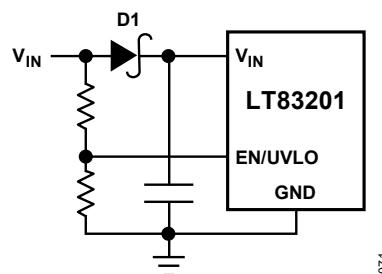
## Shorted and Reversed Input Protection

The LT83201 tolerates a shorted output. The bottom switch current is monitored such that if the inductor current is beyond safe levels, switching on of the top switch is delayed until the inductor current falls to safe levels.

There is another situation to consider in systems where the output is held high when the input to the LT83201 is absent. This occurs in battery charging applications or in battery backup systems where a battery or some other supply is diode ORed with the LT83201's output. If the  $V_{IN}$  pin is allowed to float and the EN/UVLO pin is held high, then the LT83201's internal circuitry pulls its quiescent current through its SW pin. This is acceptable if the system can tolerate current draw in this state. If the EN/UVLO pin is grounded, the SW pin current drops to  $\sim 40\mu A$ .

However, if the  $V_{IN}$  pin is grounded while the output is held high, regardless of EN/UVLO, parasitic body diodes inside the LT83201 can pull current from the output through the SW pin and the  $V_{IN}$  pin.

*Figure 59* shows a connection of the  $V_{IN}$  and EN/UVLO pins, which allows the LT83201 to run only when the input voltage is present and protects against a shorted or reversed input.



**Figure 59. Reverse  $V_{IN}$  Protection**

## Thermal Considerations

For higher ambient temperatures, care should be taken in the layout of the PCB to ensure good heat sinking of the LT83201. The exposed pad on the bottom of the package should be soldered to a ground plane. This ground should be connected to large copper layers below with thermal vias, these layers spread heat dissipated by the LT83201. Placing additional vias can reduce thermal resistance further. The maximum load current should be derated as the ambient temperature approaches the maximum junction rating. Power dissipation within the LT83201 can be estimated by calculating the total power loss from an efficiency measurement and subtracting the inductor loss. The die temperature is calculated by multiplying the LT83201 power dissipation by the thermal resistance from junction to ambient.

The internal overtemperature protection monitors the junction temperature of the LT83201. If the junction temperature reaches approximately 165°C, the LT83201 stops switching and indicates a fault condition until the temperature drops about 5°C cooler.

Temperature rise of the LT83201 is at its worst when operating at high load, high  $V_{IN}$ , and high switching frequency. If the case temperature is too high for a given application, then either  $V_{IN}$ , switching frequency, or load current can be decreased to reduce the temperature to an appropriate level. *Figure 60* shows examples of how case temperature rise can be managed by reducing load.

The LT83201's top switch current limit decreases with higher duty cycle operation for slope compensation. This also limits the output current the LT83201 can deliver for a given application. See curve in *Typical Performance Characteristics*.

