

## MAX17760

## 4.5V to 76V, 300mA, High-Efficiency, Synchronous Step-Down DC-DC Converter

### General Description

The Himalaya series of voltage regulator ICs, power modules, and chargers enable cooler, smaller, and simpler power supply solutions. The MAX17760/MAX17760A are high-efficiency, high-voltage, Himalaya synchronous step-down DC-DC converters with integrated MOSFETs that operate over a 4.5V to 76V input-voltage range. They can deliver up to 300mA current. Output voltage is programmable from 0.8V up to 88% of input voltage ( $V_{IN}$ ). Built-in control loop compensation eliminates the need for external components.

The MAX17760/MAX17760A feature a peak-current-mode control architecture. The devices can be operated in either the forced pulse-width modulation (PWM) or pulse-frequency modulation (PFM) control schemes. Forced PWM mode provides constant frequency operation at all loads for frequency sensitive applications, while PFM mode provides superior light-load efficiency by skipping pulses. The devices integrate an open-drain  $\overline{\text{RESET}}$  output voltage monitor, adjustable input undervoltage lockout (EN/UVLO), and programmable soft-start.

The feedback voltage regulation accuracy over  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$  is  $+1.6\%$  to  $-1.7\%$ . These devices are available in a compact 12-pin (3mm x 3mm) TDFN package. Simulation models are available.

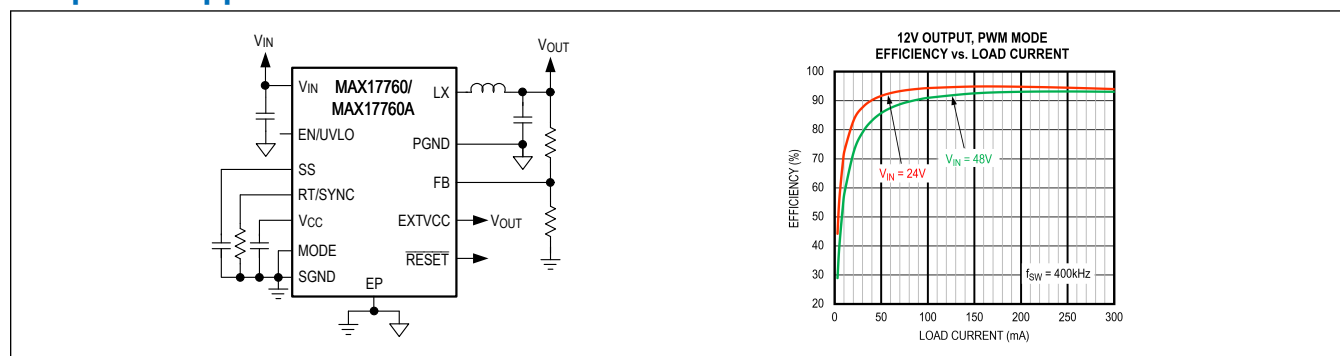
### Applications

- Industrial Control Power Supplies
- General Purpose Point-of-Load
- Distributed Supply Regulation
- Base Station Power Supplies
- Wall Transformer Regulation
- High Voltage Single-Board Systems

### Benefits and Features

- Reduces External Components and Total Cost
  - No Schottky - Synchronous Operation
  - Internal Compensation Components
  - All-Ceramic Capacitors, Compact Layout
- Reduces Number of DC-DC Regulators to Stock
  - Wide 4.5V to 76V Input
  - Adjustable Output Range from 0.8V up to 88% of  $V_{IN}$
  - Up to 300mA Output Current
  - 200kHz, 300kHz, 400kHz, and 600kHz Programmable Switching Frequency with External Clock Synchronization.
- Reduces Power Dissipation
  - 93% Peak Efficiency
  - PFM Mode Enables Enhanced Light-Load Efficiency
  - EXTVCB Bootstrap Input for Improved Efficiency
  - 5 $\mu\text{A}$  Shutdown Current
- Operates Reliably in Adverse Industrial Environments
  - Built-in Hiccup Mode Overload Protection—MAX17760
  - Programmable Soft-Start and Prebiased Power-up
  - Built-in Output-Voltage Monitoring with  $\overline{\text{RESET}}$
  - Programmable EN/UVLO Threshold
  - Overtemperature Protection
  - CISPR 22 Class B Compliant
  - Wide  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$  Ambient Operating Temperature Range/  $-40^{\circ}\text{C}$  to  $+150^{\circ}\text{C}$  Junction Temperature Range

### Simplified Application Circuit



**Ordering Information** appears at end of data sheet.

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## Absolute Maximum Ratings

$V_{IN}$ to SGND	-0.3V to +80V
EN/UVLO to SGND	-0.3 to $\min((V_{IN} + 0.3V), 26V)$
EXTVCC to SGND	-0.3V to +26V
LX to PGND	-0.3 to $(V_{IN} + 0.3V)$
FB, RESET, SS, MODE, $V_{CC}$ , RT/SYNC to SGND	-0.3V to +6V
PGND to SGND	-0.3V to +0.3V
LX Total RMS Current	$\pm 0.6A$

Continuous Power Dissipation (Multilayer Board) ( $T_A = +70^\circ C$ , derate 24.4mW/ $^\circ C$ above $+70^\circ C$ )	1951.2mW
Output Short-Circuit Duration	Continuous
Operating Temperature Range (Note 1)	$-40^\circ C$ to $+125^\circ C$
Junction Temperature	$+150^\circ C$
Storage Temperature Range	$-65^\circ C$ to $+150^\circ C$
Lead Temperature (soldering, 10s)	$+300^\circ C$
Soldering Temperature (reflow)	$+260^\circ C$

**Note 1:** Junction temperature greater than  $+125^\circ C$  degrades operating lifetimes.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## Package Information

### 12 TDFN

Package Code	TD1233+1C
Outline Number	<a href="#">21-0664</a>
Land Pattern Number	<a href="#">90-0397</a>
<b>Thermal Resistance, Four-Layer Board:</b>	
Junction to Ambient ( $\theta_{JA}$ )	$41^\circ C/W$
Junction to Case ( $\theta_{JC}$ )	$8.5^\circ C/W$

For the latest package outline information and land patterns (footprints), go to [www.maximintegrated.com/packages](http://www.maximintegrated.com/packages). Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to [www.maximintegrated.com/thermal-tutorial](http://www.maximintegrated.com/thermal-tutorial).

## Electrical Characteristics

( $V_{IN} = 24V$ , EN/UVLO = unconnected,  $R_{RT/SYNC} = 69.8k\Omega$  ( $f_{SW} = 400kHz$ ),  $V_{MODE} = V_{PGND} = V_{SGND} = V_{EXTVCC} = 0V$ ,  $C_{VCC} = 1\mu F$ ,  $V_{FB} = 1V$ , LX = SS = RESET = unconnected,  $T_A = T_J = -40^\circ C$  to  $125^\circ C$ , unless otherwise noted. Typical values are at  $T_A = +25^\circ C$ . All voltages are referenced to SGND, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>INPUT SUPPLY (<math>V_{IN}</math>)</b>						
Input Voltage Range	$V_{IN}$		4.5		76	V
Input Shutdown Current	$I_{IN-SH}$	$V_{EN/UVLO} = 0V$ (shutdown mode)	2.5	5	10	$\mu A$
Input Quiescent Current	$I_{Q\_PFM}$	MODE = Unconnected, $V_{EXTVCC} = 5V$		75		$\mu A$
	$I_{Q\_PWM}$	$V_{FB} = 0.75V$ , Normal switching mode		2.5		mA
<b>ENABLE/UVLO (EN/UVLO)</b>						
EN/UVLO Threshold	$V_{ENR}$	$V_{EN/UVLO}$ rising	1.19	1.215	1.24	V
	$V_{ENF}$	$V_{EN/UVLO}$ falling	1.09	1.115	1.14	
	$V_{ENT}$	$V_{EN/UVLO}$ falling, true shutdown		0.7		
EN/UVLO Pullup Current	$I_{EN/UVLO}$	$V_{EN/UVLO} = 1.215V$	2.2	2.5	2.8	$\mu A$
<b>LINEAR REGULATOR (<math>V_{CC}</math>)</b>						
$V_{CC}$ Output Voltage Range	$V_{CC}$	$6V \leq V_{IN} \leq 76V$ , $0mA < I_{VCC} < 5mA$	4.75	5	5.25	V
$V_{CC}$ Current Limit	$I_{VCC-MAX}$	$V_{CC} = 4.3V$ , $V_{IN} = 12V$	13	26	52	mA