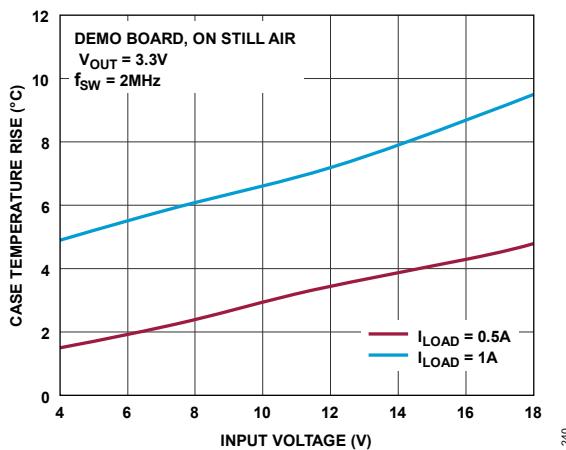
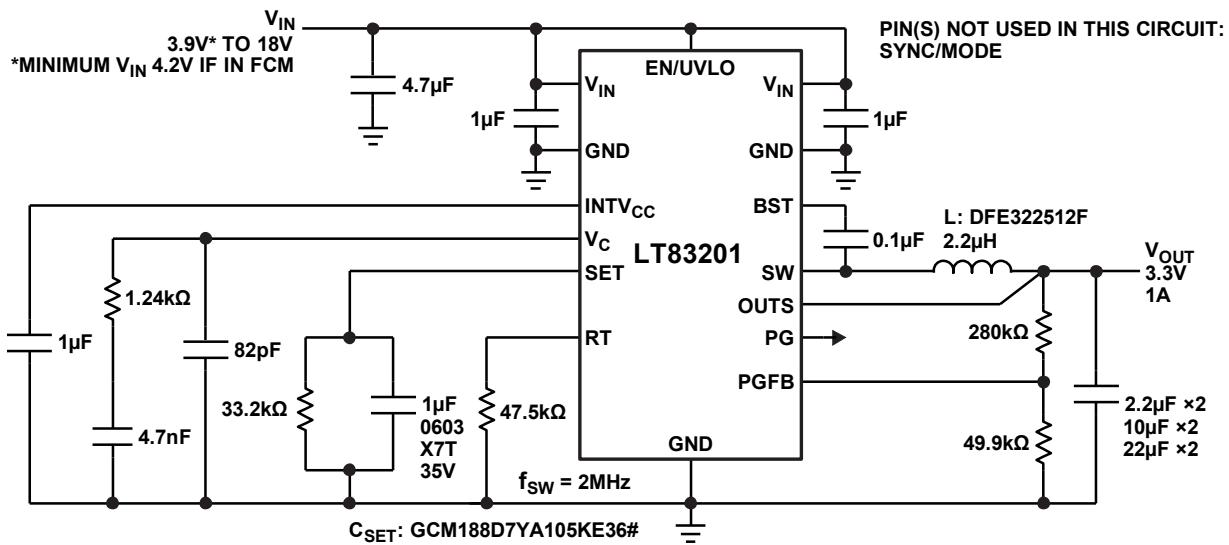


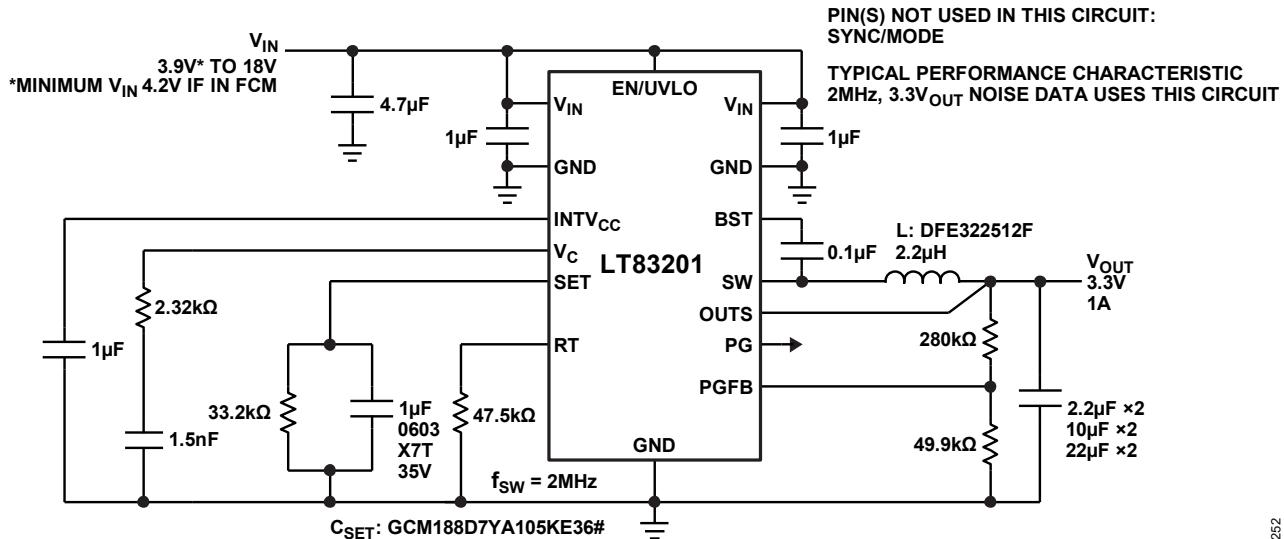
Figure 60. LT83201 Case Temperature Rise

## TYPICAL APPLICATIONS



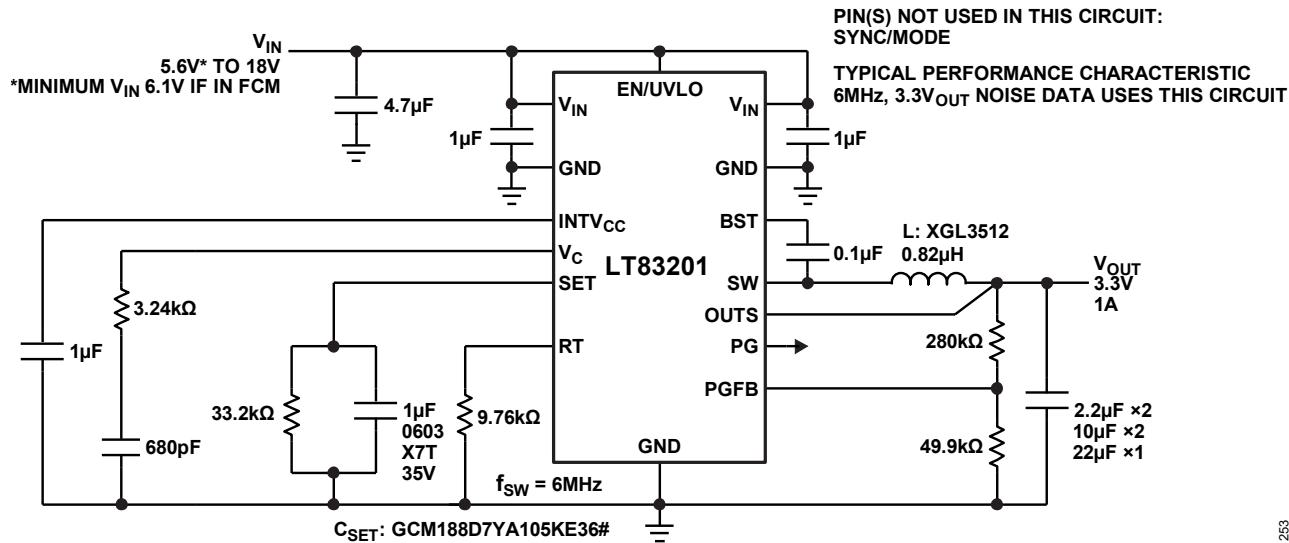
251

Figure 61. 3.3V 1A 2MHz Step-Down Converter with Soft-Start, Fast Start-Up and Power Good