**Electrical Characteristics (continued)**

( $V_{IN} = 24V$ , EN/UVLO = unconnected,  $R_{RT}/SYNC = 69.8k\Omega$  ( $f_{SW} = 400$  kHz),  $V_{MODE} = V_{PGND} = V_{SGND} = V_{EXTVCC} = 0V$ ,  $C_{VCC} = 1\mu F$ ,  $V_{FB} = 1V$ , LX = SS = RESET = unconnected,  $T_A = T_J = -40^\circ C$  to  $125^\circ C$ , unless otherwise noted. Typical values are at  $T_A = +25^\circ C$ . All voltages are referenced to SGND, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
$V_{CC}$ Dropout Voltage	$V_{CC-DO}$	$V_{IN} = 4.5V$ , $I_{VCC} = 5mA$			0.27	V
$V_{CC}$ UVLO	$V_{CC-UVR}$	$V_{CC}$ rising	4.05	4.2	4.35	V
	$V_{CC-UVF}$	$V_{CC}$ falling	3.65	3.8	3.95	
EXTVCC Operating Voltage Range			4.85		24	V
EXTVCC Switchover Threshold		$V_{EXTVCC}$ rising	4.65	4.74	4.85	V
		Hysteresis		0.3		
EXTVCC Dropout Voltage	EXTVCC-DO	$V_{EXTVCC} = 4.75V$ , $I_{VCC} = 5mA$			0.1	V
EXTVCC Current Limit	$I_{VCC-MAX}$	$V_{CC} = 4.3V$ , $V_{EXTVCC} = 5V$	13	21	34	mA
<b>POWER MOSFETS</b>						
High-Side pMOS On-Resistance	$R_{DS-ONH}$	$I_{LX} = 0.15A$ , sourcing		1.8	3.6	$\Omega$
Low-Side nMOS On-Resistance	$R_{DS-ONL}$	$I_{LX} = 0.15A$ , sinking		0.55	1.1	$\Omega$
LX Leakage Current	$I_{LX-LKG}$	$V_{LX} = (V_{PGND} + 1V)$ to $(V_{IN} - 1V)$ , $T_A = +25^\circ C$	-1		+1	$\mu A$
<b>SOFT-START (SS)</b>						
Charging Current	$I_{SS}$		4.7	5	5.3	$\mu A$
<b>FEEDBACK (FB)</b>						
FB Regulation Voltage	$V_{FB-REG}$	$V_{MODE} = 0V$ (PWM mode)	0.788	0.802	0.815	V
		MODE = Unconnected (PFM mode)	0.788	0.813	0.827	
FB Input Leakage Current	$I_{FB}$	$T_A = +25^\circ C$	-100		+100	nA
<b>CURRENT LIMIT</b>						
Peak Current Limit Threshold	$I_{PEAK-LIMIT}$		532	640	755	mA
Negative Current Limit Threshold	$I_{SINK-LIMIT}$	$V_{MODE} = 0V$ (PWM mode)	238	270	302	mA
		MODE = Unconnected (PFM mode)		2.5		
PFM Current Limit	$I_{PFM}$	MODE = Unconnected	185	240	310	mA
<b>MODE</b>						
PFM Mode Threshold	$V_{TH\_PFM}$	Rising	1	1.22	1.44	V
		Hysteresis		0.175		
MODE Pullup Current at Power-Up				2.5		$\mu A$
<b>OSCILLATOR (RT/SYNC)</b>						
Switching Frequency	$f_{SW}$	$R_{RT}/SYNC = 140k\Omega$	180	200	220	kHz
		$R_{RT}/SYNC = 93.1k\Omega$	270	300	330	
		$R_{RT}/SYNC = 69.8k\Omega$	360	400	440	
		$R_{RT}/SYNC = 46.4k\Omega$	540	600	660	

**Electrical Characteristics (continued)**

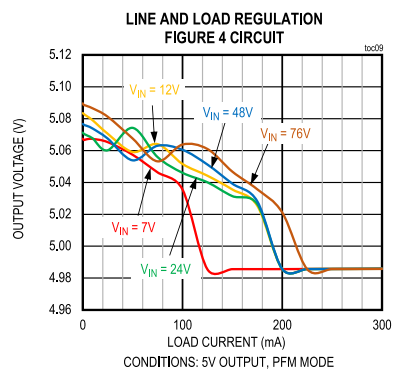
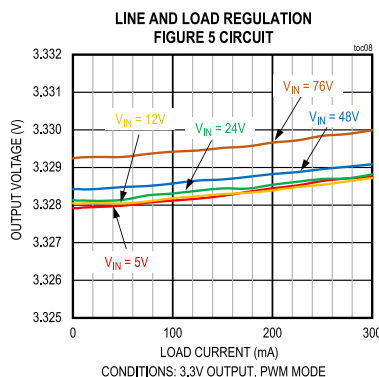
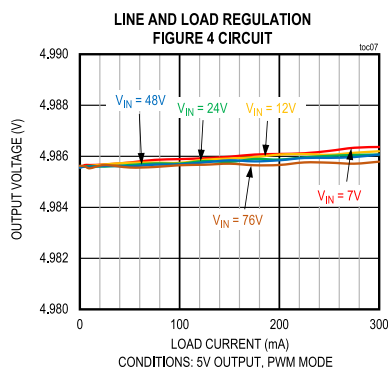
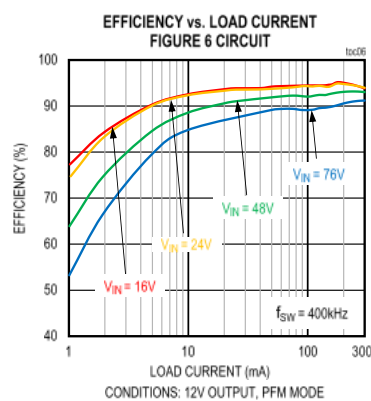
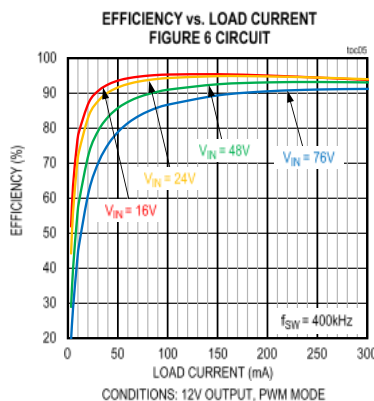
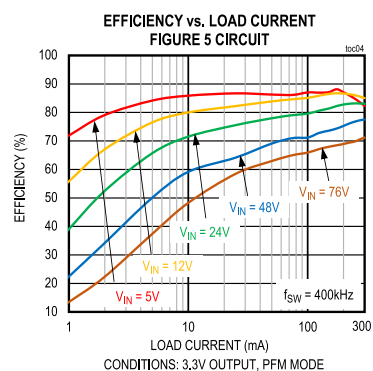
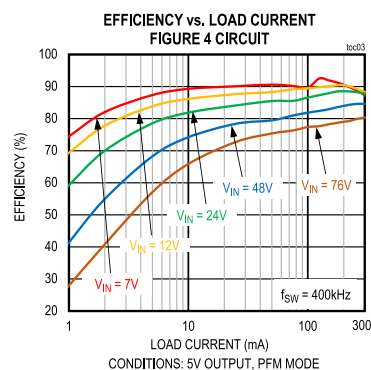
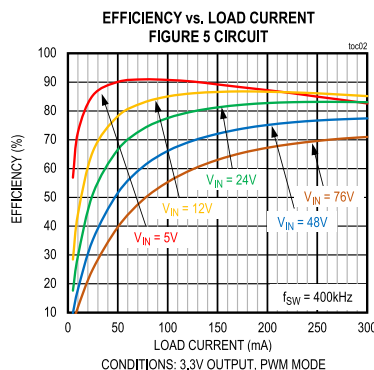
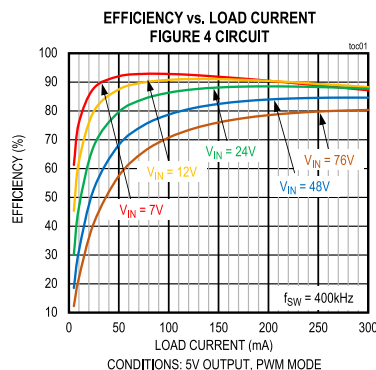
( $V_{IN} = 24V$ ,  $EN/UVLO = \text{unconnected}$ ,  $R_{RT}/SYNC = 69.8k\Omega$  ( $f_{SW} = 400\text{ kHz}$ ),  $V_{MODE} = V_{PGND} = V_{SGND} = V_{EXTVCC} = 0V$ ,  $C_{VCC} = 1\mu F$ ,  $V_{FB} = 1V$ ,  $LX = SS = \overline{RESET} = \text{unconnected}$ ,  $T_A = T_J = -40^\circ C$  to  $125^\circ C$ , unless otherwise noted. Typical values are at  $T_A = +25^\circ C$ . All voltages are referenced to SGND, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Switching Frequency Adjustable Range			200		600	kHz
Minimum On-Time	t <sub>ON-MIN</sub>			70	110	ns
Maximum Duty Cycle	D <sub>MAX</sub>		88	93	97	%
Hiccup Timeout Period	t <sub>HIC-TOUT</sub>	For MAX17760		51		ms
SYNC Frequency Capture Range			1.15 x f <sub>SW</sub> (typ)		1.4 x f <sub>SW</sub> (typ)	
SYNC Threshold	V <sub>IH</sub>		2.1			V
	V <sub>IL</sub>			0.8		
RESET						
RESET Output Level Low		I <sub>RESET</sub> = 10mA			0.4	V
RESET Output Leakage Current		T <sub>A</sub> = +25°C			1	μA
FB Threshold for RESET Deassertion	V <sub>FB-OKR</sub>	V <sub>FB</sub> rising		95		%
FB Threshold for RESET Assertion	V <sub>FB-OKF</sub>	V <sub>FB</sub> falling		92		%
RESET Delay after FB Reaches 95% Regulation				2.1		ms
THERMAL SHUTDOWN						
Thermal Shutdown Threshold		Temperature rising		160		°C
		Hysteresis		20		

**Note 2:** Electrical specifications are production tested at  $T_A = +25^\circ C$ . Specifications over the entire operating temperature range are guaranteed by design and characterization.