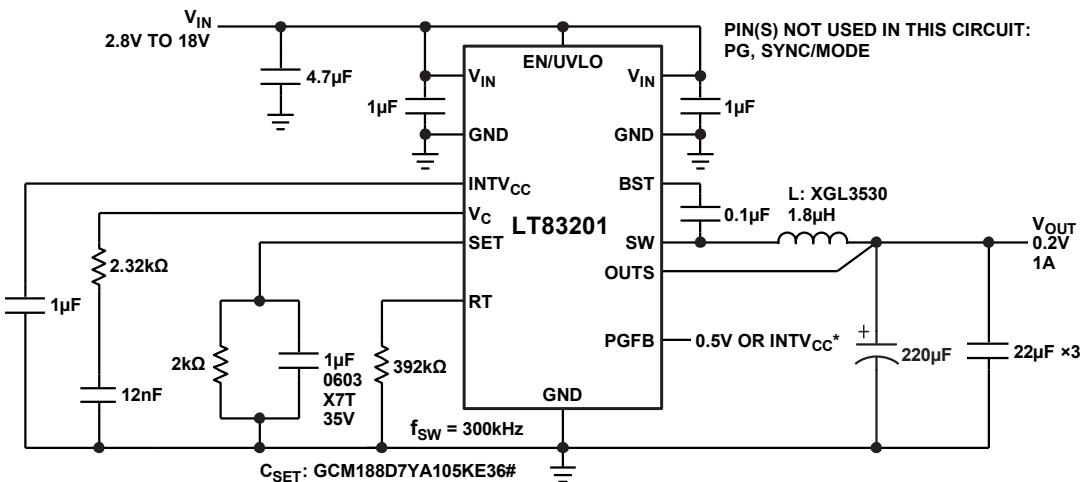
252

Figure 62. 3.3V 1A 2MHz Step-Down Converter with High Bandwidth, Soft-Start, Fast Start-Up and Power Good



253

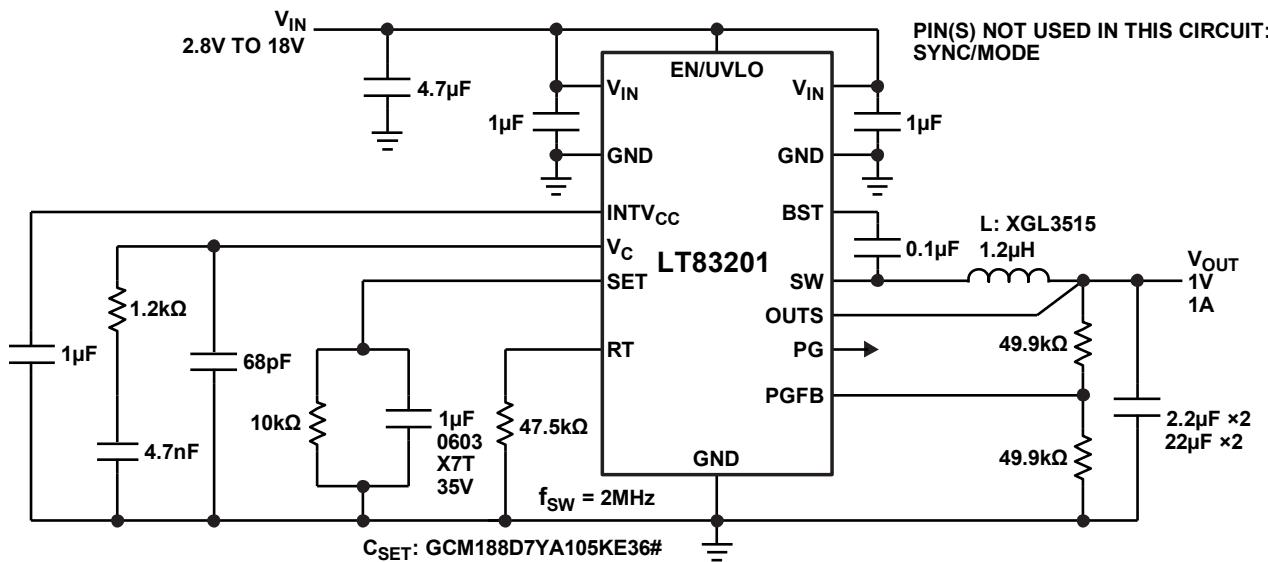
Figure 63. 3.3V 1A 6MHz Step-Down Converter with Soft-Start, Fast Start-Up and Power Good



254

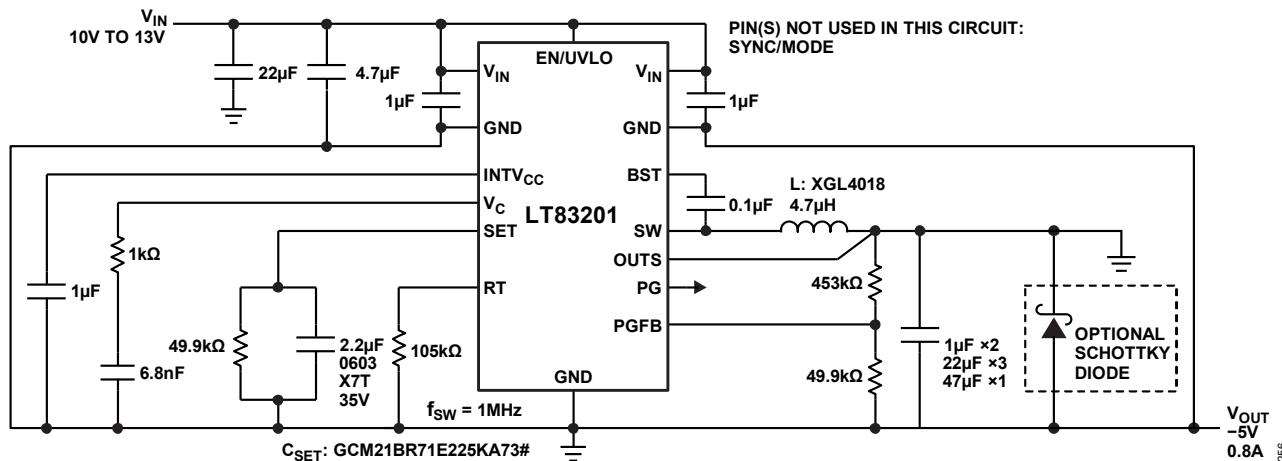
\*NOTE THAT APPLICATIONS WITH V<sub>OUT</sub> BELOW 0.5V WILL NOT BE ABLE TO USE THE POWER GOOD AND FAST START-UP FUNCTIONALITIES AND MUST TIE PGFB TO 0.5V or INTV<sub>CC</sub> TO DISABLE THESE FUNCTIONS CORRECTLY.

Figure 64. 0.2V 1A 300kHz Step-Down Converter with Soft-Start



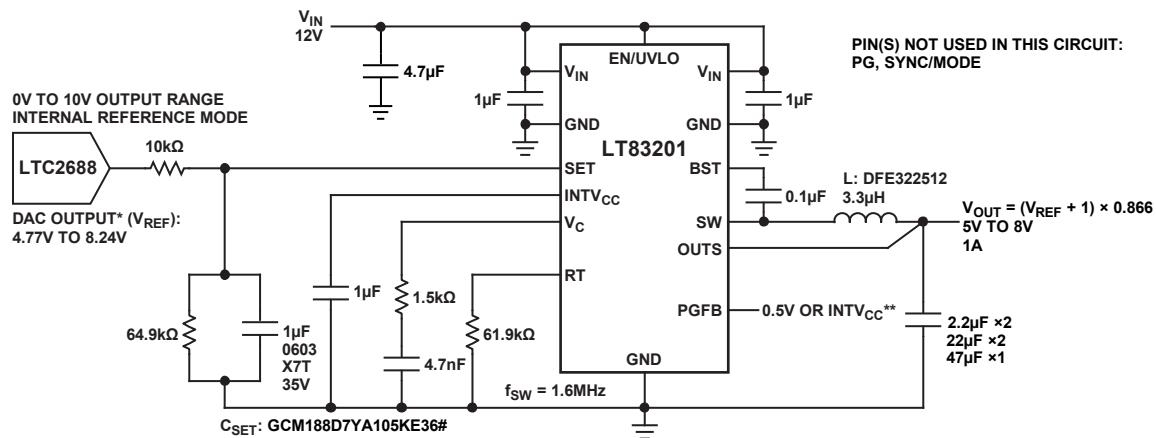
255

Figure 65. 1V 1A 2MHz Step-Down Converter with Soft-Start, Fast Start-Up, Power Good



256

Figure 66. Negative 5V 0.8A 1MHz Step-Down Converter with Soft-Start, Fast Start-Up and Power Good



\*NOTE: DAC OUTPUT SHOULD BE ABLE TO SOURCE AND SINK 1mA CURRENT.