## Typical Operating Characteristics

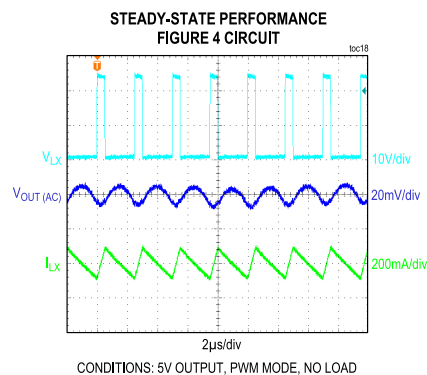
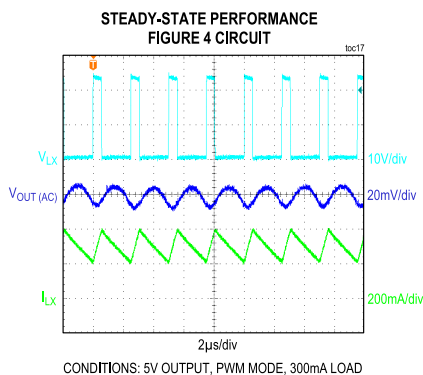
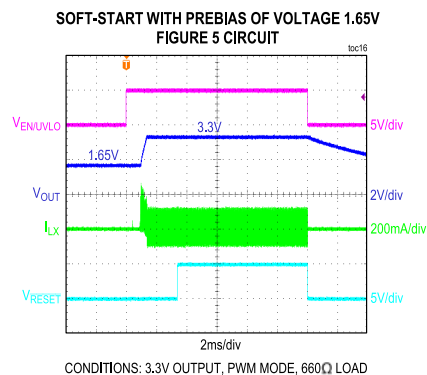
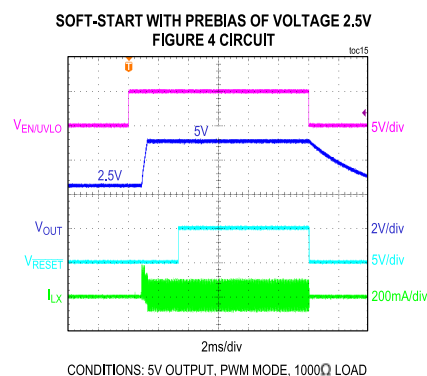
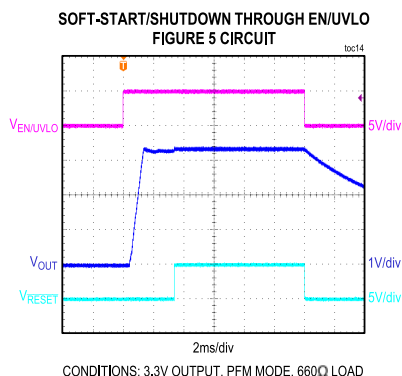
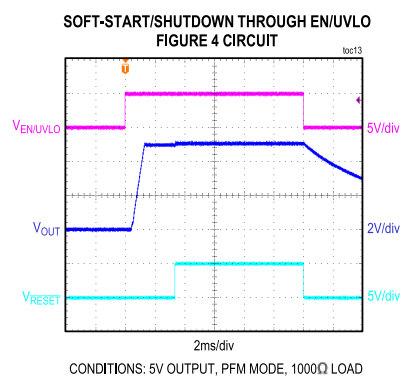
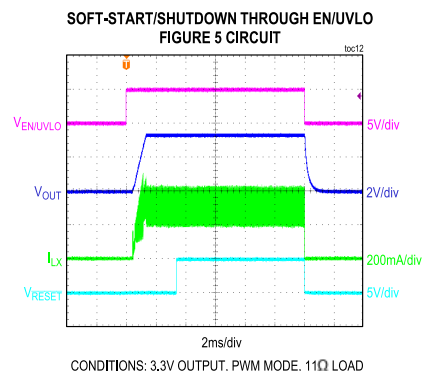
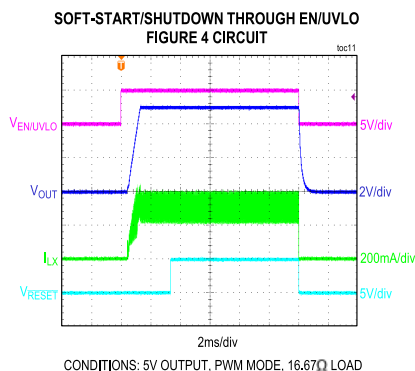
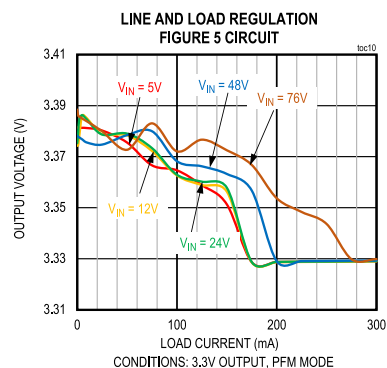
( $V_{IN} = 24V$ ,  $V_{SGND} = V_{PGND} = 0V$ ,  $C_{VCC} = 1\mu F$ , EN/UVLO = unconnected,  $C_{SS} = 5600pF$ ,  $T_A = +25^\circ C$ , unless otherwise noted. All voltages are referenced to SGND, unless otherwise noted.)





## Typical Operating Characteristics (continued)

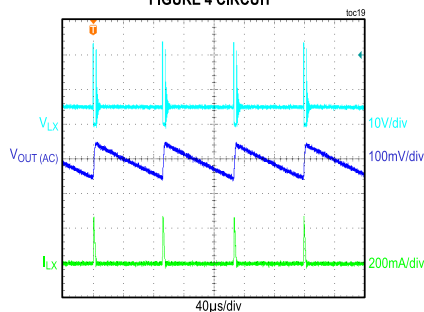
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## Typical Operating Characteristics (continued)

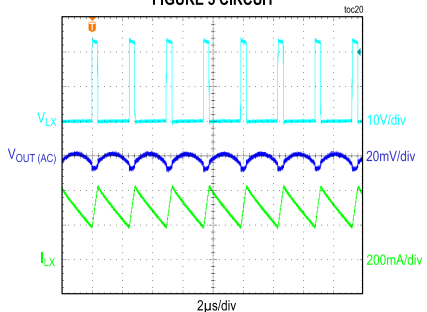
( $V_{IN} = 24V$ ,  $V_{SGND} = V_{PGND} = 0V$ ,  $C_{VCC} = 1\mu F$ , EN/UVLO = unconnected,  $C_{SS} = 5600pF$ ,  $T_A = +25^\circ C$ , unless otherwise noted. All voltages are referenced to SGND, unless otherwise noted.)

STEADY-STATE PERFORMANCE  
FIGURE 4 CIRCUIT



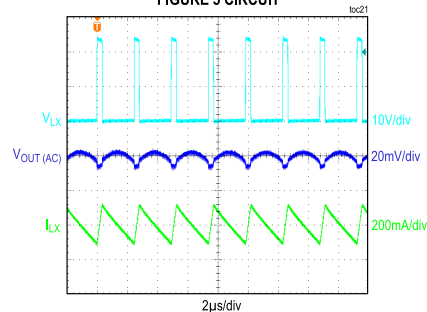
CONDITIONS: 5V OUTPUT, PFM MODE, 5mA LOAD

STEADY-STATE PERFORMANCE  
FIGURE 5 CIRCUIT



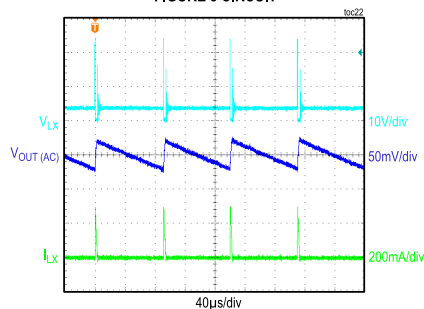
CONDITIONS: 3.3V OUTPUT, PWM MODE, 300mA LOAD

STEADY-STATE PERFORMANCE  
FIGURE 5 CIRCUIT



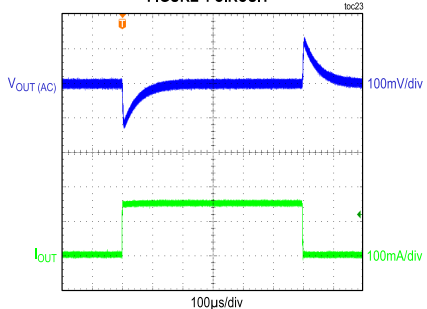
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STEADY-STATE PERFORMANCE  
FIGURE 5 CIRCUIT



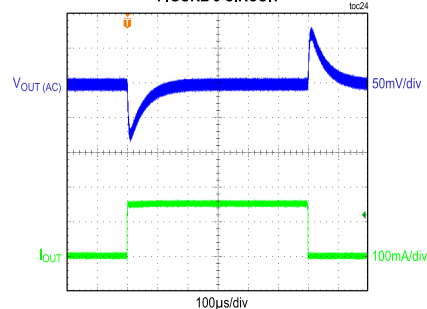
CONDITIONS: 3.3V OUTPUT, PFM MODE, 5mA LOAD