\*NOTE: APPLICATIONS WITH DYNAMIC VOLTAGE CONTROL WILL NOT BE ABLE TO USE THE POWER GOOD AND FAST START-UP FUNCTIONALITIES AND MUST TIE PGFB TO 0.5V or INTV<sub>CC</sub> TO DISABLE THESE FUNCTIONS CORRECTLY.

NOTE: CONTACT FACTORY FOR LT83201-2 WHICH DISABLES THE 100μA SET PIN CURRENT FOR IMPROVED DYNAMIC VOLTAGE CONTROL ACCURACY AND QUIESCENT CURRENT.

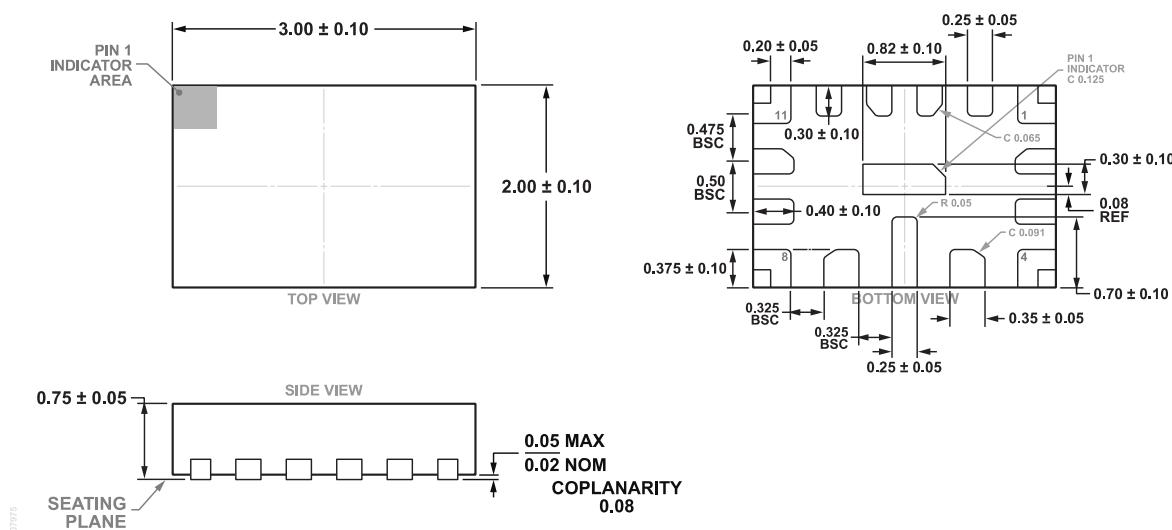
257

Figure 67. Dynamic Output Voltage Control 5V to 8V 1A 1.6MHz Step-Down Converter with External DAC

## OUTLINE DIMENSIONS



15-Lead Lead Frame Chip Scale Package [LFCSP]  
3 x 2 mm Body and 0.75 mm Package Height  
(CP-15-1)  
Dimensions shown in millimeters



PN-0001735

10-16-2023-A

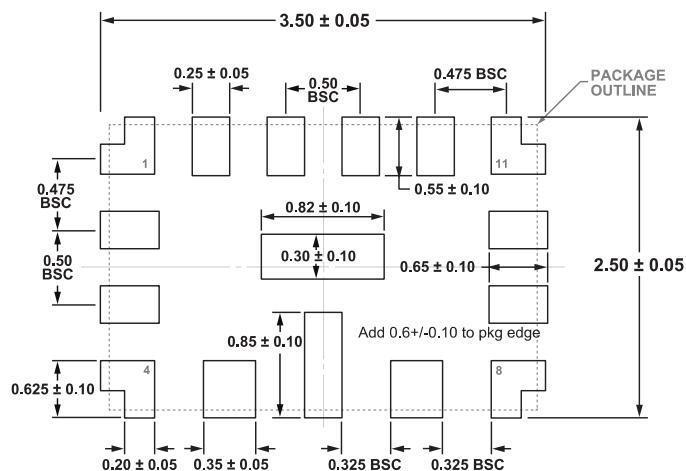
RECOMMENDED SOLDER PAD LAYOUT  
(TOP VIEW)

Figure 68. Tiny 15-Lead 3mm × 2mm LFCSP

## ORDERING GUIDE

**Table 9. Ordering Guide**

TAPE AND REEL (MINI)*	TAPE AND REEL**	PAD OR BALL FINISH***	PART MARKING****		PACKAGE TYPE*****	MSL RATING	TEMPERATURE RANGE*****
			DEVICE	FINISH CODE			
LT83201AUDB#TRMPBF	LT83201AUDB#TRPBF	Au (RoHS)	LHWK	e4	LFCSP (Lead Frame Chip Scale Package)	1	-40°C to 125°C

- \*Parts ending with PBF are RoHS and WEEE compliant.
- \*\*Tape and reel specifications. Some packages are available in 500-unit reels through designated sales channels with #TRMPBF suffix.
- \*\*\*Pad or ball finish code is per IPC/JEDEC J-STD-609.
- \*\*\*\*The temperature grade is identified by a label on the shipping container.
- \*\*\*\*\*The LT83201 package has the same dimensions as a standard 3mm × 2mm LFCSP package.
- \*\*\*\*\*The LT83201 is specified over the -40°C to 125°C operating junction temperature range. High junction temperatures degrade operating lifetimes. The junction temperature ( $T_J$ , in °C) is calculated from the ambient temperature ( $T_A$  in °C) and power dissipation ( $P_D$ , in Watts) according to the formula:  $T_J = T_A + (P_D \times \theta_{JA})$ , where  $\theta_{JA}$  (in °C/W) is the package thermal impedance.
- For recommended LGA and BGA PCB assembly and manufacturing procedures, refer to the [Recommended LGA and BGA PCB Assembly and Manufacturing Procedures](#).
- For LGA and BGA package and tray drawings, refer to the [LGA and BGA Package and Tray Drawings](#).

## RELATED PARTS

**Table 10. Related Parts**

PART	DESCRIPTION	COMMENTS
<a href="#">LT83203/5</a>	18V, 3A/5A Synchronous Step-Down Silent Switcher 3 with Ultra-Low Noise Reference	4µV <sub>RMS</sub> Noise, $V_{IN} = 2.8V$ to 18V, $V_{OUT(MIN)} = 0V$ , 3mm × 2mm LFCSP-15
<a href="#">LT8622S/</a> <a href="#">LT8624S</a>	18V, 2A/4A Synchronous Step-Down Silent Switcher 3 with Ultra-Low Noise Reference	4µV <sub>RMS</sub> Noise, $V_{IN} = 2.7V$ to 18V, $V_{OUT(MIN)} = 0V$ , 4mm × 3mm LQFN-20
<a href="#">LT8625S</a>	18V/8A Synchronous Step-Down Silent Switcher 3 with Ultra-Low Noise Reference	4µV <sub>RMS</sub> Noise, $V_{IN} = 2.7V$ to 18V, $V_{OUT(MIN)} = 0V$ , 4mm × 3mm LQFN-20
<a href="#">LT8625SP/</a> <a href="#">LT8625SP-1</a>	18V/8A Synchronous Step-Down Silent Switcher 3 with Ultra-Low Noise Reference	4µV <sub>RMS</sub> Noise, $V_{IN} = 2.7V$ to 18V, $V_{OUT(MIN)} = 0V$ , 4mm × 3mm LQFN-20 or 4mm × 4mm LQFN-24
<a href="#">LT8627SP</a>	18V/16A Synchronous Step-Down Silent Switcher 3 with Ultra-Low Noise Reference	4µV <sub>RMS</sub> Noise, $V_{IN} = 2.8V$ to 18V, $V_{OUT(MIN)} = 0V$ , 4mm × 4mm LQFN-24
<a href="#">LT8642S</a>	18V, 10A Synchronous Step-Down Silent Switcher 2 Regulator	96% Efficiency, $V_{IN} = 2.8V$ to 18V, $V_{OUT(MIN)} = 0.6V$ , $I_Q = 240\mu A$ , $I_{SD} < 1\mu A$ , 4mm × 4mm LQFN-24
<a href="#">LTC7151S</a>	20V, 15A Synchronous Step-Down Silent Switcher 2 Regulator	92.5% Efficiency, $V_{IN} = 3.1V$ to 20V, $V_{OUT(MIN)} = 0.5V$ , $I_Q = 2mA$ , $I_{SD} < 20\mu A$ , 4mm × 5mm LQFN-28