LOAD TRANSIENT BETWEEN 0mA AND 150mA  
FIGURE 4 CIRCUIT



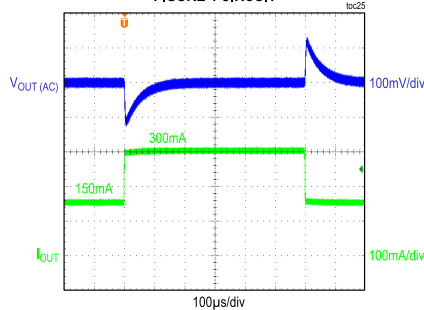
CONDITIONS: 5V OUTPUT, PWM MODE

LOAD TRANSIENT BETWEEN 0mA AND 150mA  
FIGURE 5 CIRCUIT



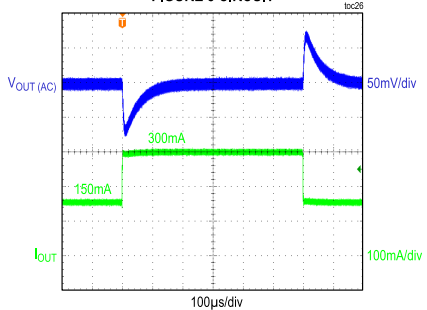
CONDITIONS: 3.3V OUTPUT, PWM MODE

LOAD TRANSIENT BETWEEN 150mA AND 300mA  
FIGURE 4 CIRCUIT



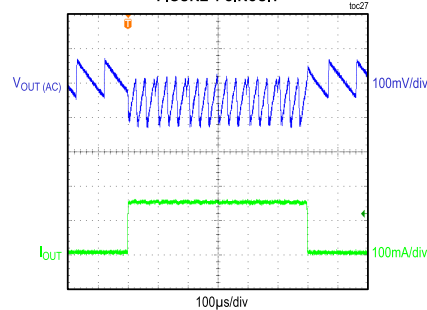
CONDITIONS: 5V OUTPUT, PWM MODE

LOAD TRANSIENT BETWEEN 150mA AND 300mA  
FIGURE 5 CIRCUIT



CONDITIONS: 3.3V OUTPUT, PWM MODE

LOAD TRANSIENT BETWEEN 5mA AND 150mA  
FIGURE 4 CIRCUIT

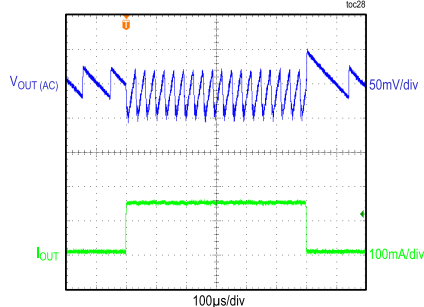


CONDITIONS: 5V OUTPUT, PFM MODE

## Typical Operating Characteristics (continued)

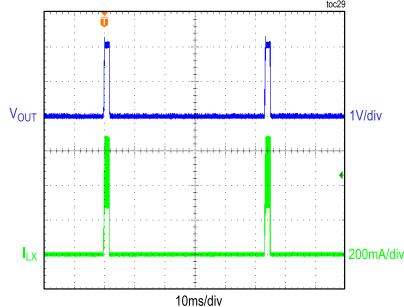
( $V_{IN} = 24V$ ,  $V_{SGND} = V_{PGND} = 0V$ ,  $C_{VCC} = 1\mu F$ , EN/UVLO = unconnected,  $C_{SS} = 5600pF$ ,  $T_A = +25^\circ C$ , unless otherwise noted. All voltages are referenced to SGND, unless otherwise noted.)

LOAD TRANSIENT BETWEEN 5mA AND 150mA  
FIGURE 5 CIRCUIT



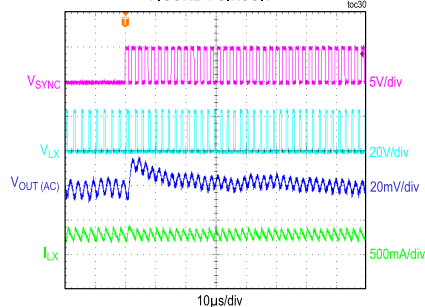
CONDITIONS: 3.3V OUTPUT, PFM MODE

OVERLOAD PROTECTION  
FIGURE 4 CIRCUIT



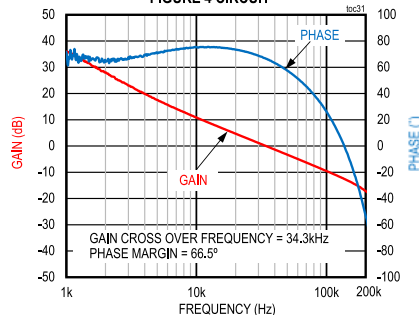
CONDITIONS: 5V OUTPUT, PWM MODE,  $R_{LOAD} = 4.4\Omega$

EXTERNAL CLOCK SYNCHRONIZATION  
FIGURE 4 CIRCUIT



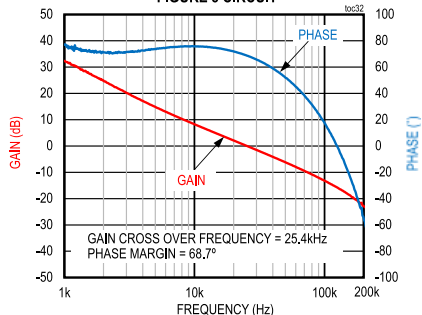
CONDITIONS: 5V OUTPUT, PWM MODE, 300mA LOAD,  
 $f_{SW} = 400kHz$ , EXTERNAL CLOCK FREQUENCY = 460kHz

BODE PLOT  
FIGURE 4 CIRCUIT



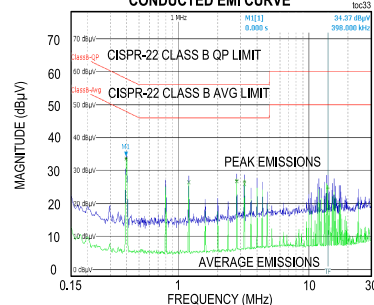
CONDITIONS: 5V OUTPUT, PWM MODE, 300mA LOAD

BODE PLOT  
FIGURE 5 CIRCUIT



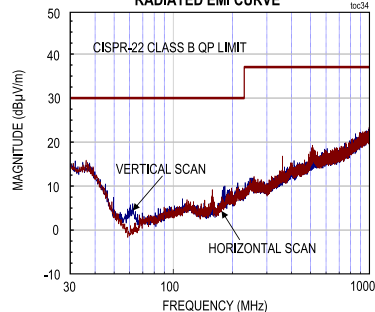
CONDITIONS: 3.3V OUTPUT, PWM MODE, 300mA LOAD

5V OUTPUT, 300mA LOAD CURRENT,  
CONDUCTED EMI CURVE



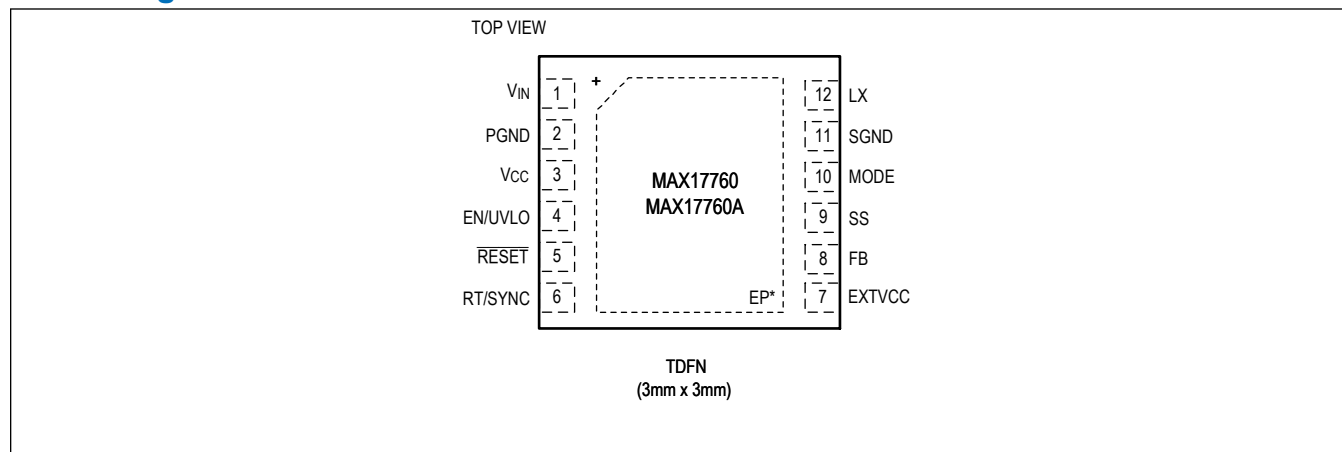
CONDITIONS: MEASURED ON THE MAX17760EVKITB# WITH  $L2 = 22\mu H$ ,  
 $C15 = 1\mu F/100V/X7R/1206$ ,  $C16 = 4.7\mu F/100V/X7R/1206$