<a href="#">LTC7150S</a>	20V, 20A Synchronous Step-Down Silent Switcher 2 Regulator	92% Efficiency, $V_{IN} = 3.1V$ to 20V, $V_{OUT(MIN)} = 0.6V$ , $I_Q = 2mA$ , $I_{SD} \leq 40\mu A$ , Differential Remote Sense, 6mm × 5mm BGA
<a href="#">LT3042</a>	20V, 200mA, Ultra-Low Noise Ultra-High PSRR Linear Regulator	0.8 $\mu V_{RMS}$ Noise and 79dB PSRR at 1MHz, $V_{IN} = 1.8V$ to 20V, 350mV Dropout Voltage, Programmable Current Limit and Power Good, 3mm × 3mm DFN and MSOP Packages
<a href="#">LT3045</a>	20V, 500mA, Ultra-Low Noise Ultra-High PSRR Linear Regulator	0.8 $\mu V_{RMS}$ Noise and 75dB PSRR at 1MHz, $V_{IN} = 1.8V$ to 20V, 260mV Dropout Voltage, 3mm × 3mm DFN and MSOP Packages
<a href="#">LT8652S</a>	18V, Dual 8.5A, 94% Efficiency, 2.2MHz Synchronous Silent Switcher 2 Step-Down DC/DC Converter with $I_Q = 16\mu A$	$V_{IN} = 3V$ to 18V, $V_{OUT(MIN)} = 0.6V$ , $I_Q = 16\mu A$ , $I_{SD} = 6\mu A$ , 4mm × 7mm LQFN-36 Package
<a href="#">LTC3636</a>	20V, Dual 6A Synchronous Step-Down Regulator	95% Efficiency, $V_{IN} = 3.1V$ to 17V, $V_{OUT(MIN)} = 0.6V$ , $I_Q < 8\mu A$ (Both Channels Enabled), $I_{SD} < 1\mu A$ , 3mm × 5mm QFN-24 Package
<a href="#">LT8640S/</a> <a href="#">LT8643S</a>	42V, 6A Synchronous Step-Down Silent Switcher 2 with $I_Q = 2.5\mu A$	$V_{IN(MIN)} = 3.4V$ , $V_{IN(MAX)} = 42V$ , $V_{OUT(MIN)} = 0.97V$ , $I_Q = 2.5\mu A$ , $I_{SD} < 1\mu A$ , 4mm × 4mm LQFN-24
<a href="#">LT8645S/</a> <a href="#">LT8646S</a>	65V, 8A, Synchronous Step-Down Silent Switcher 2 with $I_Q = 2.5\mu A$	$V_{IN(MIN)} = 3.4V$ , $V_{IN(MAX)} = 65V$ , $V_{OUT(MIN)} = 0.97V$ , $I_Q = 2.5\mu A$ , $I_{SD} < 1\mu A$ , 6mm × 4mm LQFN-32
<a href="#">LT8609/</a> <a href="#">LT8609A</a>	42V, 2A, 94% Efficiency, 2.2MHz Synchronous MicroPower Step-Down DC/DC Converter with $I_Q = 2.5\mu A$	$V_{IN(MIN)} = 3V$ , $V_{IN(MAX)} = 42V$ , $V_{OUT(MIN)} = 0.8V$ , $I_Q = 2.5\mu A$ , $I_{SD} < 1\mu A$ , MSOP-10E

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