5V OUTPUT, 300mA LOAD CURRENT,  
RADIATED EMI CURVE



CONDITIONS: MEASURED ON THE MAX17760EVKITB#

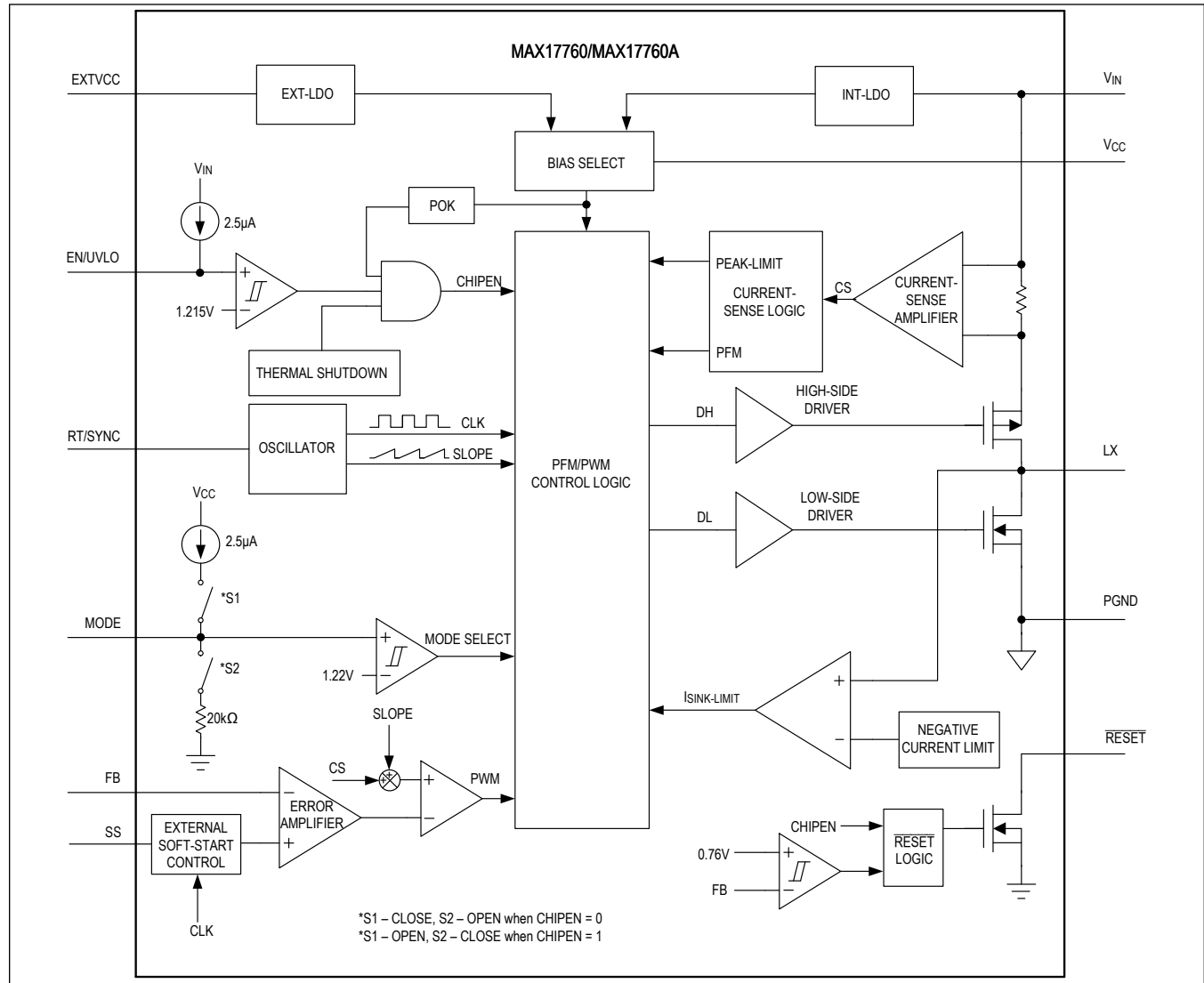
## Pin Configuration



## Pin Description

PIN	NAME	FUNCTION
1	V <sub>IN</sub>	Power Supply Input Pin. 4.5V to 76V input-supply range. Decouple to PGND with a 1μF capacitor. Place the capacitor close to the V <sub>IN</sub> and PGND pins.
2	PGND	Power Ground. Refer to the MAX17760 EV kit data sheet for the recommended PCB layout and routing.
3	V <sub>CC</sub>	5V LDO Output. Bypass V <sub>CC</sub> with a 1μF ceramic capacitor to PGND. LDO doesn't support external loading on V <sub>CC</sub> .
4	EN/UVLO	Enable/Undervoltage Lockout Pin. Drive EN/UVLO high to enable the output. Connect to the center of a resistor-divider between V <sub>IN</sub> and SGND to set the input voltage at which the device turns on. Leave the pin unconnected for always-on operation.
5	RESET	Open-Drain RESET Output. The RESET output is driven low when FB drops below 92% of its set value. RESET goes high 2.1ms after FB rises above 95% of its set value.
6	RT/SYNC	Programmable Switching Frequency and External Clock Synchronization Input. Connect a resistor from RT/SYNC to SGND to set the converter's switching frequency between 200kHz and 600kHz. An external clock can be connected to the RT/SYNC to synchronize the device with an external clock in PWM mode. See the <a href="#">Switching Frequency Selection and External Clock Synchronization (RT/SYNC)</a> section for more details.
7	EXTVCC	External Power Supply Input for the EXT-LDO. Connect EXTVCC to the buck converter output for an output voltage between 5V and 24V. When EXTVCC is not used, connect it to SGND. See the <a href="#">Linear Regulator (V<sub>CC</sub> and EXTVCC)</a> section for more details.
8	FB	Feedback Input. Connect FB to the center node of an external resistor-divider from the output to SGND to set the output voltage. See the <a href="#">Adjusting Output Voltage</a> section for more details.
9	SS	Soft-Start Input. Connect a capacitor from SS to SGND to set the soft-start time.
10	MODE	MODE Selection. The MODE pin configures the device to operate either in PWM or PFM mode of operation. Leave MODE unconnected for PFM operation. Connect MODE to SGND for constant-frequency PWM operation at all loads.
11	SGND	Signal Ground.
12	LX	Switching Node. Connect LX pin to the switching-side of the inductor.
—	EP	Exposed Pad. Connect EP to SGND. Refer to the MAX17760 EV kit data sheet for the recommended method of PCB layout, routing, and thermal vias.

## Functional Block Diagram



## Detailed Description

The MAX17760/MAX17760A are high-efficiency, high-voltage, synchronous step-down DC-DC converters with integrated MOSFETs operating over an input-voltage range of 4.5V to 76V. The devices can deliver up to 300mA current. Output voltage is programmable from 0.8V up to 88% of  $V_{IN}$ . Built-in control loop compensation eliminates the need for external components. The feedback-voltage regulation accuracy over  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$  is +1.6% to -1.7%.

The devices feature a peak-current-mode control architecture. An internal transconductance error amplifier produces an integrated error voltage at an internal node, which sets the duty cycle using a PWM comparator, a high-side current-sense amplifier, and a slope-compensation generator. At each rising edge of the clock, the high-side MOSFET turns on and remains on until either the appropriate or maximum duty cycle is reached, or the peak current limit is detected. During the high-side MOSFET on-time, the inductor current ramps up. During the rest of the switching cycle, the high-side MOSFET turns off and the low-side MOSFET turns on. The inductor releases the stored energy as its current ramps down and provides current to the output. The internal low  $R_{DS(on)}$  pMOS/nMOS switches ensure high efficiency at full load.

The MAX17760/MAX17760A feature a MODE pin that can be used to program the device in PWM or PFM control schemes. The devices also feature adjustable-input undervoltage lockout (EN/UVLO), adjustable soft-start (SS), open-drain RESET, and external clock synchronization (RT/SYNC) features. The devices offer a low minimum on-time that allows to operate for a wide range of input supply at a given switching frequency.

## Mode Selection

The MAX17760/MAX17760A support PWM and PFM mode of operation. The devices detect the MODE pin status at power-up and latches the MODE of operation. Leave the MODE pin unconnected for PFM operation. At power-up, the devices pull up the MODE pin with a 2.5 $\mu\text{A}$  current. If the MODE pin exceeds the PFM mode threshold ( $V_{TH\_PFM}$ ), the part latches PFM mode and pulls down MODE with a 20k $\Omega$  internal resistor. Connect MODE to SGND for constant-frequency forced PWM operation at all loads. The mode of operation cannot be changed on-the-fly after power-up.

In PWM mode, the inductor current is allowed to go negative. PWM operation provides constant frequency operation irrespective of loading, and is useful in applications sensitive to switching frequency.

PFM mode provides high efficiency at light load conditions by disabling negative inductor current and additionally skipping pulses. In PFM mode, the inductor current is forced to a fixed peak of  $I_{PFM}$  (240mA typ) every clock cycle until the output rises to 102.3% of the set nominal output voltage. Once the output reaches 102.3% of the set nominal output voltage, both the high-side and low-side FETs are turned off and the device enters hibernation until the load discharges the output to 101.1% of the set nominal output voltage. Most of the internal blocks are turned off in hibernate operation to reduce quiescent current. After the output falls below 101.1% of the set nominal output voltage, the devices come out of hibernate operation, turns on all internal blocks, and again commences the process of delivering pulses of energy to the output until it reaches 102.3% of the set nominal output voltage. The advantage of PFM mode is higher efficiency at light loads because of lower quiescent current drawn from supply. However, the output voltage ripple is higher compared to PWM mode of operation and switching frequency is not constant at light loads.

## Linear Regulator ( $V_{CC}$ and EXT $V_{CC}$ )

The MAX17760/MAX17760A integrate two internal low-dropout (LDO) linear regulators INT-LDO and EXT-LDO that power  $V_{CC}$ . INT-LDO is powered from  $V_{IN}$  and turns on when  $V_{EN/UVLO} > V_{ENT}$  (0.7V typ). EXT-LDO is powered from EXT $V_{CC}$ . At any time, only one of these two linear regulators operates, depending on the EXT $V_{CC}$  voltage. If EXT $V_{CC}$  is greater than 4.74V (typ),  $V_{CC}$  is powered from the EXT $V_{CC}$ . If EXT $V_{CC}$  is lower than 4.44V (typ),  $V_{CC}$  is powered from  $V_{IN}$ . Powering  $V_{CC}$  from EXT $V_{CC}$  increases efficiency at higher input voltages. Typical  $V_{CC}$  output voltage is 5V. Bypass  $V_{CC}$  to SGND with a 1 $\mu\text{F}$  low-ESR ceramic capacitor.  $V_{CC}$  powers the internal blocks and both low-side and high-side MOSFET drivers.

The MAX17760/MAX17760A employ an undervoltage-lockout circuit that forces the converter off when  $V_{CC}$  voltage falls below  $V_{CC-UVF}$  (3.8V typ). The buck converter enables when the  $V_{CC}$  voltage rises above  $V_{CC-UVR}$  (4.2 typ).

EXT $V_{CC}$  should be connected to the output capacitor with an R-C filter as shown in [Figure 4](#). Without this R-C filter, the absolute maximum rating of EXT $V_{CC}$  (-0.3V) can be exceeded under short-circuit conditions, due to oscillations between the ceramic output capacitor and the inductance of the short-circuit path. In general, parasitic board or wiring inductance

should be minimized and the output voltage under short-circuit operation should be verified to ensure that the absolute maximum rating of EXT VCC is not exceeded.

### Switching Frequency Selection and External Clock Synchronization (RT/SYNC)

The MAX17760/MAX17760A can be programmed to one of the four discrete switching frequencies (200kHz, 300kHz, 400kHz, and 600kHz) by connecting a resistor from RT/SYNC to SGND. [Table 1](#) provides resistor values for different switching frequencies.

The MAX17760/MAX17760A can be synchronized to an external clock coupled to the RT/SYNC pin through a 22pF capacitor as shown in [Figure 1](#). The external clock must be applied after RESET is asserted high for proper configuration of the internal loop compensation. If the external clock frequency is within the allowed SYNC frequency range (1.15 to 1.4 times the nominal internal clock frequency  $f_{SW}$ ), the internal clock synchronizes to the external clock within 1 clock cycle. The allowed external clock duty cycle range is 10% to 80%.

**Table 1. Switching Frequency vs. RT/SYNC Resistor**

SWITCHING FREQUENCY (kHz)	R <sub>RT/SYNC</sub> (kΩ)
200	140
300	93.1
400	69.8
600	46.4

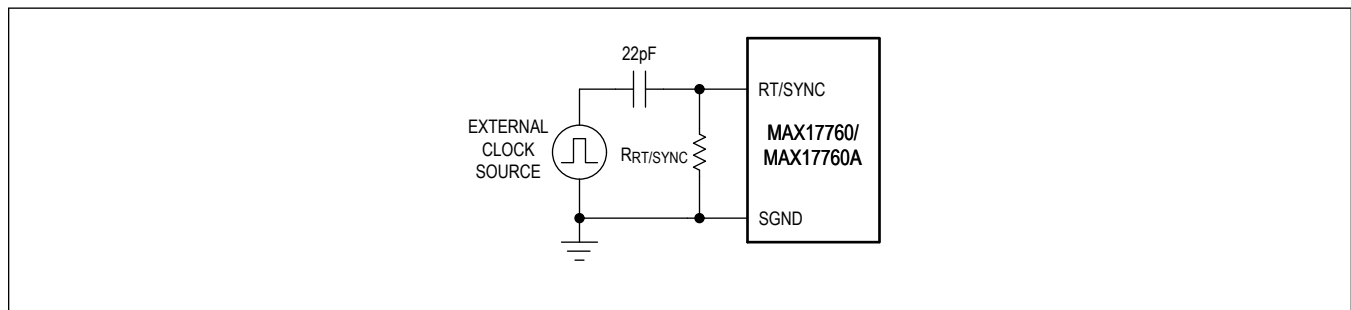


Figure 1. External Clock Synchronization

### Operating Input Voltage Range

The minimum and maximum operating input voltages for a given output-voltage setting should be calculated as follows:

$$V_{IN(MIN)} = \frac{V_{OUT} + (I_{OUT(MAX)} \times (R_{DCR(MAX)} + R_{DS-ONL(MAX)}))}{D_{MAX}} + (I_{OUT(MAX)} \times (R_{DS-ONH(MAX)} - R_{DS-ONL(MAX)}))$$

$$V_{IN(MAX)} = \frac{V_{OUT}}{f_{SW(MAX)} \times t_{ON-MIN(MAX)}}$$

where:

$V_{OUT}$  = Steady-state output voltage

$I_{OUT(MAX)}$  = Maximum load current

$R_{DCR(MAX)}$  = Worst-case DC resistance of the inductor

$f_{SW(MAX)}$  = Maximum switching frequency

$D_{MAX}$  = Minimum specification of maximum duty ratio (0.88)

$t_{ON-MIN(MAX)}$  = Worst-case minimum switch on-time (110 ns)

$R_{DS-ONL(MAX)}$  and  $R_{DS-ONH(MAX)}$  = Worst-case on-state resistances of low-side and high-side internal MOSFETs,

respectively.

### Overcurrent Protection/Hiccup Mode

The MAX17760/MAX17760A feature a hysteretic peak current-limit protection scheme to protect the internal FETs and inductor under output short-circuit conditions. When the inductor peak current exceeds  $I_{PEAK-LIMIT}$ , the high-side switch is turned off and the low-side switch is turned on. After the current is reduced to 290mA (typ), the high-side switch is turned on at the rising edge of the next clock pulse. The MAX17760 enters a hiccup timeout period ( $t_{HIC\_TOUT}$  (51ms typ)) if 16 consecutive peak current limit events are detected. After the hiccup time-out period has elapsed, the device restarts. If the overcurrent condition persists, the device remains in hiccup current limit mode until the overcurrent fault is removed. The MAX17760A does not enter hiccup mode and operates continuously in hysteretic current limit.

### RESET Output

The devices feature a  $\overline{RESET}$  comparator to monitor the output voltage. The open-drain  $\overline{RESET}$  output requires an external pullup resistor.  $\overline{RESET}$  goes high 2.1ms after the regulator output increases above 95% of the designed nominal regulated voltage.  $\overline{RESET}$  goes low when the regulator output voltage drops to below 92% of the nominal regulated voltage.  $\overline{RESET}$  also goes low during thermal shutdown.

### Prebiased Output

When the devices start into a prebiased output, both the high-side and the low-side switches are turned off so that the converters do not sink current from the output. High-side and low-side switches do not start switching until the PWM comparator commands the first PWM pulse, at which point switching commences. The output voltage is then smoothly ramped up to the target value in alignment with the internal reference.

### Thermal-Shutdown Protection

Thermal shutdown protection limits junction temperature of the device. When the junction temperature of the device exceeds +160°C, an on-chip thermal sensor shuts down the device, allowing the device to cool. The thermal sensor turns the device on with soft-start after the junction temperature cools by 20°C. Carefully evaluate the total power dissipation (see the [Power Dissipation](#) section) to avoid unwanted triggering of the thermal shutdown protection in normal operation.



## Applications Information

### Input Capacitor Selection

The input filter capacitor reduces peak currents drawn from the power source and reduces noise and voltage ripple on the input caused by the circuit switching. The input capacitor RMS current requirement ( $I_{RMS}$ ) is defined by the following equation:

$$I_{RMS} = I_{OUT(MAX)} \times \frac{\sqrt{V_{OUT} \times (V_{IN} - V_{OUT})}}{V_{IN}}$$

where,  $I_{OUT(MAX)}$  is the maximum load current.  $I_{RMS}$  has a maximum value when the input voltage equals twice the output voltage ( $V_{IN} = 2 \times V_{OUT}$ ), so

$$I_{RMS(MAX)} = \frac{I_{OUT(MAX)}}{2}.$$

Choose an input capacitor that exhibits less than +10°C temperature rise at the RMS input current for optimal long-term reliability. Use low-ESR ceramic capacitors with high-ripple-current capability at the input. X7R capacitors are recommended in industrial applications for their temperature stability. Calculate the input capacitance using the following equation:

$$C_{IN} = \frac{I_{OUT(MAX)} \times D \times (1 - D)}{\eta \times f_{SW} \times \Delta V_{IN}}$$

where:

$D = V_{OUT}/V_{IN}$  and is the duty ratio of the controller

$f_{SW}$  = Switching frequency

$\Delta V_{IN}$  = Allowable input-voltage ripple

$\eta$  = Efficiency

In applications where the source is located distant from the device input, an appropriate electrolytic capacitor should be added in parallel to the ceramic capacitor to provide necessary damping for potential oscillations caused by the inductance of the longer input power path and input ceramic capacitor.

### Inductor Selection

Three key inductor parameters must be specified for operation with the device: inductance value (L), inductor saturation current ( $I_{SAT}$ ) and DC resistance ( $R_{DCR}$ ). The switching frequency and output voltage determine the inductor value as follows:

$$L = \frac{4 \times V_{OUT}}{f_{SW}}$$

where  $V_{OUT}$  = Output voltage

$f_{SW}$  = Switching frequency

Select a low-loss inductor closest to the calculated value with acceptable dimensions and having the lowest possible DC resistance. The saturation current rating ( $I_{SAT}$ ) of the inductor must be high enough to ensure that saturation can occur only above the peak current-limit value.

### Output Capacitor Selection

X7R ceramic output capacitors are preferred due to their stability over temperature in industrial applications. The output capacitors are sized to support a step load of 50% of the maximum output current in the application, so the output-voltage deviation is contained to 3% of the output-voltage change. The minimum required output capacitance can be calculated as follows:

$$C_{OUT} = \frac{1}{2} \times \frac{I_{STEP} \times t_{RESPONSE}}{\Delta V_{OUT}}$$

$$t_{RESPONSE} \cong \frac{0.35}{f_C}$$

where:

$I_{STEP}$  = Load current step

$t_{RESPONSE}$  = Response time of the controller

$\Delta V_{OUT}$  = Allowable output-voltage deviation

$f_C$  = Target closed-loop crossover frequency

$f_{SW}$  = Switching frequency.

Select  $f_C$  to be the minimum of 1/10th of  $f_{SW}$  and 30kHz. Actual derating of ceramic capacitors with DC-bias voltage must be considered while selecting the output capacitor. Derating curves are available from all major ceramic capacitor manufacturers.

### Soft-Start Capacitor Selection

The devices implement adjustable soft-start operation to reduce inrush current. A capacitor connected from the SS pin to SGND programs the soft-start time. The selected output capacitance ( $C_{SEL}$ ) and the output voltage ( $V_{OUT}$ ) determine the minimum required soft-start capacitor as follows:

$$C_{SS} \geq 30 \times 10^{-6} \times C_{SEL} \times V_{OUT}$$

The soft-start time ( $t_{SS}$ ) is related to the capacitor connected at SS ( $C_{SS}$ ) by the following equation:

$$t_{SS} = \frac{C_{SS}}{6.25 \times 10^{-6}}$$

For example, to program a 0.9ms soft-start time, a 5.6nF capacitor should be connected from the SS pin to SGND. Note that, during startup, the device operates at half the programmed switching frequency until the output voltage reaches 80% of set output nominal voltage.

### Setting the Input Undervoltage-Lockout Level

Drive EN/UVLO high to enable the output. Leave the pin unconnected for always-on operation. Set the voltage at which each converter turns on with a resistive voltage-divider connected from  $V_{IN}$  to SGND ([Figure 2](#)). Connect the center node of the divider to EN/UVLO pin.

Choose R1 as follows:

$$R1 \leq (110000 \times V_{INU})$$

where  $V_{INU}$  is the input voltage at which the MAX17760 is required to turn on and R1 is in  $\Omega$ . Calculate the value of R2 as follows:

$$R2 = \frac{R1 \times 1.215}{(V_{INU} - 1.215 + (2.5\mu \times R1))}$$

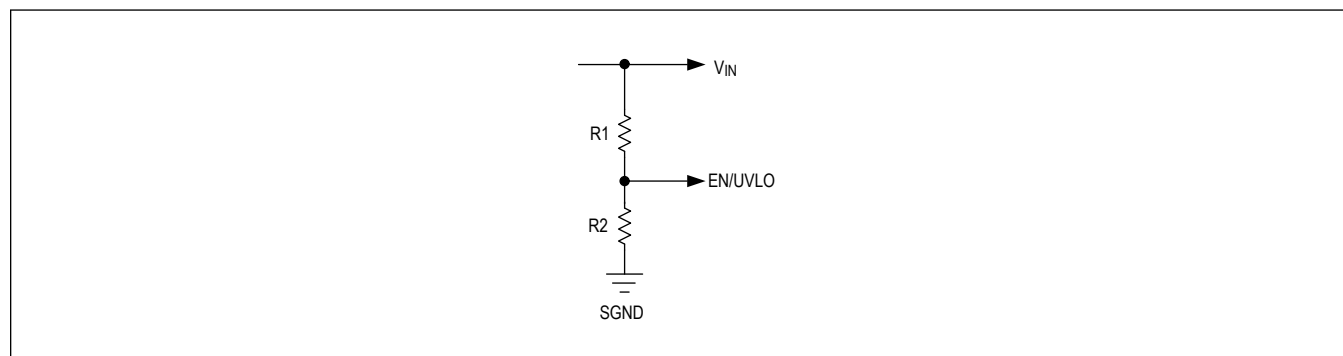


Figure 2. Setting the Input Undervoltage Lockout Level

### Adjusting Output Voltage

Set the output voltage with a resistive voltage-divider connected from the output voltage node ( $V_{OUT}$ ) to SGND (Figure 3). Connect the center node of the divider to the FB pin. Use the following procedure to choose the resistive voltage-divider values:

Calculate resistor R3 from the output to the FB pin as follows:

$$R3 = \frac{15 \times V_{OUT}}{0.8}$$

where R3 is in  $k\Omega$ .

Calculate resistor R4 from the FB pin to SGND as follows:

$$R4 = \frac{R3 \times 0.8}{(V_{OUT} - 0.8)}$$

R4 is in  $k\Omega$ .

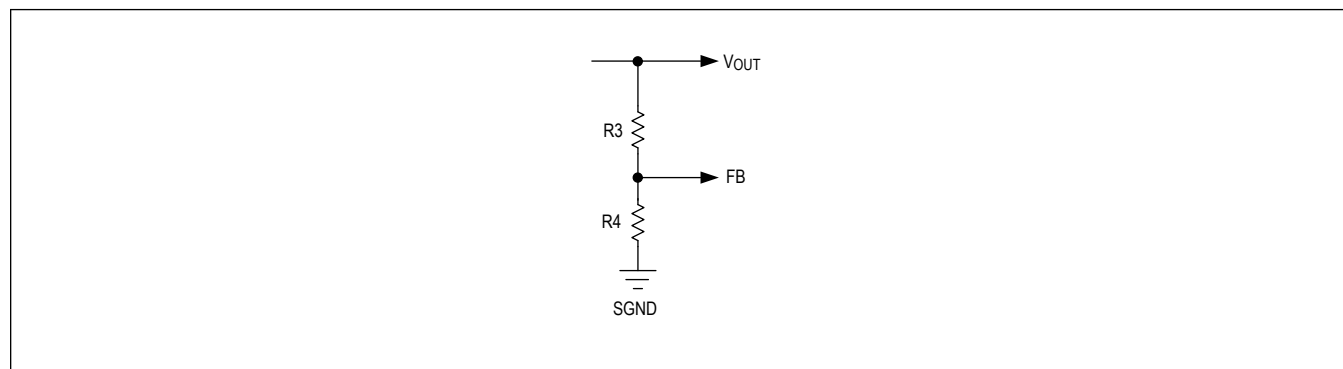


Figure 3. Adjusting Output Voltage

### Power Dissipation

At a particular operating condition, the power losses that lead to a temperature rise of the devices are estimated as follows:

$$P_{LOSS} = \left( P_{OUT} \times \left( \frac{1}{\eta} - 1 \right) \right) - \left( I_{OUT}^2 \times R_{DCR} \right)$$

$$P_{OUT} = V_{OUT} \times I_{OUT}$$

where:

$P_{OUT}$  = Output power

$\eta$  = Efficiency of the converter

$R_{DCR}$  = DC resistance of the inductor. See the [Typical Operating Characteristics](#) for more information on efficiency at typical operating conditions.

For a typical multilayer board, the thermal performance metrics for the package are given below:

$$\theta_{JA} = 41^{\circ}\text{C/W}$$

$$\theta_{JC} = 8.5^{\circ}\text{C/W}$$

The junction temperature of the devices can be estimated at any given maximum ambient temperature ( $T_{A(MAX)}$ ) from the following equation:

$$T_{J(MAX)} = T_{A(MAX)} + (\theta_{JA} \times P_{LOSS})$$

If the application has a thermal-management system that ensures the exposed pads of the devices are maintained at a given temperature ( $T_{EP(MAX)}$ ) by using proper heat sinks, then the junction temperature of the device can be estimated at any given maximum ambient temperature as:

$$T_{J(MAX)} = T_{EP(MAX)} + (\theta_{JC} \times P_{LOSS})$$

**Note:** Junction temperatures greater than +125°C degrades operating lifetimes.

### PCB Layout Guidelines

All connections carrying pulsed currents must be very short and as wide as possible. The inductance of these connections must be kept to an absolute minimum due to the high di/dt of the currents. Since inductance of a current-carrying loop is proportional to the area enclosed by the loop, if the loop area is made very small, inductance is reduced. Additionally, small-current loop areas reduce radiated EMI.

A ceramic input filter capacitor should be placed close to the  $V_{IN}$  pins of the IC. This eliminates as much trace inductance effects as possible and gives the IC a cleaner voltage supply. A bypass capacitor for the  $V_{CC}$  pin also should be placed close to the pin to reduce effects of trace impedance.

When routing the circuitry around the IC, the analog small signal ground and the power ground for switching currents must be kept separate. They should be connected together at a point where switching activity is minimum. This helps keep the analog ground quiet. The ground plane should be kept continuous (unbroken) as far as possible. No trace carrying high switching current should be placed directly over any ground plane discontinuity.

PCB layout also affects the thermal performance of the design. A number of thermal throughputs that connect to a large ground plane should be provided under the exposed pad of the device for efficient heat dissipation.

For a sample layout that ensures first pass success, refer to the MAX17760 EV Kit layout available on the Analog Device website.

## Typical Application Circuits

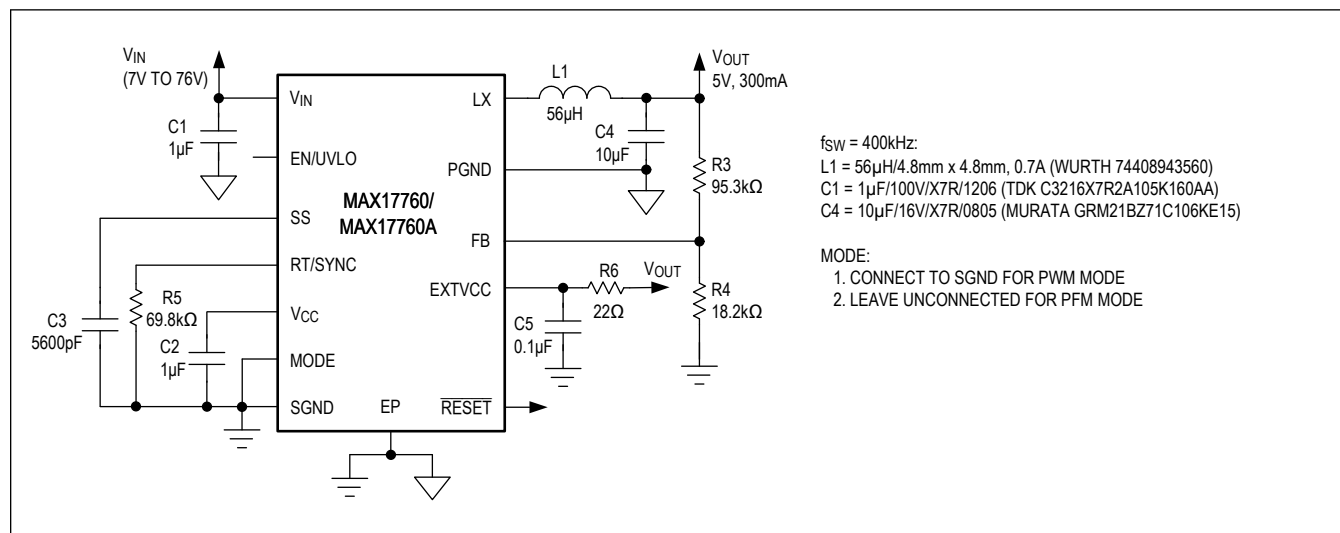


Figure 4. 5V Output with 400kHz Switching Frequency

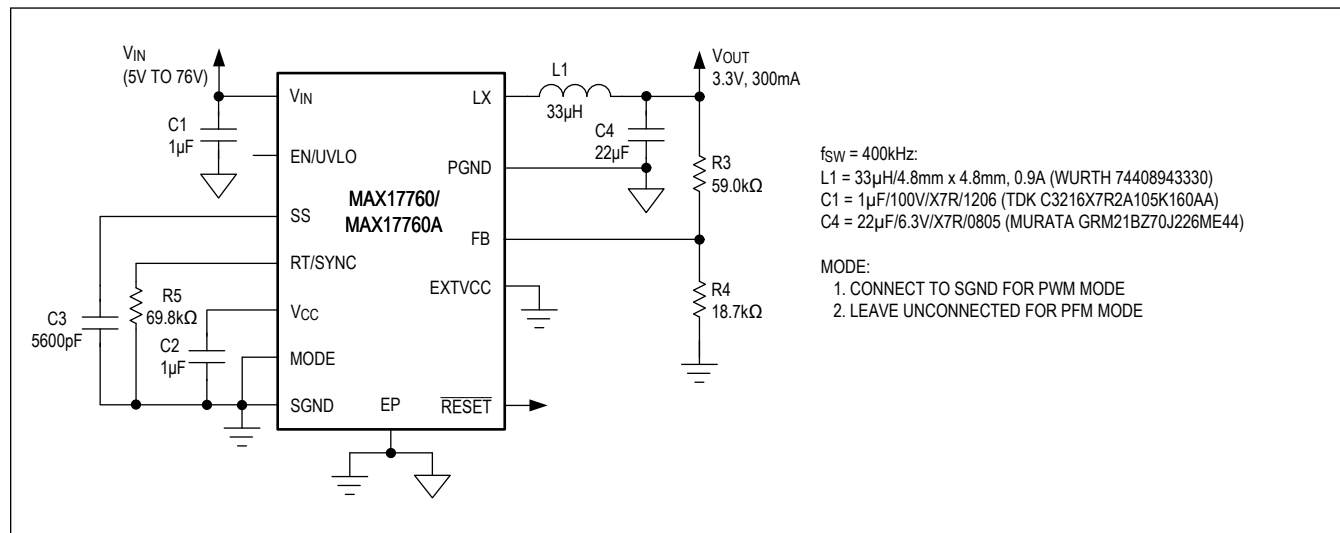


Figure 5. 3.3V Output with 400kHz Switching Frequency

MAX17760

4.5V to 76V, 300mA, High-Efficiency, Synchronous Step-Down DC-DC Converter

Typical Application Circuits (continued)

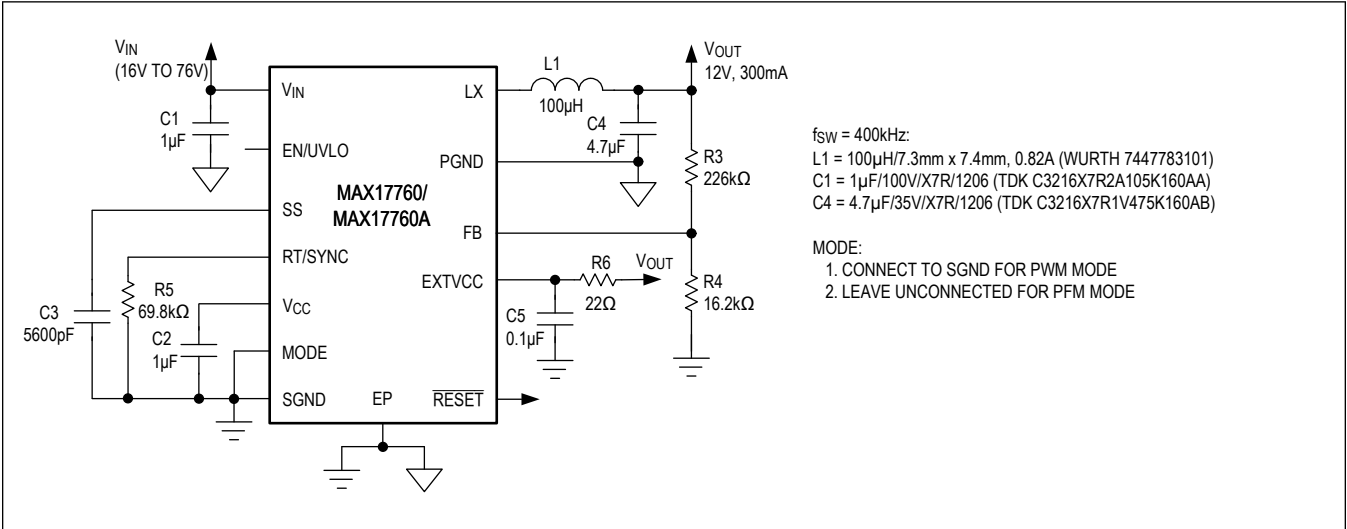


Figure 6. 12V Output with 400kHz Switching Frequency

Ordering Information

PART NUMBER	TEMP. RANGE	PIN-PACKAGE	OVERCURRENT PROTECTION
MAX17760ATC+	-40°C to +125°C	12 TDFN - EP* (3mm x 3mm)	Hysteretic Current Limit with Hiccup Time-Out
MAX17760ATC+T	-40°C to +125°C	12 TDFN - EP* (3mm x 3mm)	Hysteretic Current Limit with Hiccup Time-Out
MAX17760AATC+	-40°C to +125°C	12 TDFN - EP* (3mm x 3mm)	Hysteretic Current Limit
MAX17760AATC+T	-40°C to +125°C	12 TDFN - EP* (3mm x 3mm)	Hysteretic Current Limit

+Denotes a lead(Pb)-free/RoHS-compliant package.

\*EP = Exposed pad.

T = Tape and reel.

MAX17760

4.5V to 76V, 300mA, High-Efficiency, Synchronous  
Step-Down DC-DC Converter

## Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	4/20	Initial release	—
1	4/25	Added new IC variant. updated <i>Benefits and Features</i> , <i>Simplified Application Circuit</i> , <i>Electrical Characteristics</i> , <i>Typical Operating Characteristics</i> , <i>Overcurrent Protection/Hiccup Mode</i> , and <i>Ordering Information</i> sections, and updated Typical Operating Characteristics graphs 05 and 06	1–22
2	8/25	Removed MAX17760A from part number heading	1–22